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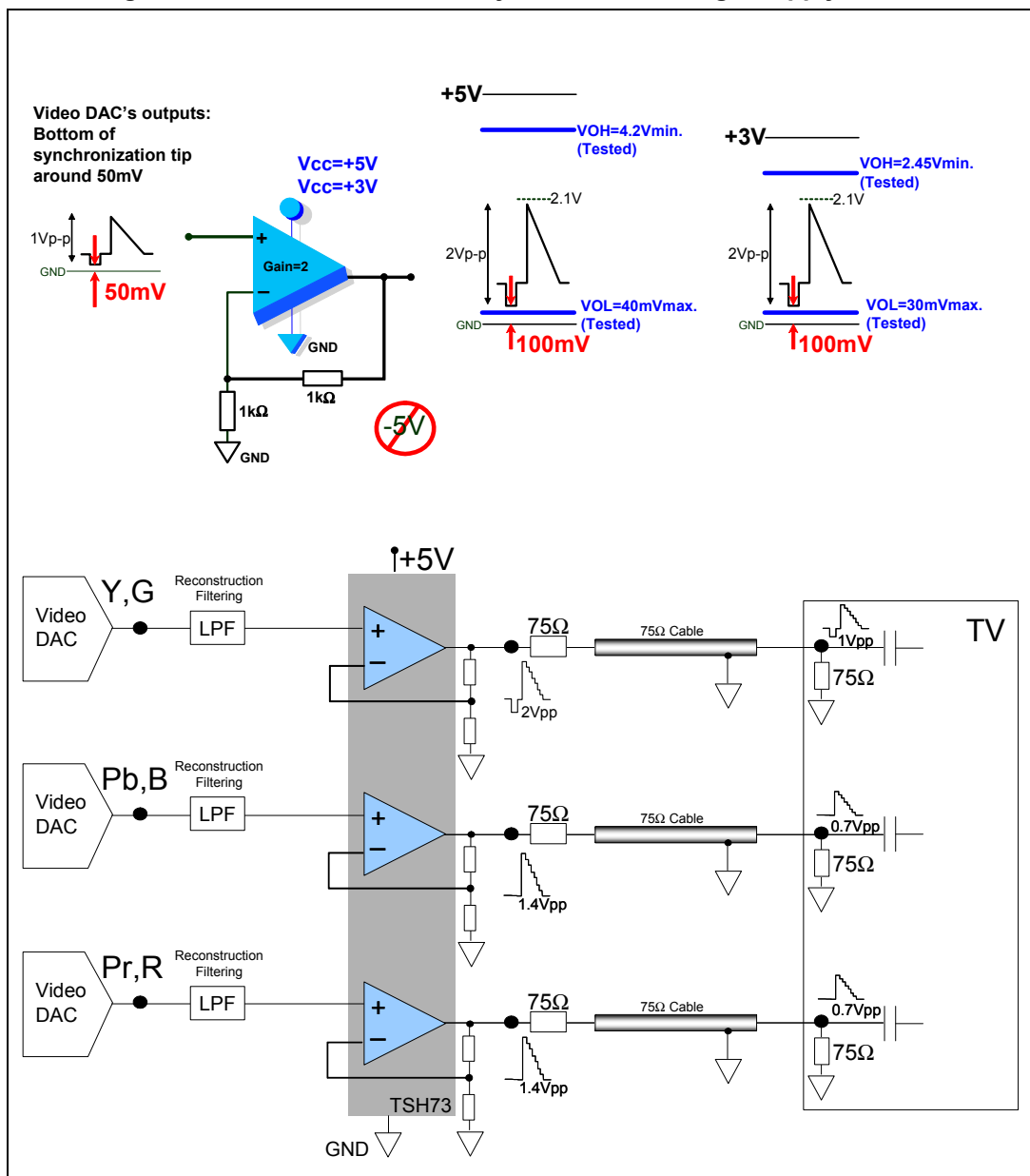
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1 Typical application: video driver

A typical application for the TSH7x family is that of a video driver for driving STi7xxx DAC outputs on 75-ohm lines.

Figure 1 show the benefits of the TSH7x family as single supply drivers.

Figure 1. Benefits of TSH7x family: +3 V or +5 V single supply solution



2 Absolute maximum ratings and operating conditions

Table 1. Absolute maximum ratings (AMR)

Symbol	Parameter	Value	Unit
V_{CC}	Supply Voltage ⁽¹⁾	14	V
V_{id}	Differential Input Voltage ⁽²⁾	± 2	
V_i	Input Voltage ⁽³⁾	± 6	
T_{oper}	Operating Free Air Temperature Range	0 to +70	°C
T_{stg}	Storage Temperature	-65 to +150	
T_j	Maximum Junction Temperature	150	
R_{thjc}	Thermal resistance junction to case ⁽⁴⁾		°C/W
	SOT23-5	80	
	SO8	28	
	TSSOP08	37	
	SO14	22	
	TSSOP14	32	
	SO16	35	
	TSSOP16	35	
R_{thja}	Thermal resistance junction to ambient area		
	SOT23-5	250	
	SO8	157	
	TSSOP08	130	
	SO14	125	
	TSSOP14	110	
	SO16	110	
	TSSOP16	110	
ESD	Human body model	2	kV

1. All voltages values, except differential voltage are with respect to the network ground terminal
2. Differential voltages are the non-inverting input terminal with respect to the inverting terminal
3. The magnitude of the input and output must never exceed $V_{CC} + 0.3V$
4. Short-circuits can cause excessive heating

Table 2. Operating conditions

Symbol	Parameter	Value	Unit
V_{CC}	Supply voltage	3 to 12	V
V_{IC}	Common mode input voltage range	V_{CC}^- to $(V_{CC}^+ - 1.1)$	
Standby		(V_{CC}^-) to (V_{CC}^+)	

3 Electrical characteristics

Table 3. $V_{CC}^+ = 3\text{ V}$, $V_{CC}^- = \text{GND}$, $V_{IC} = 1.5\text{ V}$, $T_{\text{amb}} = 25\text{ }^\circ\text{C}$ (unless otherwise specified)

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$ V_{io} $	Input offset voltage	$T_{\text{amb}} = 25\text{ }^\circ\text{C}$ $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$		1.2	10 12	mV
ΔV_{io}	Input offset voltage drift vs. temp.	$T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$		4		$\mu\text{V}/^\circ\text{C}$
I_{io}	Input offset current	$T_{\text{amb}} = 25\text{ }^\circ\text{C}$ $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$		0.1	3.5 5	μA
I_{ib}	Input bias current	$T_{\text{amb}} = 25\text{ }^\circ\text{C}$ $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$		6	15 20	
C_{in}	Input capacitance			0.2		pF
I_{CC}	Supply current per operator	$T_{\text{amb}} = 25\text{ }^\circ\text{C}$ $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$		7.2	9.8 11	mA
CMRR	Common mode rejection ratio ($\delta V_{IC}/\delta V_{io}$)	$+0.1 < V_{IC} < +1.9\text{ V}$ and $V_{out} = 1.5\text{ V}$ $T_{\text{amb}} = 25\text{ }^\circ\text{C}$ $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$	65 64	90		dB
SVRR	Supply voltage rejection ratio ($\delta V_{CC}/\delta V_{io}$)	$T_{\text{amb}} = 25\text{ }^\circ\text{C}$ $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$	66 65	74		
PSRR	Power supply rejection ratio ($\delta V_{CC}/\delta V_{out}$)	Positive and negative rail		75		
A_{vd}	Large signal voltage gain	$R_L = 150\text{ }\Omega$ to 1.5 V , $V_{out} = 1\text{ V}$ to 2 V $T_{\text{amb}} = 25\text{ }^\circ\text{C}$ $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$	70 65	81		
I_o	Output short circuit current source	$T_{\text{amb}} = 25\text{ }^\circ\text{C}$, $V_{id} = +1$, V_{out} to 1.5 V , $V_{id} = -1$, V_{out} to 1.5 V I_{Source} I_{Sink} $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$ $V_{id} = +1$, V_{out} to 1.5 V $V_{id} = -1$, V_{out} to 1.5 V I_{Source} I_{Sink}	30 20 22 19	43 33		mA
V_{OH}	High level output voltage	$T_{\text{amb}} = 25\text{ }^\circ\text{C}$ $R_L = 150\text{ }\Omega$ to GND $R_L = 600\text{ }\Omega$ to GND $R_L = 2\text{ k}\Omega$ to GND $R_L = 10\text{ k}\Omega$ to GND $R_L = 150\text{ }\Omega$ to 1.5 V $R_L = 600\text{ }\Omega$ to 1.5 V $R_L = 2\text{ k}\Omega$ to 1.5 V $R_L = 10\text{ k}\Omega$ to 1.5 V $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$ $R_L = 150\text{ }\Omega$ to GND $R_L = 150\text{ }\Omega$ to 1.5 V	2.45 2.4 2.6	2.60 2.87 2.91 2.93 2.77 2.90 2.92 2.93		V

Table 3. $V_{CC}^+ = 3\text{ V}$, $V_{CC}^- = \text{GND}$, $V_{IC} = 1.5\text{ V}$, $T_{\text{amb}} = 25\text{ }^\circ\text{C}$ (unless otherwise specified) (continued)

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
V_{OL}	Low level output voltage	$T_{\text{amb}} = 25\text{ }^\circ\text{C}$ $R_L = 150\text{ }\Omega$ to GND $R_L = 600\text{ }\Omega$ to GND $R_L = 2\text{ k}\Omega$ to GND $R_L = 10\text{ k}\Omega$ to GND $R_L = 150\text{ }\Omega$ to 1.5 V $R_L = 600\text{ }\Omega$ to 1.5 V $R_L = 2\text{ k}\Omega$ to 1.5 V $R_L = 10\text{ k}\Omega$ to 1.5 V $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$ $R_L = 150\text{ }\Omega$ to GND $R_L = 150\text{ }\Omega$ to 1.5 V		10 11 11 11 140 90 68 57	30 300 40 350	mV
GBP	Gain bandwidth product	$F = 10\text{ MHz}$ $A_{VCL} = +11$ $A_{VCL} = -10$		65 55		MHz
Bw	Bandwidth @-3dB	$A_{VCL} = +1$, $R_L = 150\text{ }\Omega$ to 1.5 V		87		
SR	Slew rate	$A_{VCL} = +2$, $R_L = 150\text{ }\Omega$ // C_L to 1.5 V $C_L = 5\text{ pF}$ $C_L = 30\text{ pF}$	45	80 85		V/ μs
ϕ_m	Phase margin	$R_L = 150\text{ }\Omega$ // 30 pF to 1.5 V		40		$^\circ$
e_n	Equivalent input noise voltage	$F = 100\text{ kHz}$		11		nV/ $\sqrt{\text{Hz}}$
THD	Total harmonic distortion	$A_{VCL} = +2$, $F = 4\text{ MHz}$, $R_L = 150\text{ }\Omega$ // 30 pF to 1.5 V $V_{\text{out}} = 1\text{ Vpp}$ $V_{\text{out}} = 2\text{ Vpp}$		-61 -54		dB
IM2	Second order intermodulation product	$A_{VCL} = +2$, $V_{\text{out}} = 2\text{ Vpp}$ $R_L = 150\text{ }\Omega$ to 1.5 V $F_{\text{in1}} = 180\text{ kHz}$, $F_{\text{in2}} = 280\text{ kHz}$ spurious measurements @100 kHz		-76		dBc
IM3	Third order inter modulation product	$A_{VCL} = +2$, $V_{\text{out}} = 2\text{ Vpp}$ $R_L = 150\text{ }\Omega$ to 1.5 V $F_{\text{in1}} = 180\text{ kHz}$, $F_{\text{in2}} = 280\text{ kHz}$ spurious measurements @400 kHz		-68		
ΔG	Differential gain	$A_{VCL} = +2$, $R_L = 150\text{ }\Omega$ to 1.5 V $F = 4.5\text{ MHz}$, $V_{\text{out}} = 2\text{ Vpp}$		0.5		%
Df	Differential phase	$A_{VCL} = +2$, $R_L = 150\text{ }\Omega$ to 1.5 V $F = 4.5\text{ MHz}$, $V_{\text{out}} = 2\text{ Vpp}$		0.5		$^\circ$
Gf	Gain flatness	$F = \text{DC to } 6\text{ MHz}$, $A_{VCL} = +2$		0.2		dB
Vo1/Vo2	Channel separation	$F = 1\text{ MHz to } 10\text{ MHz}$		65		

Table 4. $V_{CC}^+ = 5\text{ V}$, $V_{CC}^- = \text{GND}$, $V_{IC} = 2.5\text{ V}$, $T_{\text{amb}} = 25\text{ }^{\circ}\text{C}$ (unless otherwise specified)

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$ V_{io} $	Input offset voltage	$T_{\text{amb}} = 25\text{ }^{\circ}\text{C}$ $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$		1.1	10 12	mV
ΔV_{io}	Input offset voltage drift vs. temp.	$T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$		3		$\mu\text{V}/^{\circ}\text{C}$
I_{io}	Input offset current	$T_{\text{amb}} = 25\text{ }^{\circ}\text{C}$ $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$		0.1	3.5 5	μA
I_{ib}	Input bias current	$T_{\text{amb}} = 25\text{ }^{\circ}\text{C}$ $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$		6	15 20	
C_{in}	Input capacitance			0.3		pF
I_{CC}	Supply current per operator	$T_{\text{amb}} = 25\text{ }^{\circ}\text{C}$ $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$		8.2	10.5 11.5	mA
CMRR	Common mode rejection ratio ($\delta V_{IC}/\delta V_{io}$)	$+0.1 < V_{IC} < 3.9\text{ V}$ and $V_{out} = 2.5\text{ V}$ $T_{\text{amb}} = 25\text{ }^{\circ}\text{C}$ $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$	72 71	97		dB
SVRR	Supply voltage rejection ratio ($\delta V_{CC}/\delta V_{io}$)	$T_{\text{amb}} = 25\text{ }^{\circ}\text{C}$ $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$	68 67	75		
PSRR	Power supply rejection ratio ($\delta V_{CC}/\delta V_{out}$)	Positive and negative rail		75		
A_{vd}	Large signal voltage gain	$R_L = 150\text{ }\Omega$ to 1.5 V , $V_{out} = 1\text{ V}$ to 4 V $T_{\text{amb}} = 25\text{ }^{\circ}\text{C}$ $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$	75 70	84		
I_o	Output short circuit current source	$T_{\text{amb}} = 25\text{ }^{\circ}\text{C}$, $V_{id} = +1$, V_{out} to 1.5 V , $V_{id} = -1$, V_{out} to 1.5 V I_{Source} I_{Sink} $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$ $V_{id} = +1$, V_{out} to 1.5 V $V_{id} = -1$, V_{out} to 1.5 V I_{Source} I_{Sink}	35 33 34 32	55 55		mA
V_{OH}	High level output voltage	$T_{\text{amb}} = 25\text{ }^{\circ}\text{C}$ $R_L = 150\text{ }\Omega$ to GND $R_L = 600\text{ }\Omega$ to GND $R_L = 2\text{ k}\Omega$ to GND $R_L = 10\text{ k}\Omega$ to GND $R_L = 150\text{ }\Omega$ to 2.5 V $R_L = 600\text{ }\Omega$ to 2.5 V $R_L = 2\text{ k}\Omega$ to 2.5 V $R_L = 10\text{ k}\Omega$ to 2.5 V $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$ $R_L = 150\text{ }\Omega$ to GND $R_L = 150\text{ }\Omega$ to 2.5 V	4.2 4.5 4.1 4.4	4.36 4.85 4.90 4.93 4.66 4.90 4.92 4.93		V

Table 4. $V_{CC}^+ = 5\text{ V}$, $V_{CC}^- = \text{GND}$, $V_{IC} = 2.5\text{ V}$, $T_{\text{amb}} = 25\text{ }^\circ\text{C}$ (unless otherwise specified) (continued)

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
V_{OL}	Low level output voltage	$T_{\text{amb}} = 25\text{ }^\circ\text{C}$ $R_L = 150\text{ }\Omega$ to GND $R_L = 600\text{ }\Omega$ to GND $R_L = 2\text{ k}\Omega$ to GND $R_L = 10\text{ k}\Omega$ to GND $R_L = 150\text{ }\Omega$ to 2.5 V $R_L = 600\text{ }\Omega$ to 2.5 V $R_L = 2\text{ k}\Omega$ to 2.5 V $R_L = 10\text{ k}\Omega$ to 2.5 V $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$ $R_L = 150\text{ }\Omega$ to GND $R_L = 150\text{ }\Omega$ to 2.5 V		20 23 23 23 220 105 76 61	40 400 60 450	mV
GBP	Gain bandwidth product	$F = 10\text{ MHz}$ $A_{VCL} = +11$ $A_{VCL} = -10$		65 55		MHz
Bw	Bandwidth @-3 dB	$A_{VCL} = +1$, $R_L = 150\text{ }\Omega$ to 2.5 V		87		
SR	Slew rate	$A_{VCL} = +2$, $R_L = 150\text{ }\Omega // C_L$ to 2.5 V $C_L = 5\text{ pF}$ $C_L = 30\text{ pF}$	60	104 105		V/ μs
ϕ_m	Phase margin	$R_L = 150\text{ }\Omega // 30\text{ pF}$ to 2.5 V		40		$^\circ$
en	Equivalent input noise voltage	$F = 100\text{ kHz}$		11		nV/ $\sqrt{\text{Hz}}$
THD	Total harmonic distortion	$A_{VCL} = +2$, $F = 4\text{ MHz}$ $R_L = 150\text{ }\Omega // 30\text{ pF}$ to 2.5 V $V_{\text{out}} = 1\text{ Vpp}$ $V_{\text{out}} = 2\text{ Vpp}$		-61 -54		dB
IM2	Second order intermodulation product	$A_{VCL} = +2$, $V_{\text{out}} = 2\text{ Vpp}$ $R_L = 150\text{ }\Omega$ to 2.5 V $F_{\text{in1}} = 180\text{ kHz}$, $F_{\text{in2}} = 280\text{ kHz}$ spurious measurements @100 kHz		-76		dBc
IM3	Third order inter modulation product	$A_{VCL} = +2$, $V_{\text{out}} = 2\text{ Vpp}$ $R_L = 150\text{ }\Omega$ to 2.5 V $F_{\text{in1}} = 180\text{ kHz}$, $F_{\text{in2}} = 280\text{ kHz}$ spurious measurements @400 kHz		-68		
ΔG	Differential gain	$A_{VCL} = +2$, $R_L = 150\text{ }\Omega$ to 2.5 V $F = 4.5\text{ MHz}$, $V_{\text{out}} = 2\text{ Vpp}$		0.5		%
Df	Differential phase	$A_{VCL} = +2$, $R_L = 150\text{ }\Omega$ to 2.5 V $F = 4.5\text{ MHz}$, $V_{\text{out}} = 2\text{ Vpp}$		0.5		$^\circ$
Gf	Gain flatness	$F = \text{DC to } 6\text{ MHz}$, $A_{VCL} = +2$		0.2		dB
Vo1/Vo2	Channel separation	$F = 1\text{ MHz to } 10\text{ MHz}$		65		

Table 5. $V_{CC}^+ = 5\text{ V}$, $V_{CC}^- = -5\text{ V}$, $V_{IC} = \text{GND}$, $T_{\text{amb}} = 25\text{ }^{\circ}\text{C}$ (unless otherwise specified)

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$ V_{io} $	Input offset voltage	$T_{\text{amb}} = 25\text{ }^{\circ}\text{C}$ $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$		0.8	10 12	mV
ΔV_{io}	Input offset voltage drift vs. temp.	$T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$		2		$\mu\text{V}/^{\circ}\text{C}$
I_{io}	Input offset current	$T_{\text{amb}} = 25\text{ }^{\circ}\text{C}$ $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$		0.1	3.5 5	μA
I_{ib}	Input bias current	$T_{\text{amb}} = 25\text{ }^{\circ}\text{C}$ $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$		6	15 20	
C_{in}	Input capacitance			0.7		pF
I_{CC}	Supply current per operator	$T_{\text{amb}} = 25\text{ }^{\circ}\text{C}$ $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$		9.8	12.3 13.4	mA
CMRR	Common mode rejection ratio ($\delta V_{IC}/\delta V_{io}$)	$-4.9 < V_{IC} < 3.9\text{ V}$ and $V_{out} = \text{GND}$ $T_{\text{amb}} = 25\text{ }^{\circ}\text{C}$ $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$	81 80	106		dB
SVRR	Supply voltage rejection ratio ($\delta V_{CC}/\delta V_{io}$)	$T_{\text{amb}} = 25\text{ }^{\circ}\text{C}$ $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$	71 70	77		
PSRR	Power supply rejection ratio ($\delta V_{CC}/\delta V_{out}$)	Positive and negative rail		75		
A_{vd}	Large signal voltage gain	$R_L = 150\text{ }\Omega$ to GND $V_{out} = -4$ to $+4$ $T_{\text{amb}} = 25\text{ }^{\circ}\text{C}$ $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$	75 70	86		
I_o	Output short circuit current source	$T_{\text{amb}} = 25\text{ }^{\circ}\text{C}$ $V_{id} = +1$, V_{out} to 1.5 V $V_{id} = -1$, V_{out} to 1.5 V I_{Source} I_{Sink} $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$ $V_{id} = +1$, V_{out} to 1.5 V $V_{id} = -1$, V_{out} to 1.5 V I_{Source} I_{Sink}	35 30 34 29	55 55		mA
V_{OH}	High level output voltage	$T_{\text{amb}} = 25\text{ }^{\circ}\text{C}$ $R_L = 150\text{ }\Omega$ to GND $R_L = 600\text{ }\Omega$ to GND $R_L = 2\text{ k}\Omega$ to GND $R_L = 10\text{ k}\Omega$ to GND $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$ $R_L = 150\text{ }\Omega$ to GND	4.2 4.1	4.36 4.85 4.9 4.93		V
V_{OL}	Low level output voltage	$T_{\text{amb}} = 25\text{ }^{\circ}\text{C}$ $R_L = 150\text{ }\Omega$ to GND $R_L = 600\text{ }\Omega$ to GND $R_L = 2\text{ k}\Omega$ to GND $R_L = 10\text{ k}\Omega$ to GND $T_{\text{min.}} < T_{\text{amb}} < T_{\text{max.}}$ $R_L = 150\text{ }\Omega$ to GND		-4.63 -4.86 -4.9 -4.93	-4.4 -4.3	V

Table 5. $V_{CC}^+ = 5\text{ V}$, $V_{CC}^- = -5\text{ V}$, $V_{IC} = \text{GND}$, $T_{\text{amb}} = 25\text{ }^\circ\text{C}$ (unless otherwise specified) (continued)

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
GBP	Gain bandwidth product	$F = 10\text{ MHz}$ $A_{VCL} = +11$ $A_{VCL} = -10$		65 55		MHz
Bw	Bandwidth @-3dB	$A_{VCL} = +1$ $R_L = 150\text{ }\Omega // 30\text{ pF to GND}$		100		MHz
SR	Slew rate	$A_{VCL} = +2$, $R_L = 150\text{ }\Omega // C_L \text{ to GND}$ $C_L = 5\text{ pF}$ $C_L = 30\text{ pF}$	68	117 118		V/ μs
ϕ_m	Phase margin	$R_L = 150\text{ }\Omega \text{ to GND}$		40		$^\circ$
en	Equivalent input noise voltage	$F = 100\text{ kHz}$		11		nV/ $\sqrt{\text{Hz}}$
THD	Total harmonic distortion	$A_{VCL} = +2$, $F = 4\text{ MHz}$ $R_L = 150\text{ }\Omega // 30\text{ pF to GND}$ $V_{out} = 1\text{ Vpp}$ $V_{out} = 2\text{ Vpp}$		-61 -54		dB
IM2	Second order intermodulation product	$A_{VCL} = +2$, $V_{out} = 2\text{ Vpp}$ $R_L = 150\text{ }\Omega \text{ to GND}$ $F_{in1} = 180\text{ kHz}$, $F_{in2} = 280\text{ kHz}$ spurious measurements @100 kHz		-76		dBc
IM3	Third order intermodulation product	$A_{VCL} = +2$, $V_{out} = 2\text{ Vpp}$ $R_L = 150\text{ }\Omega \text{ to GND}$ $F_{in1} = 180\text{ kHz}$, $F_{in2} = 280\text{ kHz}$ spurious measurements @400 kHz		-68		
ΔG	Differential gain	$A_{VCL} = +2$, $R_L = 150\text{ }\Omega \text{ to GND}$ $F = 4.5\text{ MHz}$, $V_{out} = 2\text{ Vpp}$		0.5		%
Df	Differential phase	$A_{VCL} = +2$, $R_L = 150\text{ }\Omega \text{ to GND}$ $F = 4.5\text{ MHz}$, $V_{out} = 2\text{ Vpp}$		0.5		$^\circ$
Gf	Gain flatness	$F = \text{DC to } 6\text{ MHz}$, $A_{VCL} = +2$		0.2		dB
Vo1/Vo2	Channel separation	$F = 1\text{ MHz to } 10\text{ MHz}$		65		

3.1 Standby mode

Table 6. V_{CC}^+ , V_{CC}^- , $T_{amb} = 25\text{ °C}$ (unless otherwise specified)

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
V_{low}	Standby low level		V_{CC}^-		$(V_{CC}^- + 0.8)$	V
V_{high}	Standby high level		$(V_{CC}^- + 2)$		(V_{CC}^+)	
$I_{CC\ STBY}$	Current consumption per operator when STANDBY is active	Pin 8 (TSH71) to V_{CC}^- Pin 1, 2 or 3 (TSH73) to V_{CC}^- Pin 8 (TSH75) to V_{CC}^+ Pin 9 (TSH75) to V_{CC}^-		20	55	μA
Z_{out}	Output impedance (R_{out}/C_{out})	R_{out} C_{out}		10 17		M Ω pF
T_{on}	Time from standby mode to active mode			2		μs
T_{off}	Time from active mode to standby mode	Down to $I_{CC\ STBY} = 10\text{ }\mu A$		10		

Table 7. TSH71 standby function table

TSH71 standby control pin 8 ($\overline{STBY}$)	Operator status
V_{low}	Standby
V_{high}	Active

Table 8. TSH73 standby function table

TSH73 standby control			Operator status		
Pin 1 ($\overline{STBY\ OP1}$)	Pin 2 ($\overline{STBY\ OP2}$)	Pin 3 ($\overline{STBY\ OP3}$)	OP1	OP1	OP3
V_{low}	x	x	Standby	x	x
V_{high}	x	x	Active	x	x
x	V_{low}	x	x	Standby	x
x	V_{high}		x	Active	x
x	x	V_{low}	x	x	Standby
x	x	V_{high}	x	x	Active

Table 9. TSH75 standby function table

TSH75 standby control		Operator status			
Pin 8 (STBY OP2)	Pin 9 (STBY OP3)	OP1	OP2	OP3	OP4
V_{high}	V_{low}	Active	Standby	Standby	Active
V_{high}	V_{high}			Active	
V_{low}	V_{low}		Active	Standby	
V_{low}	V_{high}			Active	

3.2 Characteristic curves for $V_{CC} = 3\text{ V}$

Figure 2. Closed loop gain and phase vs. frequency (gain = +2, $V_{CC} = \pm 1.5\text{ V}$, $R_L = 150\ \Omega$, $T_{amb} = 25\text{ }^\circ\text{C}$)

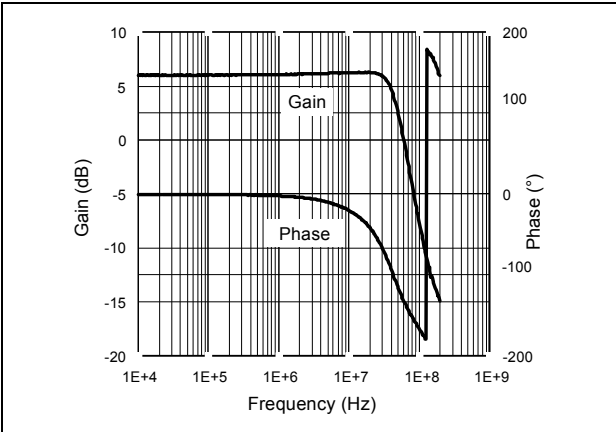


Figure 3. Overshoot function of output capacitance (gain = +2, $V_{CC} = \pm 1.5\text{ V}$, $T_{amb} = 25\text{ }^\circ\text{C}$)

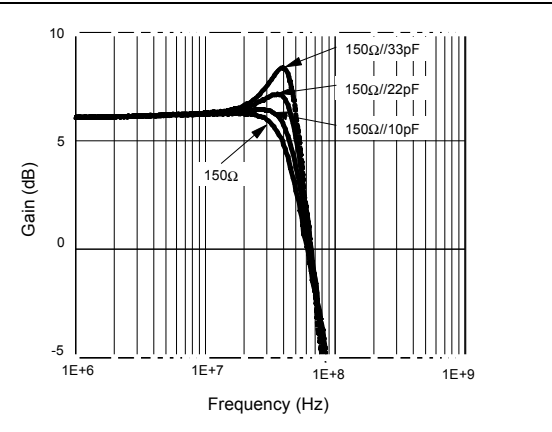


Figure 4. Closed loop gain and phase vs. frequency (gain = -10, $V_{CC} = \pm 1.5\text{ V}$, $R_L = 150\ \Omega$, $T_{amb} = 25\text{ }^\circ\text{C}$)

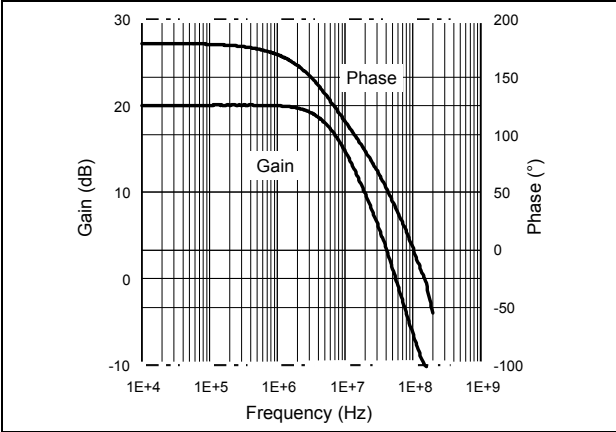


Figure 5. Closed loop gain and phase vs. frequency (gain = +11, $V_{CC} = \pm 1.5\text{ V}$, $R_L = 150\ \Omega$, $T_{amb} = 25\text{ }^\circ\text{C}$)

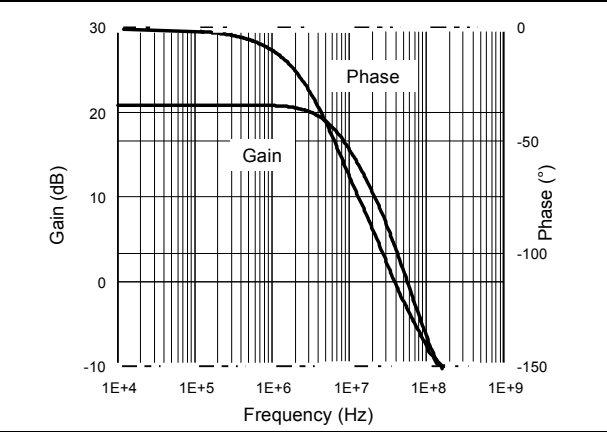


Figure 6. Large signal measurement - positive slew rate (gain = 2, $V_{CC} = \pm 1.5$ V, $Z_L = 150\ \Omega // 5.6$ pF)

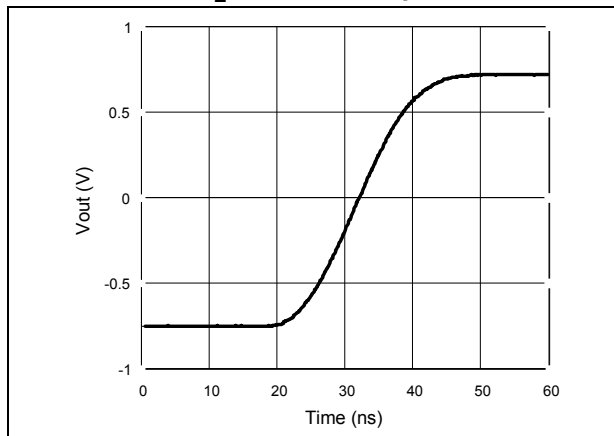


Figure 7. Large signal measurement - negative slew rate (gain = 2, $V_{CC} = \pm 1.5$ V, $Z_L = 150\ \Omega // 5.6$ pF)

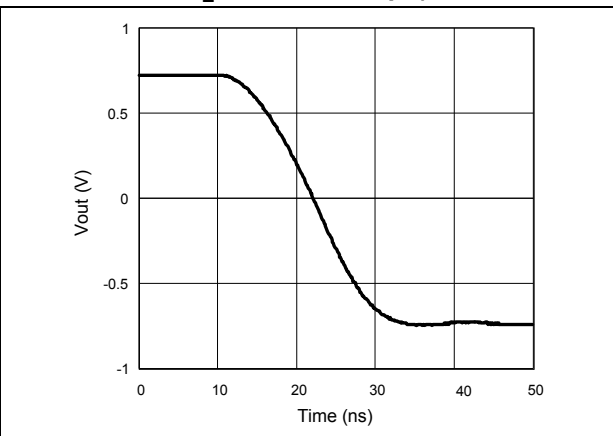


Figure 8. Small signal measurement - rise time (gain = 2, $V_{CC} = \pm 1.5$ V, $Z_L = 150\ \Omega$)

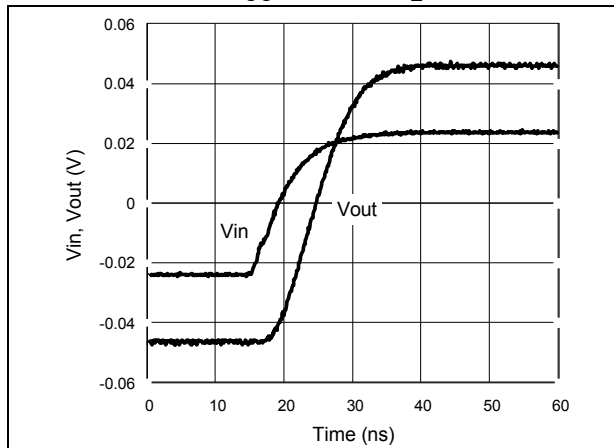


Figure 9. Small signal measurement - fall time (gain = 2, $V_{CC} = \pm 1.5$ V, $Z_L = 150\ \Omega$)

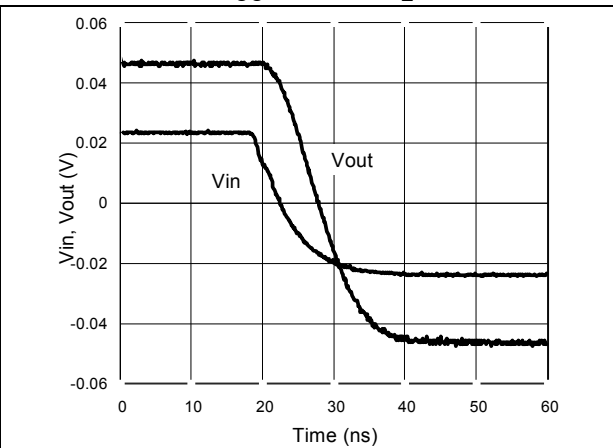


Figure 10. Channel separation (Xtalk) vs. frequency (measurement configuration: $X_{talk} = 20 \log (V_0/V_1)$)

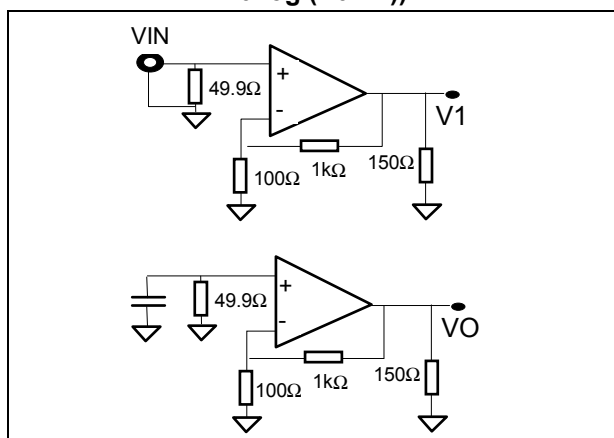


Figure 11. Channel separation (Xtalk) vs. frequency (gain = +11, $V_{CC} = 1.5$ V, $Z_L = 150\ \Omega // 27$ pF)

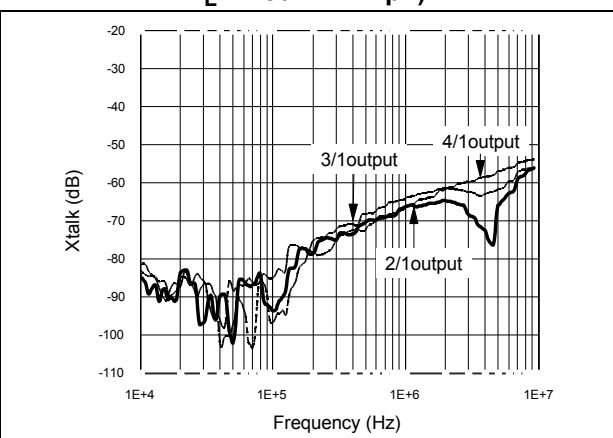


Figure 12. Equivalent noise voltage
(gain = 100, $V_{CC} = \pm 1.5$ V, No load)

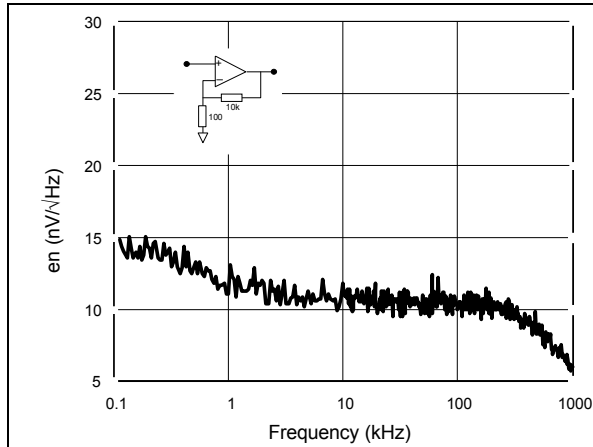


Figure 13. Maximum output swing
(gain = 11, $V_{CC} = \pm 5$ V, $R_L = 150 \Omega$)

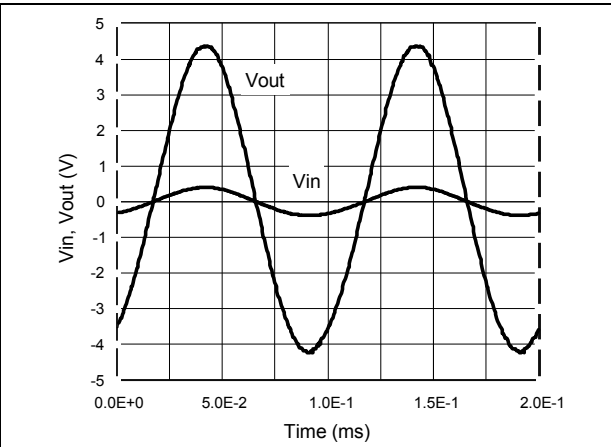


Figure 14. Standby mode - T_{on} , T_{off}
($V_{CC} = \pm 1.5$ V, open loop)

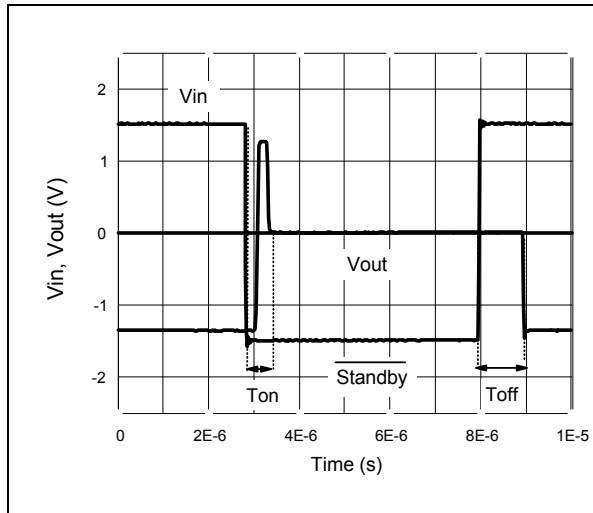


Figure 15. Group delay gain = 2 ($V_{CC} = \pm 1.5$ V, $Z_L = 150 \Omega // 27$ pF, $T_{amb} = 25^\circ\text{C}$)

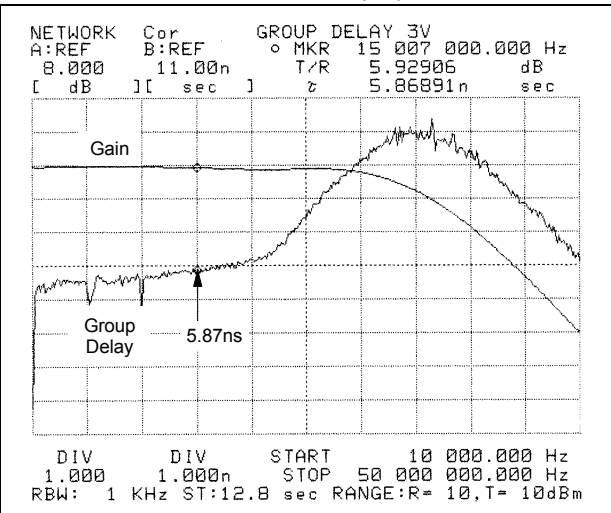
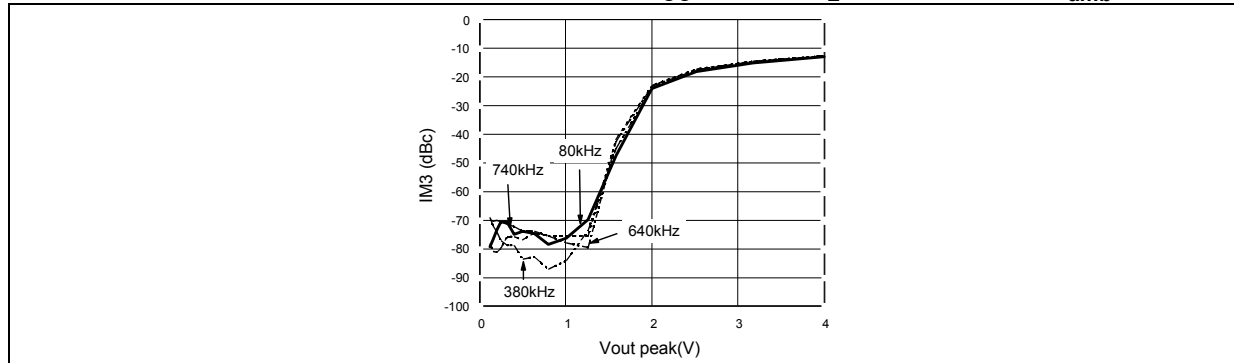


Figure 16. Third order intermodulation (gain = 2, $V_{CC} = \pm 1.5$ V, $Z_L = 150 \Omega // 27$ pF, $T_{amb} = 25^\circ\text{C}$)



- Note on intermodulation products:
The IFR2026 synthesizer generates a two tone signal ($F_1 = 180$ kHz, $F_2 = 280$ kHz); each tone has the same amplitude level.
The HP3585 spectrum analyzer measures the intermodulation products function of the output voltage. The generator and the spectrum analyzer are phase locked for precision considerations.

3.3 Characteristic curves for $V_{CC} = 5\text{ V}$

Figure 17. Closed loop gain and phase vs. frequency (gain = +2, $V_{CC} = \pm 2.5\text{ V}$, $R_L = 150\ \Omega$, $T_{amb} = 25\text{ }^\circ\text{C}$)

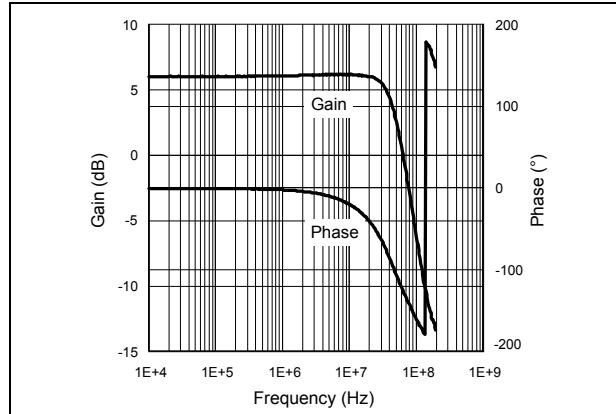


Figure 18. Overshoot function of output capacitance (gain = +2, $V_{CC} = \pm 2.5\text{ V}$, $T_{amb} = 25\text{ }^\circ\text{C}$)

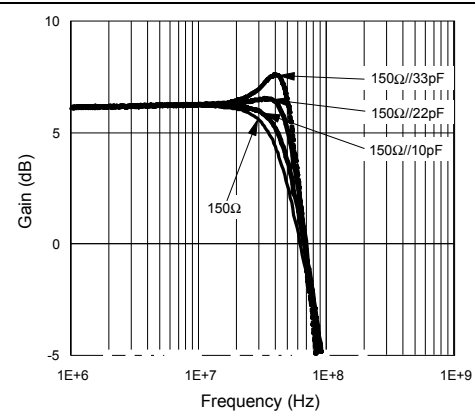


Figure 19. Closed loop gain and phase vs. frequency (gain = -10, $V_{CC} = \pm 2.5\text{ V}$, $R_L = 150\ \Omega$, $T_{amb} = 25\text{ }^\circ\text{C}$)

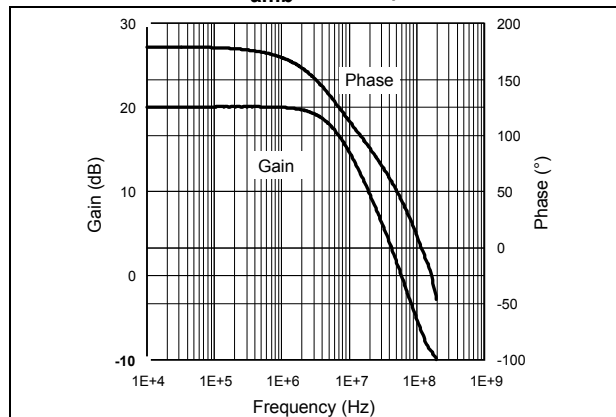


Figure 20. Closed loop gain and phase vs. frequency (gain = +11, $V_{CC} = \pm 2.5\text{ V}$, $R_L = 150\ \Omega$, $T_{amb} = 25\text{ }^\circ\text{C}$)

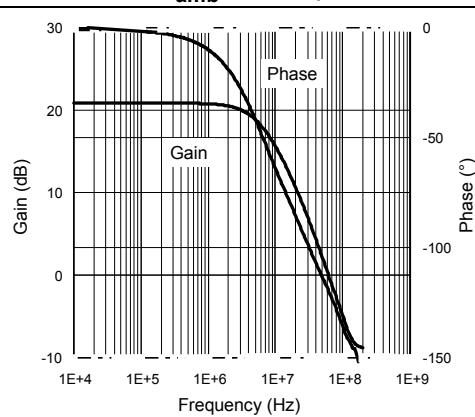


Figure 21. Large signal measurement - positive slew rate (gain = 2, $V_{CC} = \pm 2.5\text{ V}$, $Z_L = 150\ \Omega // 5.6\text{ pF}$)

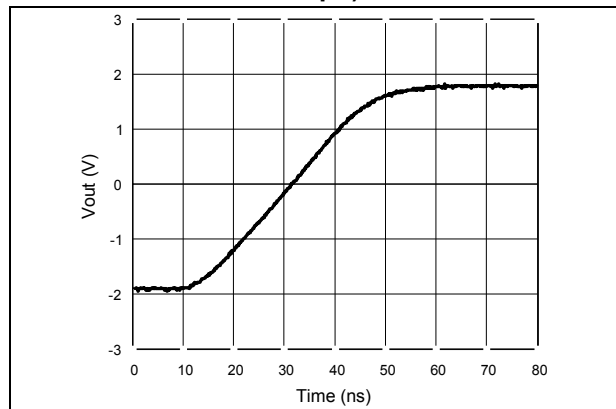


Figure 22. Large signal measurement - negative slew rate (gain = 2, $V_{CC} = \pm 2.5\text{ V}$, $Z_L = 150\ \Omega // 5.6\text{ pF}$)

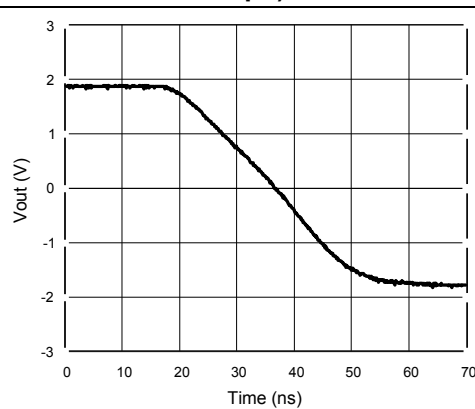


Figure 23. Small signal measurement - rise time
(gain = 2, $V_{CC} = \pm 2.5\text{ V}$, $Z_L = 150\ \Omega$)

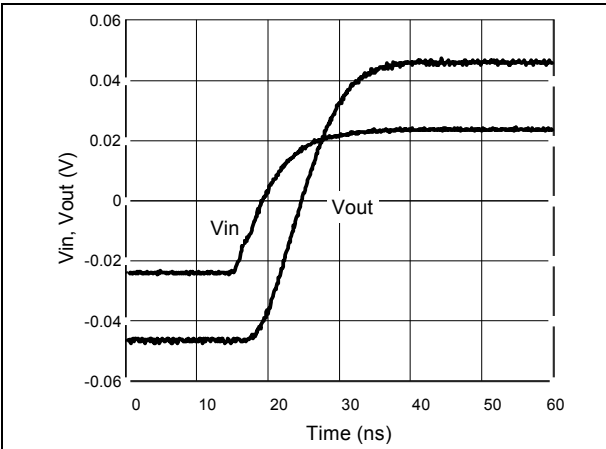


Figure 24. Small signal measurement - fall time
(gain = 2, $V_{CC} = \pm 2.5\text{ V}$, $Z_L = 150\ \Omega$)

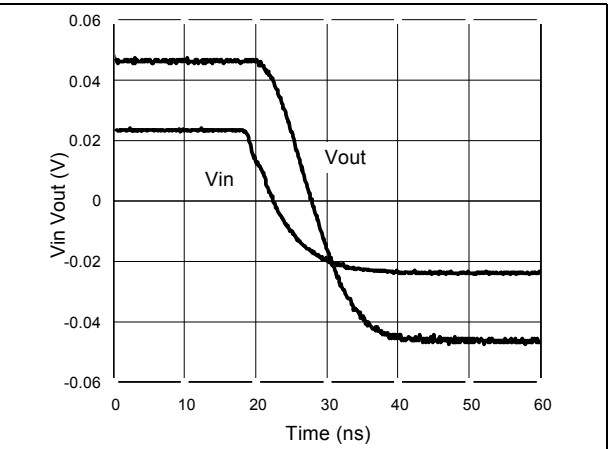


Figure 25. Channel separation (Xtalk) vs. frequency (measurement configuration: $X_{talk} = 20 \log (V_0/V_1)$)

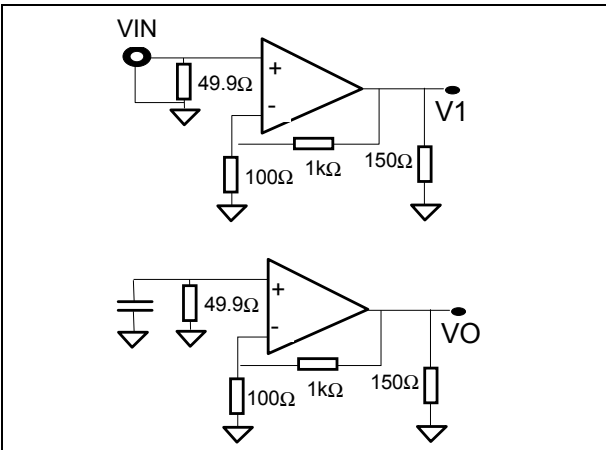


Figure 26. Channel separation (Xtalk) vs. frequency (gain = +11, $V_{CC} = \pm 2.5\text{ V}$, $Z_L = 150\ \Omega // 27\text{ pF}$)

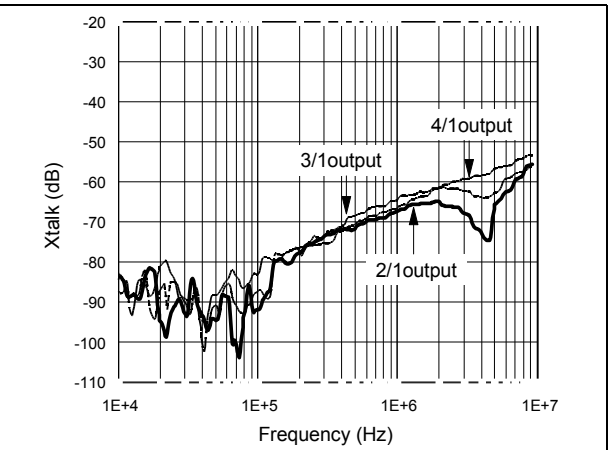


Figure 27. Equivalent noise voltage
(gain = 100, $V_{CC} = \pm 2.5\text{ V}$, no load)

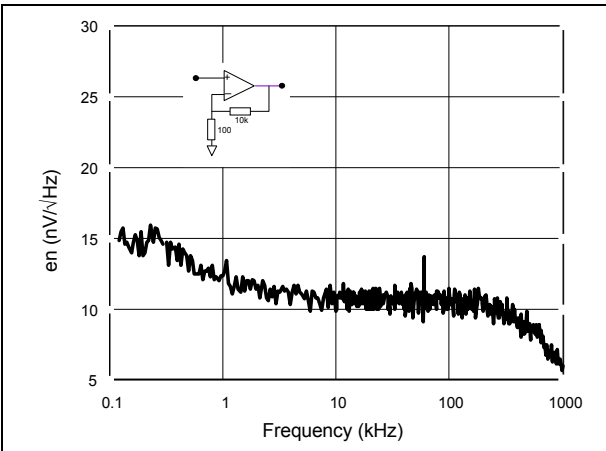


Figure 28. Maximum output swing
(gain = 11, $V_{CC} = \pm 2.5\text{ V}$, $R_L = 150\ \Omega$)

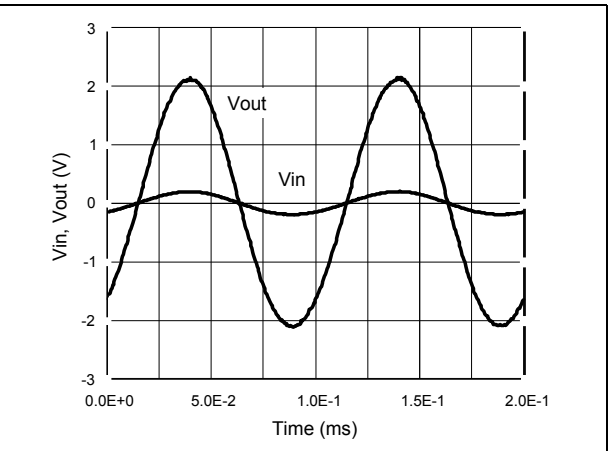


Figure 29. Standby mode - T_{on} , T_{off}
($V_{CC} = \pm 2.5$ V, open loop)

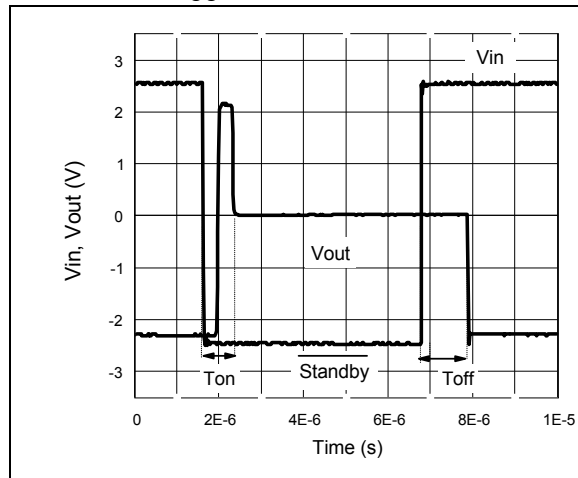


Figure 30. Group delay (gain = 2, $V_{CC} = \pm 2.5$ V, $Z_L = 150 \Omega // 27$ pF, $T_{amb} = 25^\circ\text{C}$)

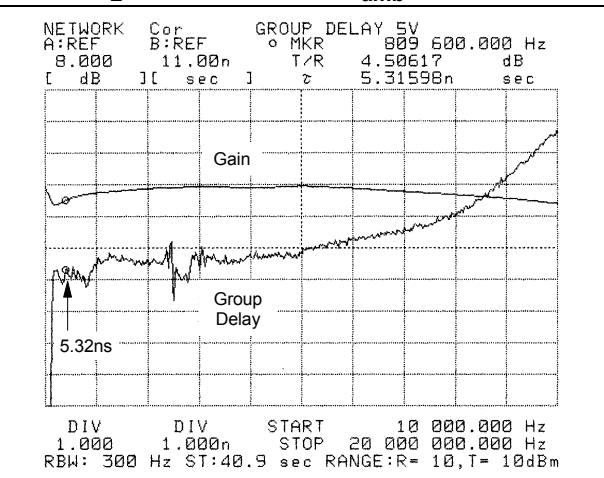
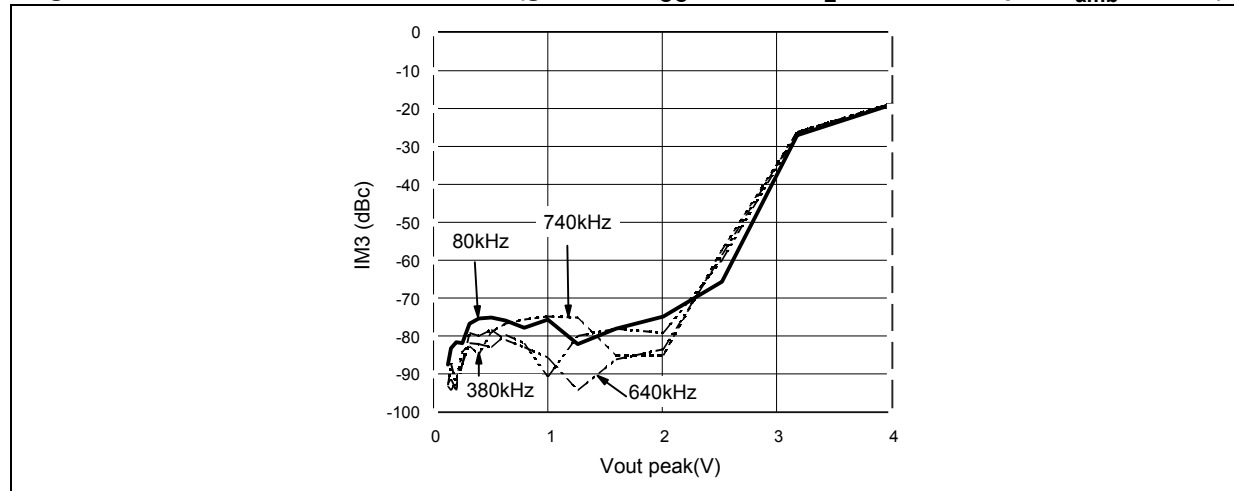


Figure 31. Third order intermodulation (gain = 2, $V_{CC} = \pm 2.5$ V, $Z_L = 150 \Omega // 27$ pF, $T_{amb} = 25^\circ\text{C}$)



- Note on intermodulation products:
The IFR2026 synthesizer generates a two tone signal ($F_1 = 180$ kHz, $F_2 = 280$ kHz); each tone has the same amplitude level.
The HP3585 spectrum analyzer measures the intermodulation products function of the output voltage. The generator and the spectrum analyzer are phase locked for precision considerations.

3.4 Characteristic curves for $V_{CC} = 10\text{ V}$

Figure 32. Closed loop gain and phase vs. frequency (gain = +2, $V_{CC} = \pm 5\text{ V}$, $R_L = 150\ \Omega$, $T_{amb} = 25\text{ }^\circ\text{C}$)

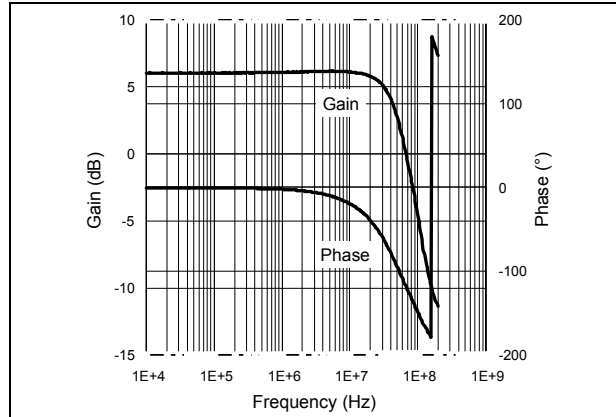


Figure 33. Overshoot function of output capacitance (gain = +2, $V_{CC} = \pm 5\text{ V}$, $T_{amb} = 25\text{ }^\circ\text{C}$)

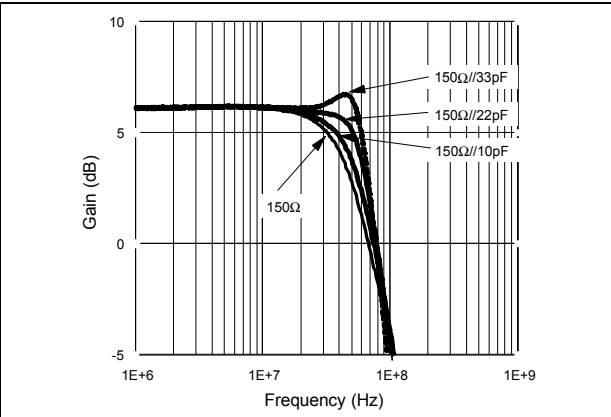


Figure 34. Closed loop gain and phase vs. frequency (gain = -10, $V_{CC} = \pm 5\text{ V}$, $R_L = 150\ \Omega$, $T_{amb} = 25\text{ }^\circ\text{C}$)

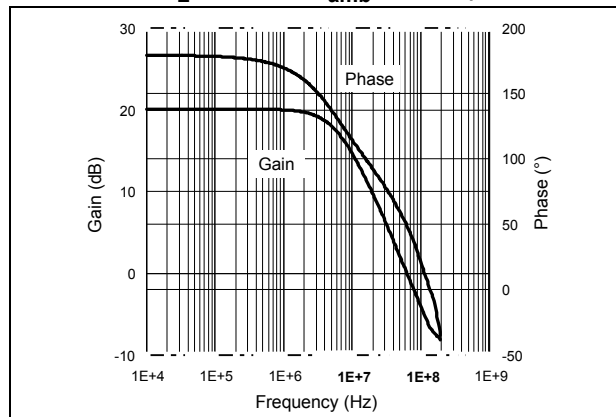


Figure 35. Closed loop gain and phase vs. frequency (gain = +11, $V_{CC} = \pm 5\text{ V}$, $R_L = 150\ \Omega$, $T_{amb} = 25\text{ }^\circ\text{C}$)

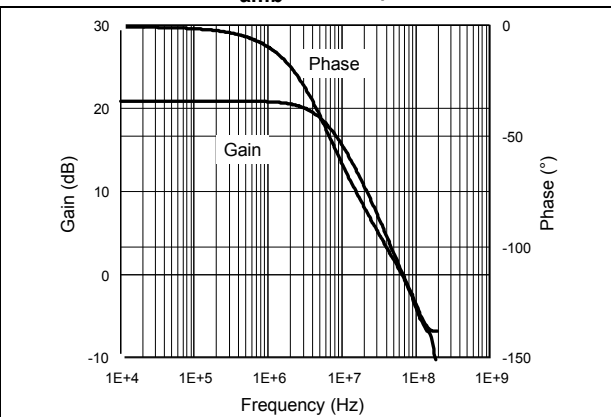


Figure 36. Large signal measurement - positive slew rate (gain = 2, $V_{CC} = \pm 5\text{ V}$, $Z_L = 150\ \Omega // 5.6\text{ pF}$)

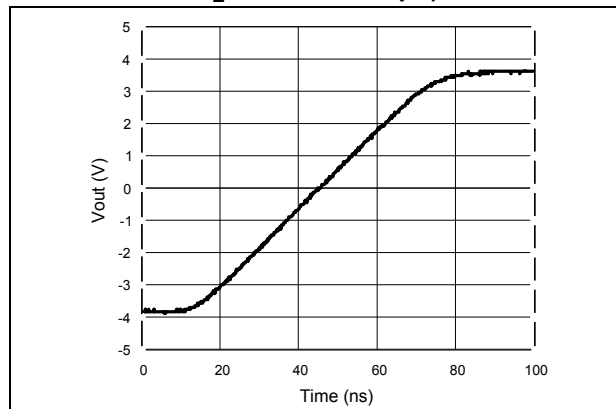


Figure 37. Large signal measurement - negative slew rate (gain = 2, $V_{CC} = \pm 5\text{ V}$, $Z_L = 150\ \Omega // 5.6\text{ pF}$)

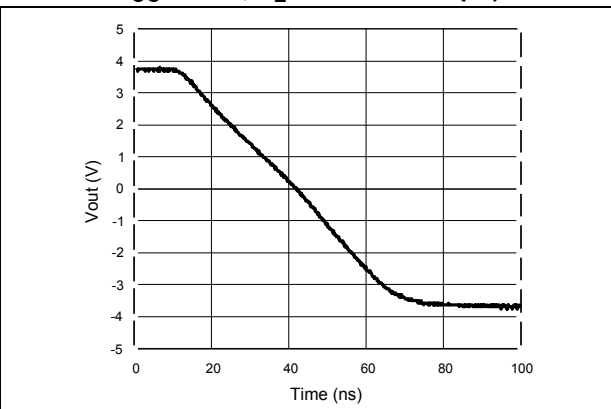


Figure 38. Small signal measurement - rise time (gain = 2, $V_{CC} = \pm 5\text{ V}$, $Z_L = 150\ \Omega$)

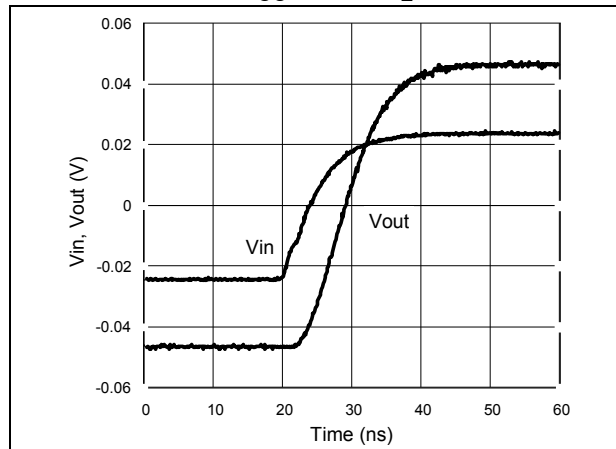


Figure 39. Small signal measurement - fall time (gain = 2, $V_{CC} = \pm 5\text{ V}$, $Z_L = 150\ \Omega$)

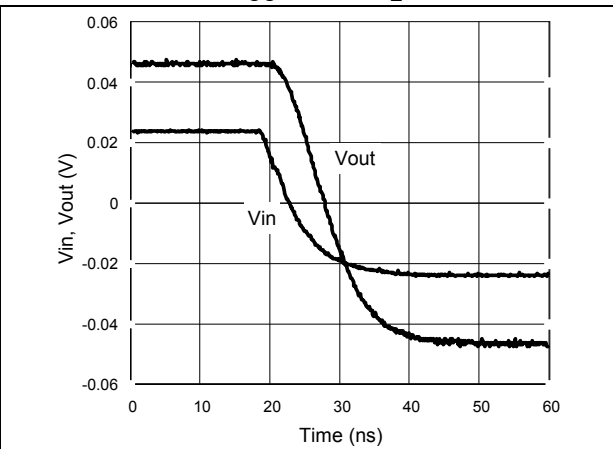


Figure 40. Channel separation (Xtalk) vs. frequency (measurement configuration: $X_{talk} = 20 \log(V_0/V_1)$)

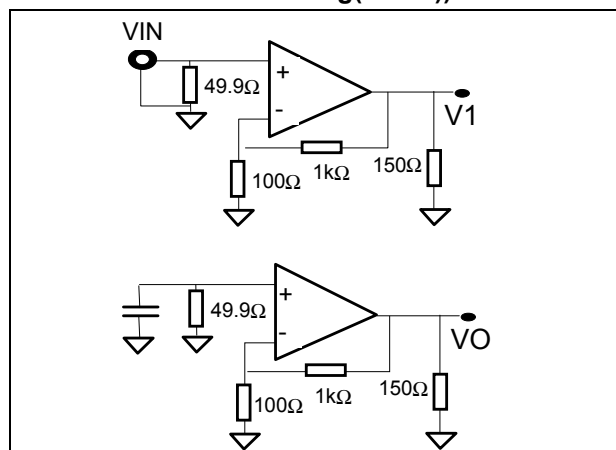


Figure 41. Channel separation (Xtalk) vs. frequency (gain = +11, $V_{CC} = \pm 5\text{ V}$, $Z_L = 150\ \Omega // 27\text{ pF}$)

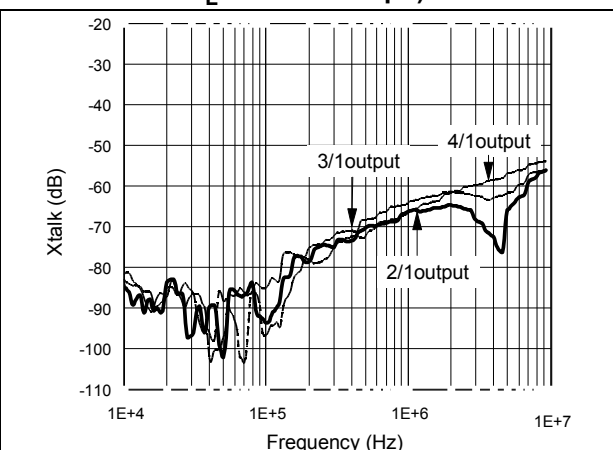


Figure 42. Equivalent noise voltage (gain = 100, $V_{CC} = \pm 5\text{ V}$, no load)

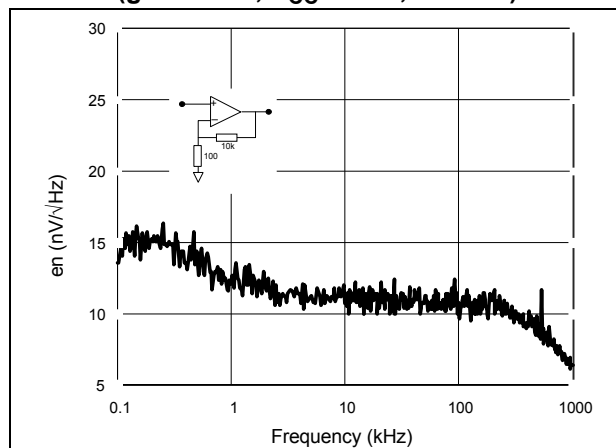


Figure 43. Maximum output swing (gain = 11, $V_{CC} = \pm 5\text{ V}$, $R_L = 150\ \Omega$)

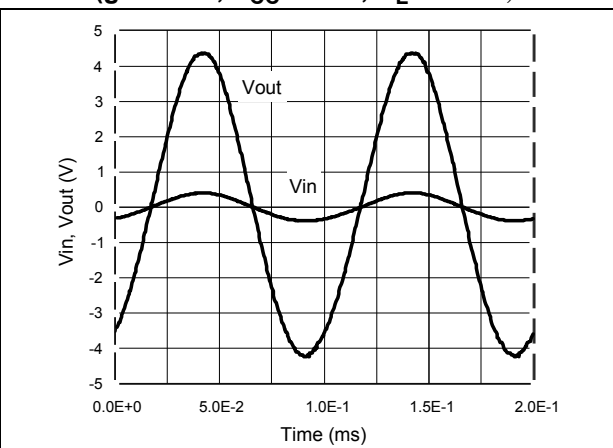


Figure 44. Standby mode - T_{on} , T_{off}
($V_{CC} = \pm 5$ V, open loop)

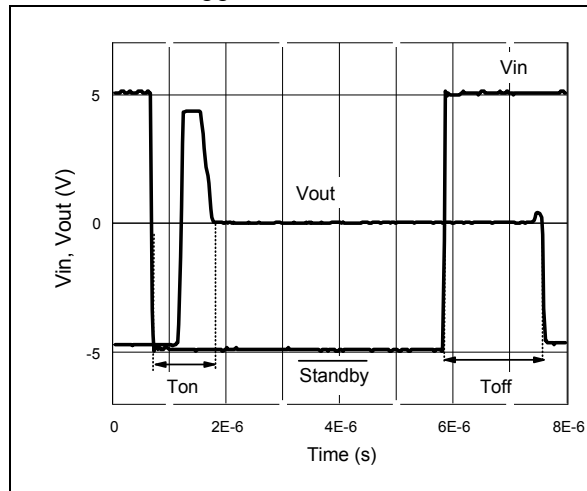


Figure 45. Group delay (gain = 2, $V_{CC} = \pm 5$ V
 $Z_L = 150 \Omega // 27$ pF, $T_{amb} = 25^\circ\text{C}$)

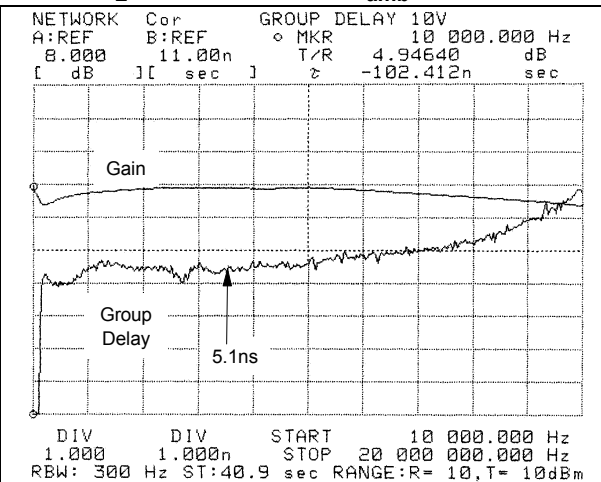
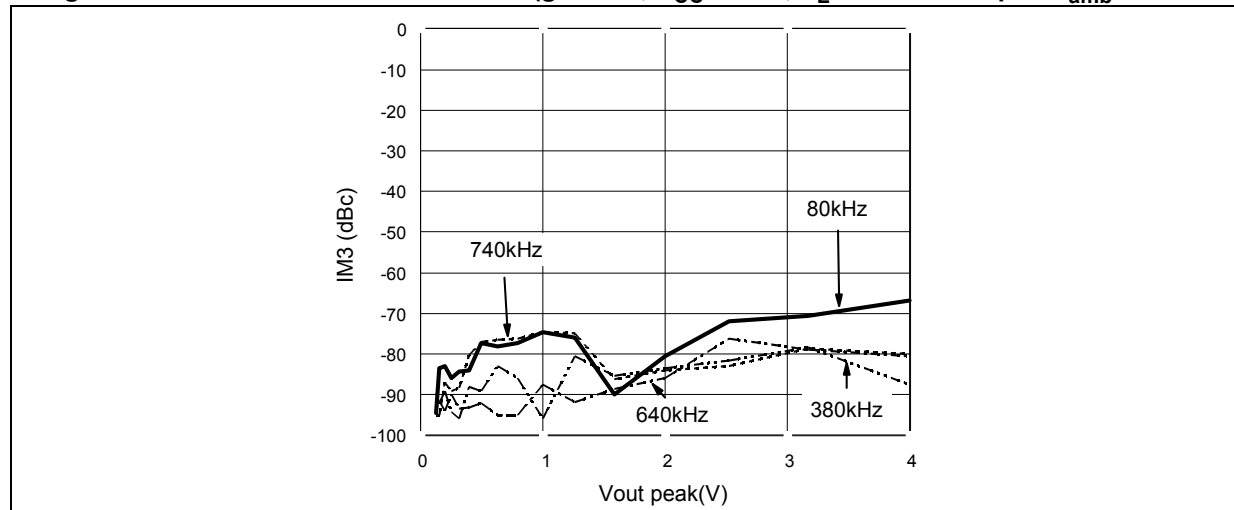


Figure 46. Third order intermodulation (gain = 2, $V_{CC} = \pm 5$ V, $Z_L = 150 \Omega // 27$ pF, $T_{amb} = 25^\circ\text{C}$



- Note on intermodulation products:
The IFR2026 synthesizer generates a two tone signal ($F_1 = 180$ kHz, $F_2 = 280$ kHz); each tone has the same amplitude level.
The HP3585 spectrum analyzer measures the intermodulation products function of the output voltage. The generator and the spectrum analyzer are phase locked for precision considerations.

4 Testing conditions

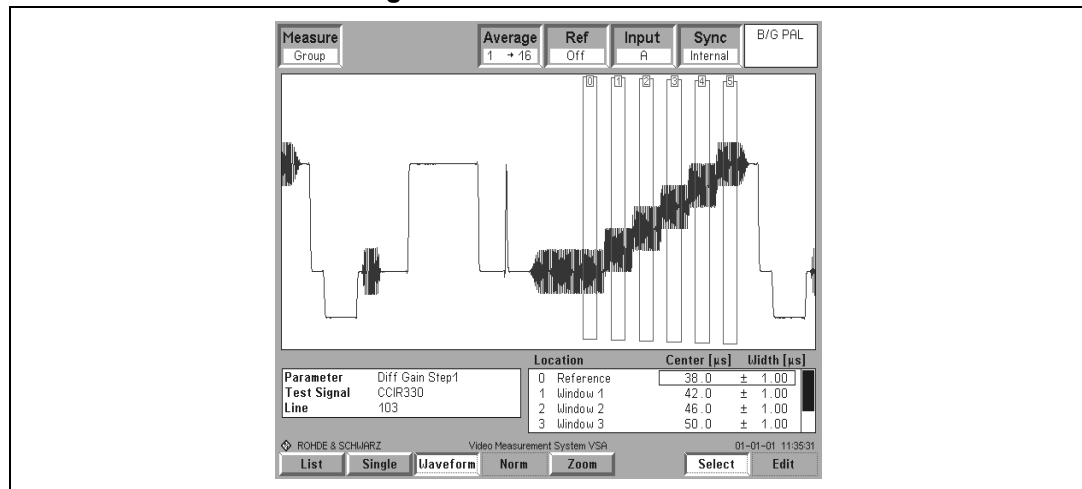
4.1 Layout precautions

To use the TSH7X circuits in the best manner at high frequencies, some precautions have to be taken for power supplies:

- First of all, the implementation of a proper ground plane on both sides of the PCB is mandatory for high-speed circuit applications to provide low inductance and low resistance common return.
- Power supply bypass capacitors (4.7 μ F and ceramic 100 pF) should be placed as close as possible to the IC pins in order to improve high frequency bypassing and reduce harmonic distortion. The power supply capacitors must be incorporated for both the negative and the positive pins.
- Proper termination of all inputs and outputs must be in accordance with output termination resistors. In this way, the amplifier load is resistive only, and the stability of the amplifier is improved.
- All leads must be wide and as short as possible (especially for op-amp inputs and outputs) in order to decrease parasitic capacitance and inductance.
- For lower gain applications, care should be taken to avoid large feedback resistance ($> 1 \text{ k}\Omega$) in order to reduce the time constant of parasitic capacitances.
- Choose component sizes as small as possible (SMD)
- Finally, on output, the load capacitance must be negligible to maintain good stability. You can put a serial resistance as close as possible to the output pin to minimize capacitance.

4.2 Maximum input level

Figure 47. CCIR330 video line



The input level must not exceed the following values:

- Negative peak: must be greater than $-V_{CC}+400$ mV
- Positive peak value: must be lower than $+V_{CC}-400$ mV

The electrical characteristics show the influence of the load on this parameter.

4.3 Video capabilities

To characterize the differential phase and differential gain, a CCIR330 video line is used.

The video line contains five (flat) levels of luma on which is superimposed a chroma signal. The first level contains no luma. The luma gives various amplitudes which define the saturation of the signal. The chrominance gives various phases which define the color of the signal.

Differential phase (respectively differential gain) distortion is present if a signal chrominance phase (gain) is affected by luminance level. They represent the ability to uniformly process the high frequency information at all luminance levels.

When differential gain is present, color saturation is not correctly reproduced.

The input generator is the Rohde and Schwarz CCVS. The output measurement was made by the Rohde and Schwarz VSA.

Figure 48. Measurement on Rohde and Schwarz VSA

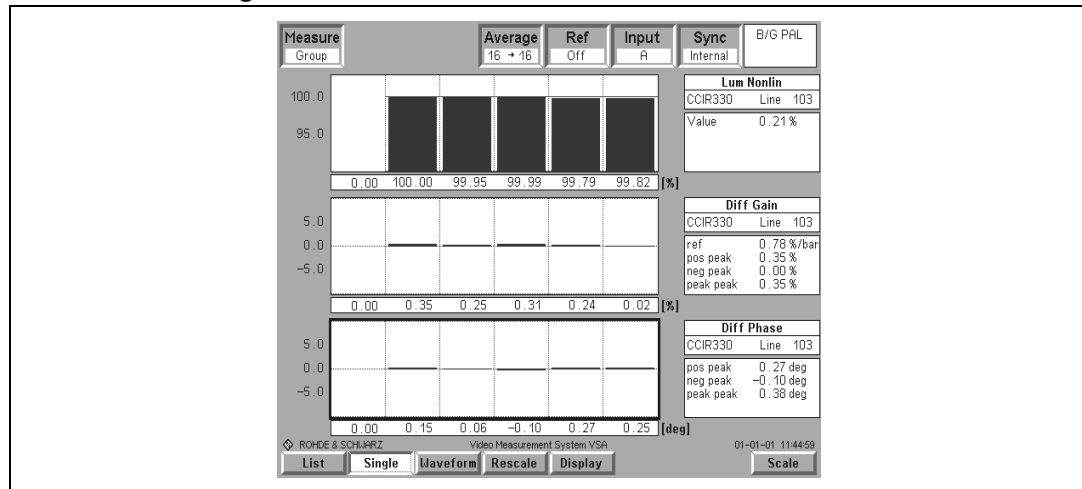


Table 10. Video results

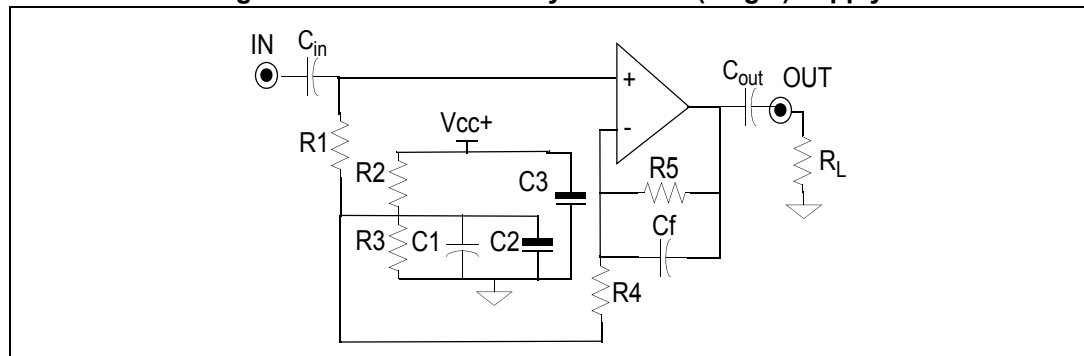
Parameter	Value $V_{CC} = \pm 2.5 \text{ V}$	Value $V_{CC} = \pm 5 \text{ V}$	Unit
Lum NL	0.1	0.3	%
Lum NL step 1	100	100	
Lum NL step 2	100	99.9	
Lum NL step 3	99.9	99.8	
Lum NL step 4	99.9	99.9	
Lum NL step 5	99.9	99.7	
Diff gain pos	0	0	
Diff gain neg	-0.7	-0.6	
Diff gain pp	0.7	0.6	
Diff gain step1	-0.5	-0.3	
Diff gain step2	-0.7	-0.6	
Diff gain step3	-0.3	-0.5	
Diff gain step4	-0.1	-0.3	
Diff gain step5	-0.4	-0.5	
Diff phase pos	0	0.1	deg
Diff phase neg	-0.2	-0.4	
Diff phase pp	0.2	0.5	
Diff phase step1	-0.2	-0.4	
Diff phase step2	-0.1	-0.4	
Diff phase step3	-0.1	-0.3	
Diff phase step4	0	0.1	
Diff phase step5	-0.2	-0.1	

4.4 Precautions when operating on an asymmetrical supply

The TSH7X can be used with either a dual or a single supply. If a single supply is used, the inputs are biased to the mid-supply voltage ($+V_{CC}/2$). This bias network must be carefully designed, in order to reject any noise present on the supply rail.

As the bias current is $15\text{ }\mu\text{A}$, you must carefully choose the resistance $R1$ so as not to introduce an offset mismatch at the amplifier inputs.

Figure 49. Schematic of asymmetrical (single) supply

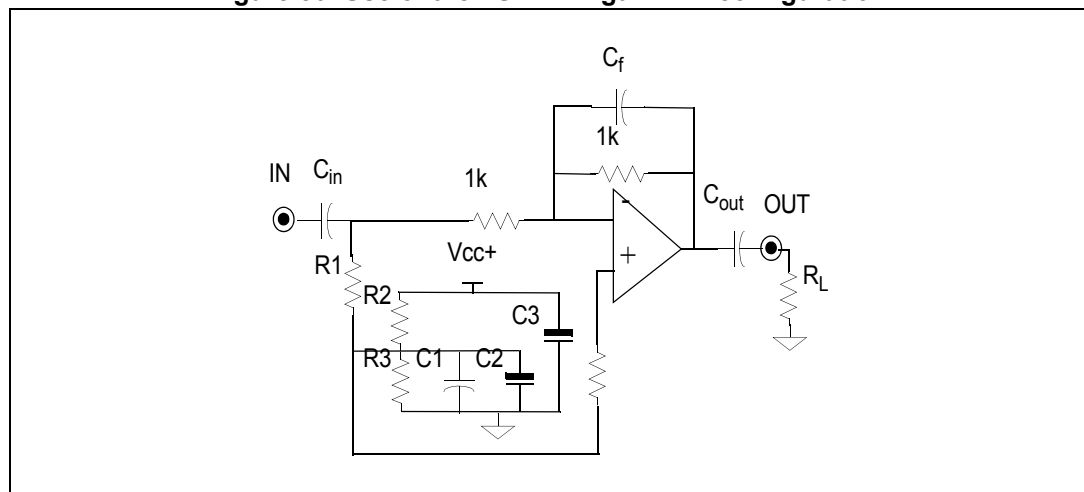


$R1 = 10\text{ k}\Omega$ is a typical and convenient value. $C1$, $C2$, $C3$ are bypass capacitors that filter perturbations on V_{CC} , as well as for the input and output signals. We choose $C1 = 100\text{ nF}$ and $C2 = C3 = 100\text{ }\mu\text{F}$.

$R2$, $R3$ are such that the current through them must be greater than 100 times the bias current. Therefore, we set $R2 = R3 = 4.7\text{ k}\Omega$

C_{in} , as C_{out} , is chosen to filter the DC signal by the low-pass filters ($R1, C_{in}$ and R_{out}, C_{out}). By taking $R1 = 10\text{ k}\Omega$, $R_L = 150\text{ }\Omega$ and $C_{in} = 2\text{ }\mu\text{F}$, $C_{out} = 220\text{ }\mu\text{F}$ we provide a cut-off frequency below 10 Hz .

Figure 50. Use of the TSH7x in gain = -1 configuration



Some precautions must be taken, especially for low-power supply applications.

A feedback capacitance, C_f , should be added for better stability. [Table 11](#) summarizes the impact of the capacitance C_f on the phase margin of the circuit.

Table 11. Impact capacitance C_f

Parameter	C_f (pF)	$V_{CC} = \pm 1.5 \text{ V}$	$V_{CC} = \pm 2.5 \text{ V}$	$V_{CC} = \pm 5 \text{ V}$	Unit
Phase margin	0	28	43	56	deg
f-3 dB		40	39.3	38.3	MHz
Phase margin	5.6	30	43	56	deg
f-3 dB		40	39.3	38.3	MHz
Phase margin	22	37	52	67	deg
f-3 dB		37	34	32	MHz
Phase margin	33	48	65	78	deg
f-3 dB		33.7	30.7	27.6	MHz

5 Package information

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK[®] packages, depending on their level of environmental compliance. ECOPACK[®] specifications, grade definitions and product status are available at: www.st.com. ECOPACK[®] is an ST trademark.

5.1 SOT23-5 package information

Figure 51. SOT23-5 package mechanical drawing

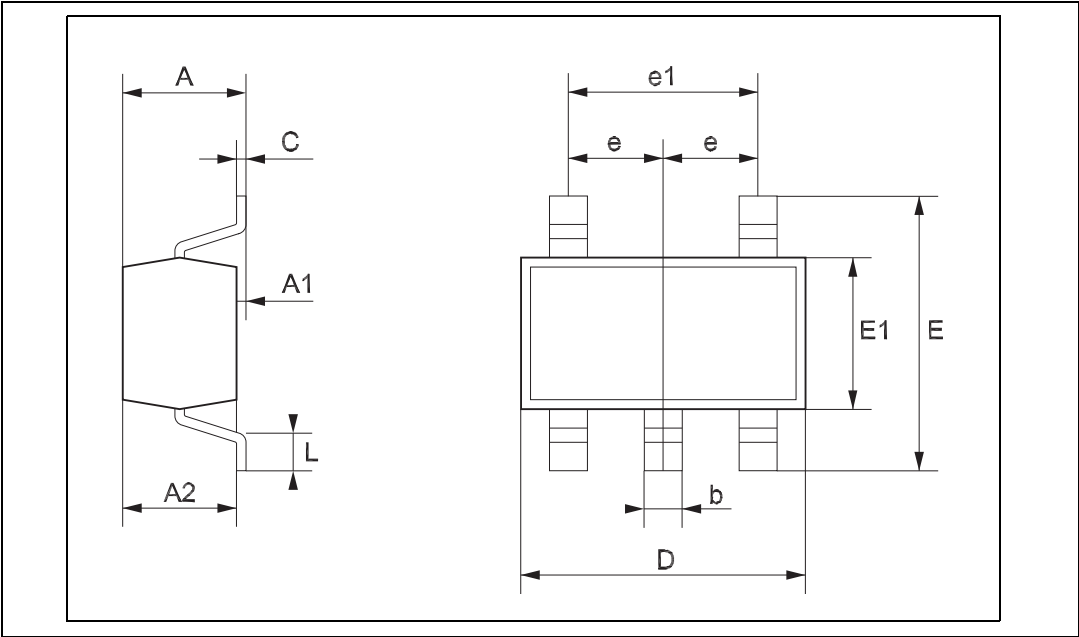


Table 12. SOT23-5 package mechanical data

Symbol	Dimensions					
	Millimeters			Inches		
	Min	Typ	Max	Min	Typ	Max
A	0.90		1.45	0.035		0.057
A1	0.00		0.15	0.000		0.006
A2	0.90		1.30	0.035		0.051
b	0.35		0.50	0.014		0.020
C	0.09		0.20	0.004		0.008
D	2.80		3.00	0.110		0.118
E	2.60		3.00	0.102		0.118
E1	1.50		1.75	0.059		0.069
e		0.95			0.037	
e1		1.9			0.075	
L	0.35		0.55	0.014		0.022

5.2 SO8 package information

Figure 52. SO8 package mechanical drawing

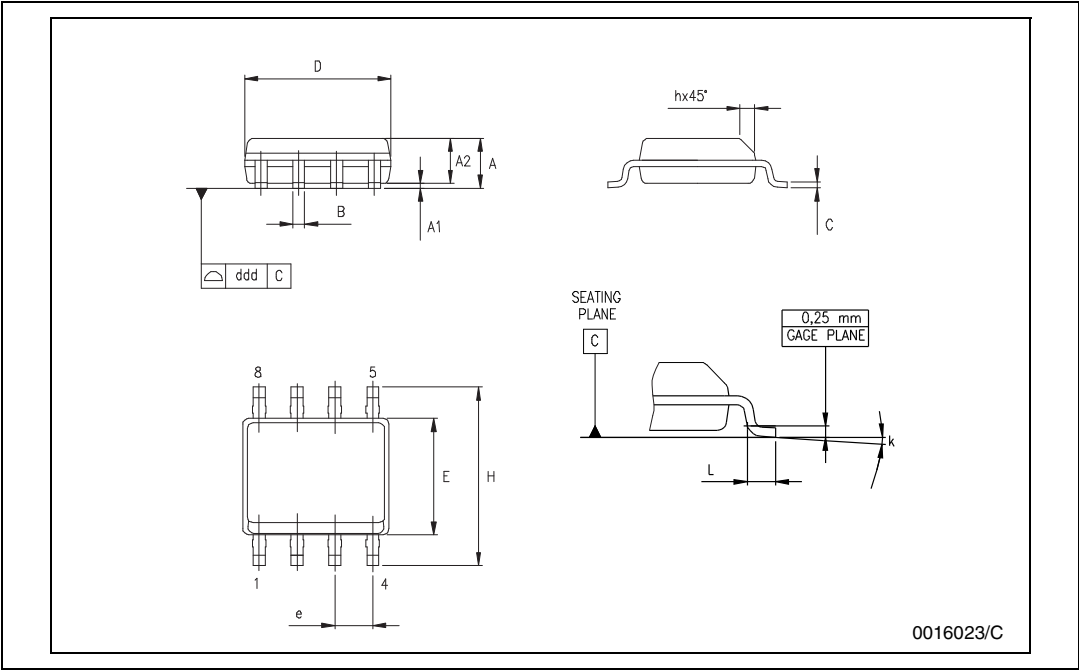


Table 13. SO8 package mechanical data

Symbol	Dimensions					
	Millimeters			Inches		
	Min	Typ	Max	Min	Typ	Max
A	1.35		1.75	0.053		0.069
A1	0.10		0.25	0.004		0.010
A2	1.10		1.65	0.043		0.065
B	0.33		0.51	0.013		0.020
C	0.19		0.25	0.007		0.010
D	4.80		5.00	0.189		0.197
E	3.80		4.00	0.150		0.157
e		1.27			0.050	
H	5.80		6.20	0.228		0.244
h	0.25		0.50	0.010		0.020
L	0.40		1.27	0.016		0.050
k			8 °			8 °
ddd			0.1			0.004

5.3 TSSOP8 package information

Figure 53. TSSOP8 package mechanical drawing

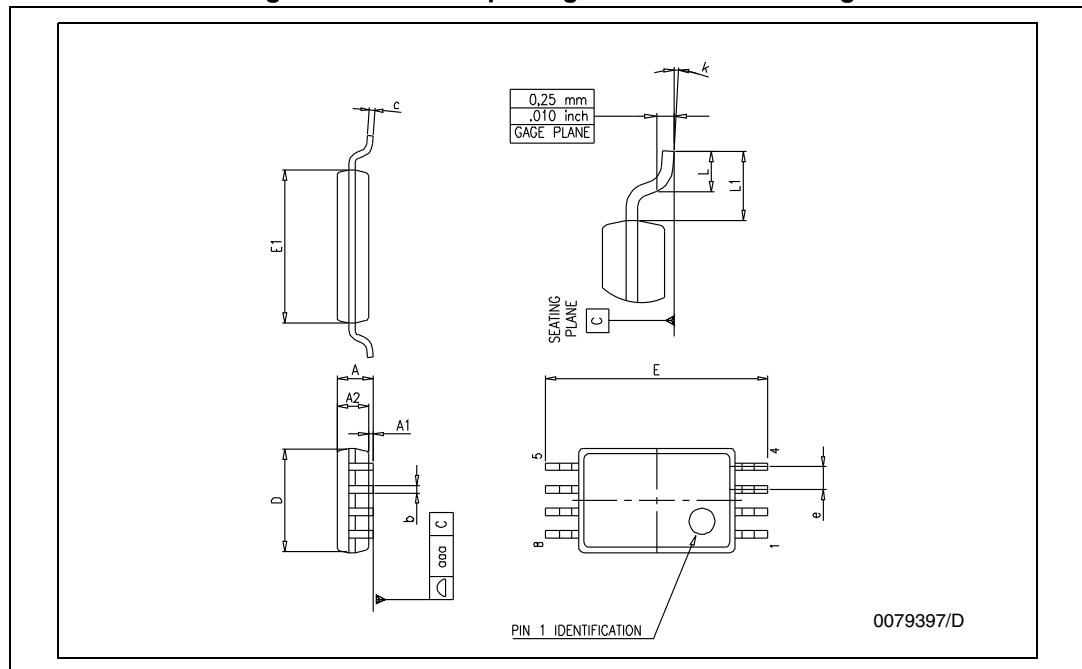


Table 14. TSSOP8 package mechanical data

Symbol	Dimensions					
	Millimeters			Inches		
	Min	Typ	Max	Min	Typ	Max
A			1.2			0.047
A1	0.05		0.15	0.002		0.006
A2	0.80	1.00	1.05	0.031	0.039	0.041
b	0.19		0.30	0.007		0.012
c	0.09		0.20	0.004		0.008
D	2.90	3.00	3.10	0.114	0.118	0.122
E	6.20	6.40	6.60	0.244	0.252	0.260
E1	4.30	4.40	4.50	0.169	0.173	0.177
e		0.65			0.0256	
K	0 °		8 °	0 °		8 °
L	0.45	0.60	0.75	0.018	0.024	0.030
L1		1			0.039	

5.4 SO14 package information

Figure 54. SO14 package mechanical drawing

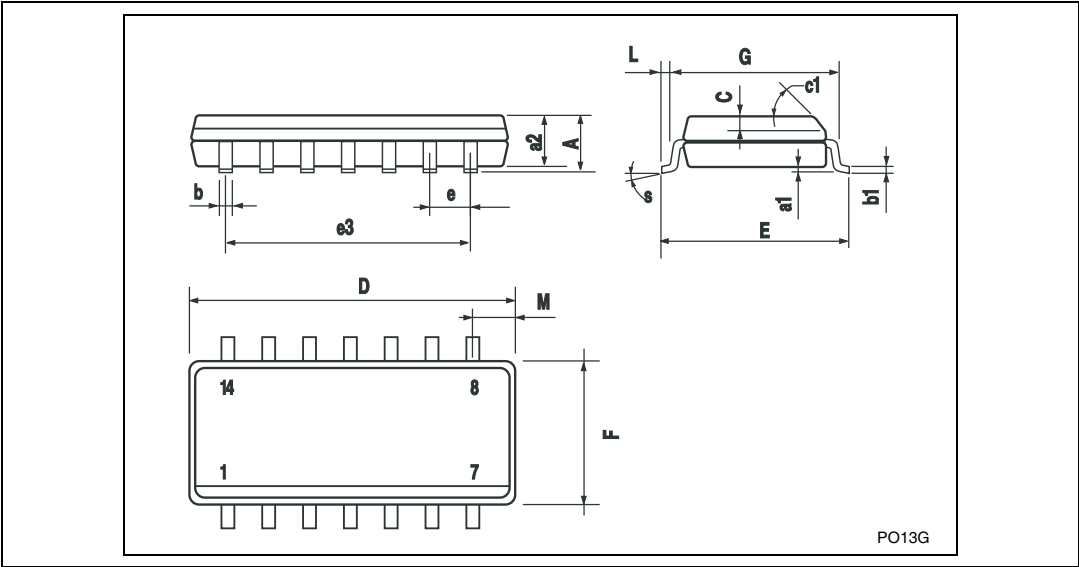


Table 15. SO14 package mechanical data

Symbol	Dimensions					
	Millimeters			Inches		
	Min	Typ	Max	Min	Typ	Max
A			1.75			0.068
a1	0.1		0.2	0.003		0.007
a2			1.65			0.064
b	0.35		0.46	0.013		0.018
b1	0.19		0.25	0.007		0.010
C		0.5			0.019	
c1		45 °			45 °	
D	8.55		8.75	0.336		0.344
E	5.8		6.2	0.228		0.244
e		1.27			0.050	
e3		7.62			0.300	
F	3.8		4.0	0.149		0.157
G	4.6		5.3	0.181		0.208
L	0.5		1.27	0.019		0.050
M			0.68			0.026
S			8 °			8 °

5.5 TSSOP14 package information

Figure 55. TSSOP14 package mechanical drawing

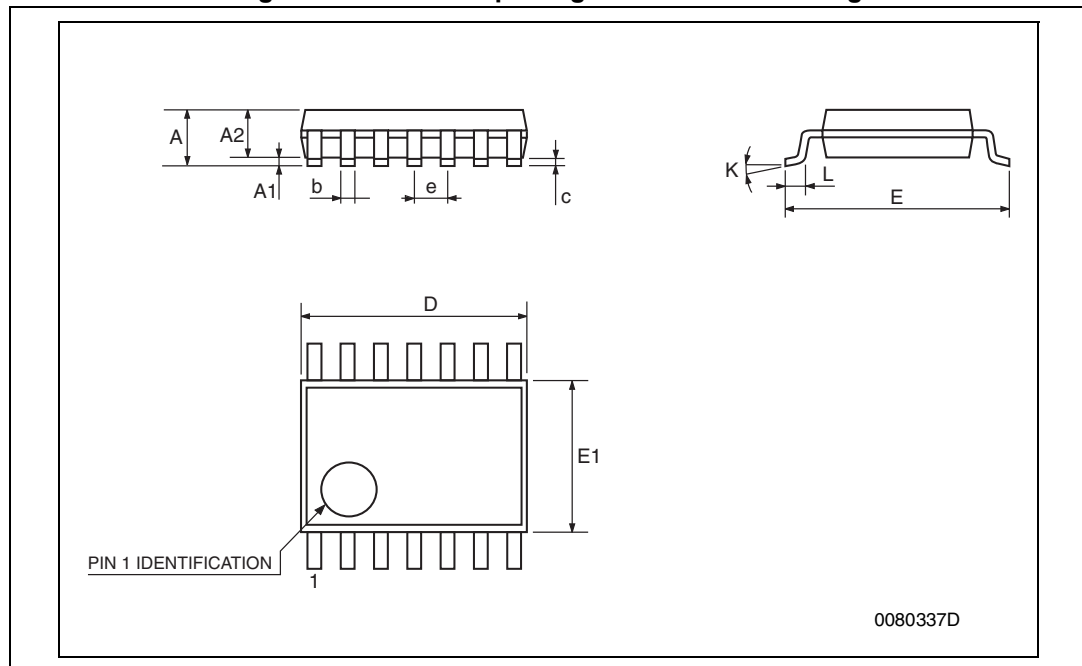


Table 16. TSSOP14 package mechanical data

Symbol	Dimensions					
	Millimeters			Inches		
	Min	Typ	Max	Min	Typ	Max
A			1.2			0.047
A1	0.05		0.15	0.002	0.004	0.006
A2	0.8	1	1.05	0.031	0.039	0.041
b	0.19		0.30	0.007		0.012
c	0.09		0.20	0.004		0.0089
D	4.9	5	5.1	0.193	0.197	0.201
E	6.2	6.4	6.6	0.244	0.252	0.260
E1	4.3	4.4	4.48	0.169	0.173	0.176
e		0.65			0.0256	
K	0 °		8 °	0 °		8 °
L	0.45	0.60	0.75	0.018	0.024	0.030

5.6 SO16 package information

Figure 56. SO16 package mechanical drawing

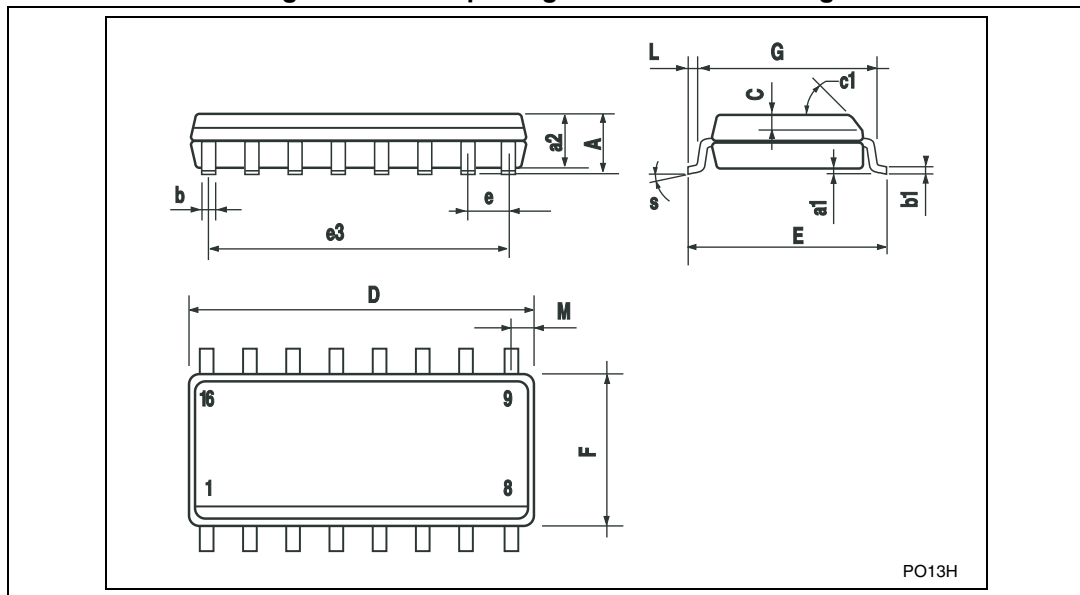


Table 17. SO16 package mechanical data

Symbol	Dimensions					
	Millimeters			Inches		
	Min	Typ	Max	Min	Typ	Max
A			1.75			0.068
a1	0.1		0.2	0.004		0.008
a2			1.65			0.064
b	0.35		0.46	0.013		0.018
b1	0.19		0.25	0.007		0.010
C		0.5			0.019	
c1		45 °			45 °	
D	9.8			0.385		0.393
E	5.8		10	0.228		0.244
e		1.27	6.2		0.050	
e3		8.89			0.350	
F	3.8		4.0	0.149		0.157
G	4.6		5.3	0.181		0.208
L	0.5		1.27	0.019		0.050
M			0.62			0.024
S			8 °			8 °

5.7 TSSOP16 package information

Figure 57. TSSOP16 package mechanical drawing

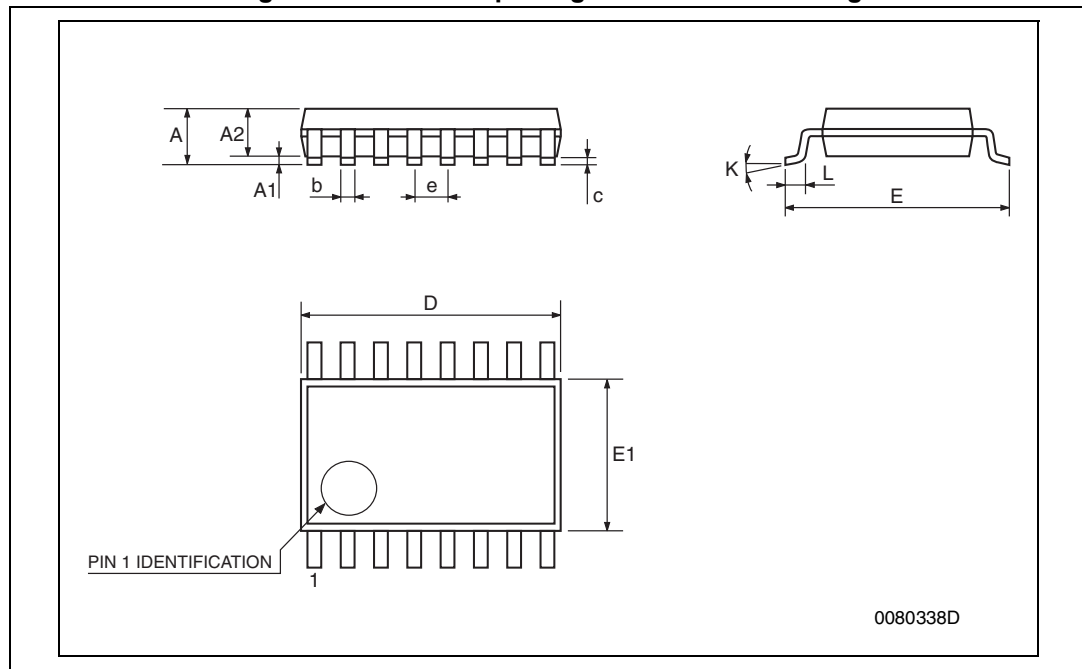


Table 18. TSSOP16 package mechanical data

Symbol	Dimensions					
	Millimeters			Inches		
	Min	Typ	Max	Min	Typ	Max
A			1.2			0.047
A1	0.05		0.15	0.002		0.006
A2	0.8	1	1.05	0.031	0.039	0.041
b	0.19		0.30	0.007		0.012
c	0.09		0.20	0.004		0.0079
D	4.9	5	5.1	0.193	0.197	0.201
E	6.2	6.4	6.6	0.244	0.252	0.260
E1	4.3	4.4	4.48	0.169	0.173	0.176
e		0.65			0.0256	
K	0 °		8 °	0 °		8 °
L	0.45	0.60	0.75	0.018	0.024	0.030

6 Order information

Table 19. Order codes

Part number	Temperature range	Package	Packing	Marking
TSH70CLT	0 °C to 70 °C	SOT23-5	Tape and reel	K301
TSH70CD/CDT		SO8	Tube or tape and reel	70C
TSH71CD/CDT				71C
TSH71CPT		TSSOP8	Tape and reel	72C
TSH72CD/CDT		SO8	Tube or tape and reel	
TSH72CPT		TSSOP8	Tape and reel	73C
TSH73CD/CDT		SO14	Tube or tape and reel	
TSH73CPT		TSSOP14	Tape and reel	74C
TSH74CD/CDT		SO14	Tube or tape and reel	
TSH74CPT		TSSOP14	Tape and reel	75C
TSH75CD/CDT		SO16	Tube or tape and reel	
TSH75CPT		TSSOP16	Tape and reel	

7 Revision history

Table 20. Document revision history

Date	Revision	Changes
Nov. 2000	1	First Release.
Aug. 2002	2	Limit min. of I_{sink} from 24mA to 20mA (only on 3V power supply). Reason: yield improvement.
May 2006	3	Improvement of VOL max. at 3V and 5V power supply on 150-ohm load connected to GND (pages 6 and 8). Reason: TSH7x can drive video signals from DACs to lines in single supply (3V or 5V) without any DC level change of the video signals. Grammatical and typographical changes throughout. Package mechanical data updated.
05-Dec-2013	4	Updated slew rate in Features Table 12: SOT23-5 package mechanical data : added information for inches.

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