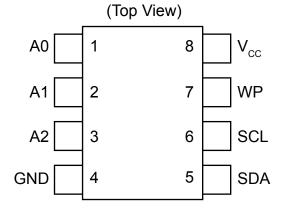
# **Table of Contents**

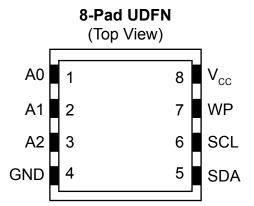
Fe	atures.		1					
Pa	ckages	S	1					
1.	Pack	rage Types (not to scale)	4					
2.	Pin Descriptions							
	2.1.	Device Address Inputs (A0, A1, A2)						
	2.2.	Ground						
	2.3.	Serial Data (SDA)						
	2.4.	Serial Clock (SCL)						
	2.5.	Write-Protect (WP)						
	2.6.	Device Power Supply						
3.	Desc	cription	7					
	3.1.	System Configuration Using Two-Wire Serial EEPROMs	7					
	3.2.	Block Diagram	8					
4.	Electrical Characteristics							
	4.1.	Absolute Maximum Ratings	9					
	4.2.	DC and AC Operating Range	9					
	4.3.	DC Characteristics	g					
	4.4.	AC Characteristics	10					
	4.5.	Electrical Specifications	11					
5.	Device Operation and Communication							
	5.1.	Clock and Data Transition Requirements						
	5.2.	Start and Stop Conditions						
	5.3.	Acknowledge and No-Acknowledge						
	5.4.	Standby Mode						
	5.5.	Software Reset	14					
6.	Mem	ory Organization						
	6.1.	Device Addressing	16					
7.	Write	Operations	17					
	7.1.	Byte Write	17					
	7.2.	Page Write	17					
	7.3.	Acknowledge Polling	18					
	7.4.	Write Cycle Timing						
	7.5.	Write Protection	19					
8.	Read	d Operations						
	8.1.	Current Address Read						
	8.2.	Random Read						
	8.3.	Sequential Read	21					
9.	Devi	ce Default Condition from Microchip	22					

10. Packaging Information	23
10.1. Package Marking Information	23
11. Revision History	38
The Microchip Website	39
Product Change Notification Service	39
Customer Support	39
Product Identification System	40
Microchip Devices Code Protection Feature	40
Legal Notice	41
Trademarks	41
Quality Management System	42
Worldwide Sales and Service	43

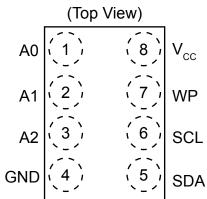
# 1. Package Types (not to scale)

# 8-Lead SOIC/SOIJ/TSSOP

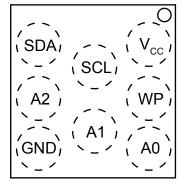




8-Ball VFBGA



8-Ball WLCSP (Top View)



## 2. Pin Descriptions

The descriptions of the pins are listed in Table 2-1.

Table 2-1. Pin Function Table

Name	8-Lead SOIC	8-Lead SOIJ	8-Lead TSSOP	8-Pad UDFN <sup>(1)</sup>	8-Ball VFBGA	8-Ball WLCSP	Function
A0 <sup>(2)</sup>	1	1	1	1	1	A5	Device Address Input
A1 <sup>(2)</sup>	2	2	2	2	2	B4	Device Address Input
A2 <sup>(2)</sup>	3	3	3	3	3	C3	Device Address Input
GND	4	4	4	4	4	C5	Ground
SDA	5	5	5	5	5	C1	Serial Data
SCL	6	6	6	6	6	B2	Serial Clock
WP <sup>(2)</sup>	7	7	7	7	7	A3	Write-Protect
V <sub>CC</sub>	8	8	8	8	8	A1	Device Power Supply

#### Notes:

- 1. The exposed pad on this package can be connected to GND or left floating.
- 2. If the A0, A1, A2 or WP pins are not driven, they are internally pulled down to GND. In order to operate in a wide variety of application environments, the pull-down mechanism is intentionally designed to be somewhat strong. Once these pins are biased above the CMOS input buffer's trip point (~0.5 x V<sub>CC</sub>), the pull-down mechanism disengages. Microchip recommends connecting these pins to a known state whenever possible.

## 2.1 Device Address Inputs (A0, A1, A2)

The A0, A1 and A2 pins are device address inputs that are hard-wired (directly to GND or to  $V_{CC}$ ) for compatibility with other two-wire Serial EEPROM devices. When the pins are hard-wired, as many as eight devices may be addressed on a single bus system. A device is selected when a corresponding hardware and software match is true. If these pins are left floating, the A0, A1 and A2 pins will be internally pulled down to GND. However, due to capacitive coupling that may appear in customer applications, Microchip recommends always connecting the address pins to a known state. When using a pull-up resistor, Microchip recommends using 10 k $\Omega$  or less.

### 2.2 Ground

The ground reference for the power supply. GND should be connected to the system ground.

### 2.3 Serial Data (SDA)

The SDA pin is an open-drain bidirectional input/output pin used to serially transfer data to and from the device. The SDA pin must be pulled high using an external pull-up resistor (not to exceed 10 k $\Omega$  in value) and may be wire-ORed with any number of other open-drain or open-collector pins from other devices on the same bus.

## 2.4 Serial Clock (SCL)

The SCL pin is used to provide a clock to the device and to control the flow of data to and from the device. Command and input data present on the SDA pin is always latched in on the rising edge of SCL, while output data on the SDA pin is clocked out on the falling edge of SCL. The SCL pin must either be forced high when the serial bus is idle or pulled high using an external pull-up resistor.

## 2.5 Write-Protect (WP)

The write-protect input, when connected to GND, allows normal write operations. When the WP pin is connected directly to  $V_{CC}$ , all write operations to the protected memory are inhibited.

If the pin is left floating, the WP pin will be internally pulled down to GND. However, due to capacitive coupling that may appear in customer applications, Microchip recommends always connecting the WP pin to a known state. When using a pull-up resistor, Microchip recommends using 10 k $\Omega$  or less.

Table 2-2. Write-Protect

WP Pin Status	Part of the Array Protected				
At V <sub>CC</sub>	Full Array				
At GND	Normal Write Operations				

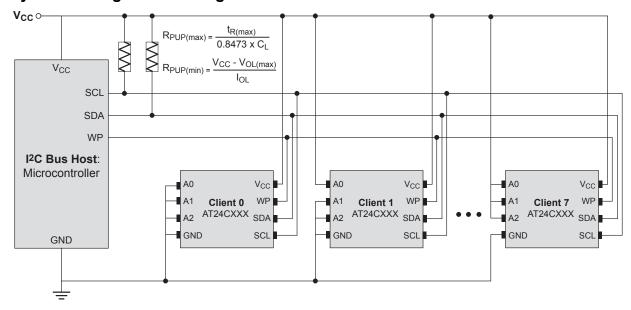
## 2.6 Device Power Supply

The  $V_{CC}$  pin is used to supply the source voltage to the device. Operations at invalid  $V_{CC}$  voltages may produce spurious results and should not be attempted.

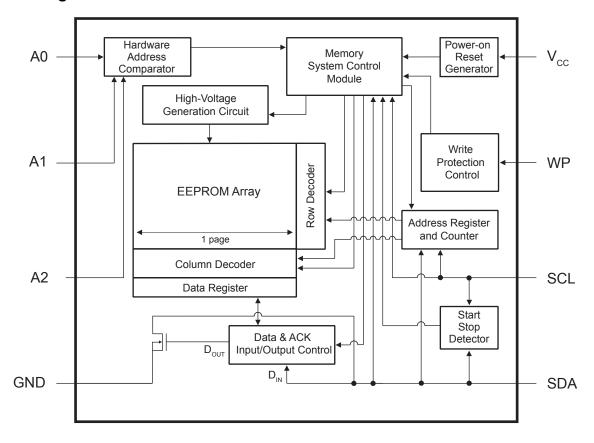
# 3. Description

The AT24C512C provides 524,288 bits of Serial Electrically Erasable and Programmable Read-Only Memory (EEPROM) organized as 65,536 words of 8 bits each. The device's cascading feature allows up to eight devices to share a common two-wire bus. The device is optimized for use in many industrial and commercial applications where low-power and low-voltage operation are essential. The devices are available in space-saving 8-lead SOIC, 8-lead SOIJ, 8-lead TSSOP, 8-pad UDFN, 8-ball WLCSP and 8-ball VFBGA packages. All packages operate from 1.7V to 3.6V or 2.5V to 5.5V.

## 3.1 System Configuration Using Two-Wire Serial EEPROMs



# 3.2 Block Diagram



## 4. Electrical Characteristics

## 4.1 Absolute Maximum Ratings

Temperature under bias -55°C to +125°C
Storage temperature -65°C to +150°C

**V<sub>CC</sub>** 6.25V

Voltage on any pin with respect to ground -1.0V to +7.0V

DC output current 5.0 mA
ESD protection ≥4 kV

**Note:** Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## 4.2 DC and AC Operating Range

Table 4-1. DC and AC Operating Range

AT24C512C		
Operating Temperature (Case)	Industrial Temperature Range	-40°C to +85°C
V Power Supply	Low-Voltage Grade	1.7V to 3.6V
V <sub>CC</sub> Power Supply	Standard-Voltage Grade	2.5V to 5.5V

### 4.3 DC Characteristics

Table 4-2. DC Characteristics

Parameter	Symbol	Minimum	Typical <sup>(1)</sup>	Maximum	Units	Test Conditions
Supply Voltage	V <sub>CC1</sub>	1.7	_	3.6	V	
Supply Voltage	V <sub>CC2</sub>	2.5	_	5.5	V	
	1	_	_	1.0	mA	V <sub>CC</sub> = 3.6V, Read at 400 kHz
Supply Current	I <sub>CC1</sub>	_	_	3.0	mA	V <sub>CC</sub> = 3.6V, Write at 400 kHz
Supply Current	I <sub>CC2</sub>	_	_	2.0	mA	V <sub>CC</sub> = 5.0V, Read at 400 kHz
		_	_	3.0	mA	V <sub>CC</sub> = 5.0V, Write at 400 kHz
	I <sub>SB1</sub>	_	_	1.0	μA	$V_{CC}$ = 1.7V, $V_{IN}$ = $V_{CC}$ or GND
Standby Current		_	_	3.0	μA	$V_{CC}$ = 3.6V, $V_{IN}$ = $V_{CC}$ or GND
Standby Current	1.	_	_	2.0	μA	$V_{CC}$ = 2.5V, $V_{IN}$ = $V_{CC}$ or $V_{SS}$
	I <sub>SB2</sub>	_	_	6.0	μA	$V_{CC}$ = 5.5V, $V_{IN}$ = $V_{CC}$ or $V_{SS}$
Input Leakage Current	ILI	_	0.10	3.0	μA	$V_{IN} = V_{CC}$ or GND; $V_{CC} = 5.0V$

continued						
Parameter	Symbol	Minimum	Typical <sup>(1)</sup>	Maximum	Units	Test Conditions
Output Leakage Current	I <sub>LO</sub>	_	0.05	3.0	μΑ	V <sub>OUT</sub> = V <sub>CC</sub> or GND; V <sub>CC</sub> = 5.0V
Input Low Level	V <sub>IL</sub>	-0.6	_	V <sub>CC</sub> x 0.3	V	Note 2
Input High Level	V <sub>IH</sub>	V <sub>CC</sub> x 0.7	_	V <sub>CC</sub> + 0.5	V	Note 2
Output Low Level	V <sub>OL1</sub>	_	_	0.2	V	V <sub>CC</sub> = 1.7V, I <sub>OL</sub> = 0.15 mA
Output Low Level	V <sub>OL2</sub>	_	_	0.4	V	V <sub>CC</sub> = 3.0V, I <sub>OL</sub> = 2.1 mA

#### Note:

- 1. Typical values characterized at  $T_A$  = +25°C unless otherwise noted.
- 2. This parameter is characterized but is not 100% tested in production.

## 4.4 AC Characteristics

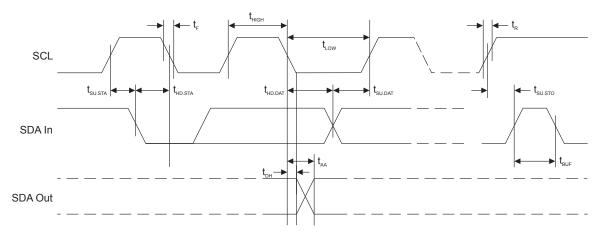
Table 4-3. AC Characteristics<sup>(1)</sup>

		Fast	Mode	Fast Mo		
Parameter	Symbol	V <sub>CC</sub> = 1.7	V to 2.5V	V <sub>CC</sub> = 2.5	Units	
		Min.	Max.	Min.	Max.	
Clock Frequency, SCL	f <sub>SCL</sub>	_	400	_	1000	kHz
Clock Pulse Width Low	t <sub>LOW</sub>	1300	_	500	_	ns
Clock Pulse Width High	t <sub>HIGH</sub>	600	_	400	_	ns
Noise Suppression Time <sup>(2)</sup>	t <sub>l</sub>		50	_	50	ns
Clock Low to Data Out Valid	t <sub>AA</sub>	50	900	50	450	ns
Bus Free Time between Stop and Start <sup>(2)</sup>	t <sub>BUF</sub>	1300	_	500	_	ns
Start Hold Time	t <sub>HD.STA</sub>	600		250		ns
Start Set-up Time	t <sub>SU.STA</sub>	600		250		ns
Data In Hold Time	t <sub>HD.DAT</sub>	0	_	0	_	ns
Data In Set-up Time	t <sub>SU.DAT</sub>	100		100		ns
Inputs Rise Time <sup>(2)</sup>	t <sub>R</sub>	_	300	_	300	ns
Inputs Fall Time <sup>(2)</sup>	t <sub>F</sub>	_	300	_	100	ns
Stop Set-up Time	t <sub>su.sto</sub>	600	_	250	_	ns
Data Out Hold Time	t <sub>DH</sub>	50	_	50	_	ns
Write Cycle Time	t <sub>WR</sub>	_	5	_	5	ms

#### Notes:

- AC measurement conditions:
  - $C_1 = 100 pF$
  - R<sub>PUP</sub> (SDA bus line pull-up resistor to V<sub>CC</sub>): 1.3 kΩ (1000 kHz), 4 kΩ (400 kHz), 10 kΩ (100 kHz)
  - Input pulse voltages: 0.3 V<sub>CC</sub> to 0.7 V<sub>CC</sub>
  - Input rise and fall times: ≤ 50 ns
  - Input and output timing reference voltages: 0.5 x V<sub>CC</sub>
- 2. This parameter is ensured by characterization and is not 100% tested.

Figure 4-1. Bus Timing



## 4.5 Electrical Specifications

#### 4.5.1 Power-Up Requirements and Reset Behavior

During a power-up sequence, the  $V_{CC}$  supplied to the AT24C512C should monotonically rise from GND to the minimum  $V_{CC}$  level, as specified in Table 4-1, with a slew rate no faster than 0.1 V/µs.

#### 4.5.1.1 Device Reset

To prevent inadvertent write operations or any other spurious events from occurring during a power-up sequence, the AT24C512C includes a Power-on Reset (POR) circuit. Upon power-up, the device will not respond to any commands until the  $V_{CC}$  level crosses the internal voltage threshold ( $V_{POR}$ ) that brings the device out of Reset and into Standby mode.

The system designer must ensure the instructions are not sent to the device until the  $V_{CC}$  supply has reached a stable value greater than or equal to the minimum  $V_{CC}$  level. Additionally, once the  $V_{CC}$  is greater than or equal to the minimum  $V_{CC}$  level, the bus host must wait at least  $t_{PUP}$  before sending the first command to the device. See Table 4-4 for the values associated with these power-up parameters.

Table 4-4. Power-Up Conditions<sup>(1)</sup>

Symbol	Parameter	Min.	Max.	Units
t <sub>PUP</sub>	Time required after V <sub>CC</sub> is stable before the device can accept commands	100	_	μs
V <sub>POR</sub>	Power-on Reset Threshold Voltage	_	1.5	V
t <sub>POFF</sub>	Minimum time at V <sub>CC</sub> = 0V between power cycles	500	_	ms

#### Note:

1. These parameters are characterized but they are not 100% tested in production.

If an event occurs in the system where the  $V_{CC}$  level supplied to the AT24C512C drops below the maximum  $V_{POR}$  level specified, it is recommended that a full-power cycle sequence be performed by first driving the  $V_{CC}$  pin to

GND, waiting at least the minimum  $t_{POFF}$  time and then performing a new power-up sequence in compliance with the requirements defined in this section.

#### 4.5.2 Pin Capacitance

## Table 4-5. Pin Capacitance<sup>(1)</sup>

Symbol	Test Condition	Max.	Units	Conditions
C <sub>I/O</sub>	Input/Output Capacitance (SDA)	8	pF	V <sub>I/O</sub> = 0V
C <sub>IN</sub>	Input Capacitance (A0, A1, A2 and SCL)	6	pF	V <sub>IN</sub> = 0V

#### Note:

1. This parameter is characterized but is not 100% tested in production.

#### 4.5.3 EEPROM Cell Performance Characteristics

#### Table 4-6. EEPROM Cell Performance Characteristics

Operation	Test Condition	Min.	Max.	Units	
Write Endurance <sup>(1, 2)</sup>	$T_A = 25^{\circ}C, V_{CC} = 3.3V$	1,000,000	_	Write Cycles	
Data Retention <sup>(1)</sup>	T <sub>A</sub> = 55°C	100		Years	

#### Notes:

- 1. Performance is determined through characterization and the qualification process.
- 2. Due to the memory array architecture, the Write Cycle Endurance is specified for writes in groups of four data bytes. The beginning of any 4-byte boundaries can be determined by multiplying any integer (N) by four (i.e., 4\*N). The end address can be found by adding three to the beginning value (i.e., 4\*N+3).

Datasheet

## 5. Device Operation and Communication

The AT24C512C operates as a client device and utilizes a simple I<sup>2</sup>C-compatible two-wire digital serial interface to communicate with a host controller, commonly referred to as the bus host. The host initiates and controls all read and write operations to the client devices on the serial bus, and both the host and the client devices can transmit and receive data on the bus.

The serial interface is comprised of just two signal lines: Serial Clock (SCL) and Serial Data (SDA). The SCL pin is used to receive the clock signal from the host, while the bidirectional SDA pin is used to receive command and data information from the host as well as to send data back to the host. Data is always latched into the AT24C512C on the rising edge of SCL and always output from the device on the falling edge of SCL. Both the SCL and SDA pins incorporate integrated spike suppression filters and Schmitt Triggers to minimize the effects of input spikes and bus noise.

All command and data information is transferred with the Most Significant bit (MSb) first. During bus communication, one data bit is transmitted every clock cycle, and after eight bits (one byte) of data have been transferred, the receiving device must respond with either an Acknowledge (ACK) or a No-Acknowledge (NACK) response bit during a ninth clock cycle (ACK/NACK clock cycle) generated by the host. Therefore, nine clock cycles are required for every one byte of data transferred. There are no unused clock cycles during any read or write operation, so there must not be any interruptions or breaks in the data stream during each data byte transfer and ACK or NACK clock cycle.

During data transfers, data on the SDA pin must only change while SCL is low and the data must remain stable while SCL is high. If data on the SDA pin changes while SCL is high, then either a Start or a Stop condition will occur. Start and Stop conditions are used to initiate and end all serial bus communication between the host and the client devices. The number of data bytes transferred between a Start and a Stop condition is not limited and is determined by the host. In order for the serial bus to be idle, both the SCL and SDA pins must be in the logic high state at the same time.

## 5.1 Clock and Data Transition Requirements

The SDA pin is an open-drain terminal and therefore must be pulled high with an external pull-up resistor. SCL is an input pin that can either be driven high or pulled high using an external pull-up resistor. Data on the SDA pin may change only during SCL low time periods. Data changes during SCL high periods will indicate a Start or Stop condition as defined below. The relationship of the AC timing parameters with respect to SCL and SDA for the AT24C512C are shown in the timing waveform in Figure 4-1. The AC timing characteristics and specifications are outlined in AC Characteristics.

### 5.2 Start and Stop Conditions

#### 5.2.1 Start Condition

A Start condition occurs when there is a high-to-low transition on the SDA pin while the SCL pin is at a stable logic '1' state and will bring the device out of Standby mode. The host uses a Start condition to initiate any data transfer sequence; therefore, every command must begin with a Start condition. The device will continuously monitor the SDA and SCL pins for a Start condition but will not respond unless one is detected. Refer to Figure 5-1 for more details.

#### 5.2.2 Stop Condition

A Stop condition occurs when there is a low-to-high transition on the SDA pin while the SCL pin is stable in the logic '1' state.

The host can use the Stop condition to end a data transfer sequence with the AT24C512C, which will subsequently return to Standby mode. The host can also utilize a repeated Start condition instead of a Stop condition to end the current data transfer if the host will perform another operation. Refer to Figure 5-1 for more details.

## 5.3 Acknowledge and No-Acknowledge

After every byte of data is received, the receiving device must confirm to the transmitting device that it has successfully received the data byte by responding with what is known as an Acknowledge (ACK). An ACK is accomplished by the transmitting device first releasing the SDA line at the falling edge of the eighth clock cycle, followed by the receiving device responding with a logic '0' during the entire high period of the ninth clock cycle.

When the AT24C512C is transmitting data to the host, the host can indicate that it is done receiving data and wants to end the operation by sending a logic '1' response to the AT24C512C instead of an ACK response during the ninth clock cycle. This is known as a No-Acknowledge (NACK) and is accomplished by the host sending a logic '1' during the ninth clock cycle, at which point the AT24C512C will release the SDA line so the host can then generate a Stop condition.

The transmitting device, which can be the bus host or the Serial EEPROM, must release the SDA line at the falling edge of the eighth clock cycle to allow the receiving device to drive the SDA line to a logic '0' to ACK the previous 8-bit word. The receiving device must release the SDA line at the end of the ninth clock cycle to allow the transmitter to continue sending new data. A timing diagram has been provided in Figure 5-1 to better illustrate these requirements.

SDA SDA Must Be Must Be Acknowledge Window Stable Stable 2 SCL SDA Stop Acknowledge Condition Start Valid Condition The transmitting device (Host or Client) The receiver (Host or Client) SDA SDA must release the SDA line at this point to allow must release the SDA line at Change Change the receiving device (Host or Client) to drive the this point to allow the transmitter Allowed Allowed SDA line low to ACK the previous 8-bit word. to continue sending new data

Figure 5-1. Start Condition, Data Transitions, Stop Condition and Acknowledge

## 5.4 Standby Mode

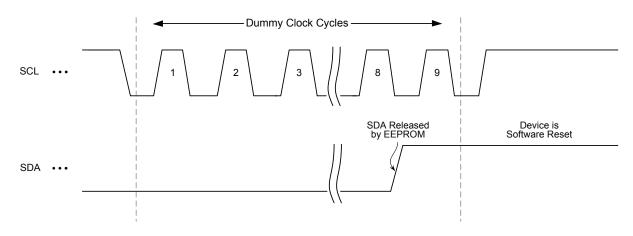
The AT24C512C features a low-power Standby mode that is enabled when any one of the following occurs:

- A valid power-up sequence is performed (see Power-Up Requirements and Reset Behavior).
- · A Stop condition is received by the device unless it initiates an internal write cycle (see Write Operations).
- · At the completion of an internal write cycle (see Write Operations).

#### 5.5 Software Reset

After an interruption in protocol, power loss or system Reset, any two-wire device can be protocol reset by clocking SCL until SDA is released by the EEPROM and goes high. The number of clock cycles until SDA is released by the EEPROM will vary. The software Reset sequence should not take more than nine dummy clock cycles. Once the software Reset sequence is complete, new protocol can be sent to the device by sending a Start condition followed by the protocol. Refer to Figure 5-2 for an illustration.

Figure 5-2. Software Reset



In the event that the device is still non-responsive or remains active on the SDA bus, a power cycle must be used to reset the device (see Power-Up Requirements and Reset Behavior).

## 6. Memory Organization

The AT24C512C is internally organized as 512 pages of 128 bytes each.

## 6.1 Device Addressing

Accessing the device requires an 8-bit device address byte following a Start condition to enable the device for a read or write operation. Since multiple client devices can reside on the serial bus, each client device must have its own unique address so the host can access each device independently.

The Most Significant four bits of the device address byte is referred to as the device type identifier. The device type identifier '1010' (Ah) is required in bits 7 through 4 of the device address byte (see Table 6-1).

Following the 4-bit device type identifier are the hardware client address bits, A2, A1 and A0. These bits can be used to expand the address space by allowing up to eight Serial EEPROM devices on the same bus. These hardware client address bits must correlate with the voltage level on the corresponding hardwired device address input pins A0, A1 and A2. The A0, A1 and A2 pins use an internal proprietary circuit that automatically biases the pin to a logic '0' state if the pin is allowed to float. In order to operate in a wide variety of application environments, the pull-down mechanism is intentionally designed to be somewhat strong. Once the pin is biased above the CMOS input buffer's trip point (~0.5 x V<sub>CC</sub>), the pull-down mechanism disengages. Microchip recommends connecting the A0, A1 and A2 pins to a known state whenever possible.

The eighth bit (bit 0) of the device address byte is the Read/Write Select bit. A read operation is initiated if this bit is high and a write operation is initiated if this bit is low.

Upon the successful comparison of the device address byte, the AT24C512C will return an ACK. If a valid comparison is not made, the device will NACK.

Table 6-1. Device Address Byte

Package	Device Type Identifier			Hardware	R/W Select			
rackaye	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
SOIC, SOIJ, TSSOP, UDFN, VFBGA, WLCSP	1	0	1	0	A2	A1	A0	R/W

For all operations except the current address read, two 8-bit word address bytes must be transmitted to the device immediately following the device address byte. The word address bytes consist of the 16-bit memory array word address, and are used to specify which byte location in the EEPROM to start reading or writing.

The first word address byte contains the eight Most Significant bits of the word address (A15 through A8) in bit positions seven through zero, as seen in Table 6-2. Upon completion of the first word address byte, the AT24C512C will return an ACK.

Table 6-2. First Word Address Byte

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
A15	A14	A13	A12	A11	A10	A9	A8

Next, the second word address byte is sent to the device which provides the remaining eight bits of the word address (A7 through A0). Upon completion of the second word address byte, the AT24C512C will return an ACK. See Table 6-3 to review these bit positions.

Table 6-3. Second Word Address Byte

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
A7	A6	A5	A4	A3	A2	A1	A0

## 7. Write Operations

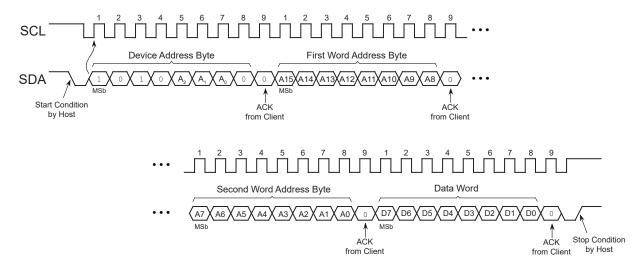
All write operations for the AT24C512C begin with the host sending a Start condition, followed by a device address byte with the R/W bit set to logic '0', and then by the word address bytes. The data value(s) to be written to the device immediately follow the word address bytes.

## 7.1 Byte Write

The AT24C512C supports the writing of a single 8-bit byte. Selecting a data word in the AT24C512C requires a 16-bit word address.

Upon receipt of the proper device address and the word address bytes, the EEPROM will send an Acknowledge. The device will then be ready to receive the 8-bit data word. Following receipt of the 8-bit data word, the EEPROM will respond with an ACK. The addressing device, such as a bus host, must then terminate the write operation with a Stop condition. At that time, the EEPROM will enter an internally self-timed write cycle, which will be completed within  $t_{WR}$ , while the data word is being programmed into the nonvolatile EEPROM. All inputs are disabled during this write cycle and the EEPROM will not respond until the write is complete.

Figure 7-1. Byte Write



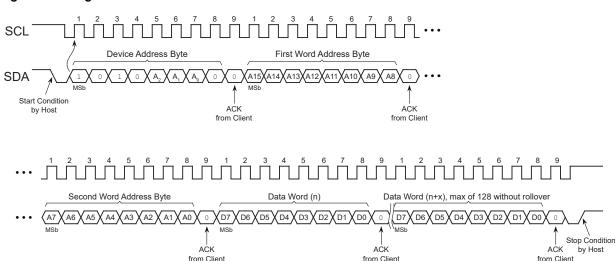
## 7.2 Page Write

A page write operation allows up to 128 bytes to be written in the same write cycle, provided all bytes are in the same row of the memory array (where address bits A15 through A7 are the same). Partial page writes of less than 128 bytes are also allowed.

A page write is initiated the same way as a byte write, but the bus host does not send a Stop condition after the first data word is clocked in. Instead, after the EEPROM acknowledges receipt of the first data word, the bus host can transmit up to 127 additional data words. The EEPROM will respond with an ACK after each data word is received. Once all data to be written has been sent to the device, the bus host must issue a Stop condition (see Figure 7-2) at which time the internally self-timed write cycle will begin.

The lower seven bits of the word address are internally incremented following the receipt of each data word. The higher order address bits are not incremented and retain the memory page row location. Page write operations are limited to writing bytes within a single physical page, regardless of the number of bytes actually being written. When the incremented word address reaches the page boundary, the address counter will rollover to the beginning of the same page. Nevertheless, creating a rollover event should be avoided as previously loaded data in the page could become unintentionally altered.

Figure 7-2. Page Write

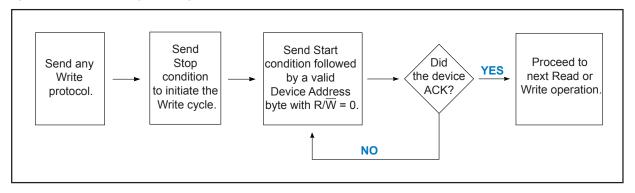


## 7.3 Acknowledge Polling

An Acknowledge Polling routine can be implemented to optimize time-sensitive applications that would prefer not to wait the fixed maximum write cycle time ( $t_{WR}$ ). This method allows the application to know immediately when the Serial EEPROM write cycle has completed, so a subsequent operation can be started.

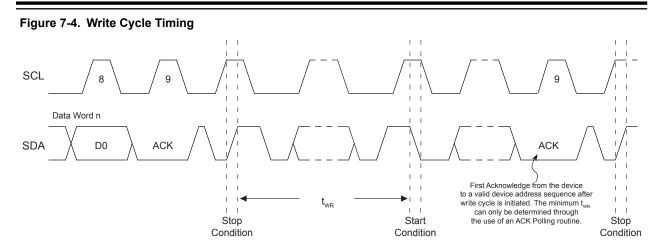
Once the internally self-timed write cycle has started, an Acknowledge Polling routine can be initiated. This involves repeatedly sending a Start condition followed by a valid device address byte with the  $R/\overline{W}$  bit set at logic '0'. The device will not respond with an ACK while the write cycle is ongoing. Once the internal write cycle has completed, the EEPROM will respond with an ACK, allowing a new read or write operation to be immediately initiated. A flowchart has been included below in Figure 7-3 to better illustrate this technique.

Figure 7-3. Acknowledge Polling Flowchart



## 7.4 Write Cycle Timing

The length of the self-timed write cycle (t<sub>WR</sub>) is defined as the amount of time from the Stop condition that begins the internal write cycle to the Start condition of the first device address byte sent to the AT24C512C that it subsequently responds to with an ACK. Figure 7-4 has been included to show this measurement. During the internally self-timed write cycle, any attempts to read from or write to the memory array will not be processed.



### 7.5 Write Protection

The AT24C512C utilizes a hardware data protection scheme that allows the user to write-protect the entire memory contents when the WP pin is at  $V_{CC}$  (or a valid  $V_{IH}$ ). No write protection will be set if the WP pin is at GND or left floating.

Table 7-1. AT24C512C Write-Protect Behavior

WP Pin Voltage	Part of the Array Protected
V <sub>CC</sub>	Full Array
GND	None — Write Protection Not Enabled

The status of the WP pin is sampled at the Stop condition for every byte write or page write operation prior to the start of an internally self-timed write cycle. Changing the WP pin state after the Stop condition has been sent will not alter or interrupt the execution of the write cycle.

If an attempt is made to write to the device while the WP pin has been asserted, the device will acknowledge the device address, word address and data bytes. However, no write cycle will occur when the Stop condition is issued. The device will immediately be ready to accept a new read or write command.

# 8. Read Operations

Read operations are initiated the same way as write operations with the exception that the Read/Write Select bit in the device address byte must be a logic '1'. There are three read operations:

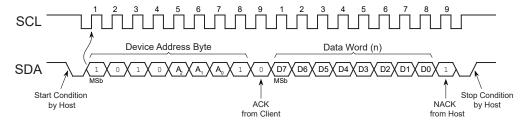
- · Current Address Read
- · Random Address Read
- · Sequential Read

#### 8.1 Current Address Read

The internal data word address counter maintains the last address accessed during the last read or write operation, incremented by one. This address stays valid between operations as long as the  $V_{CC}$  is maintained to the part. The address rollover during a read is from the last byte of the last page to the first byte of the first page of the memory.

A current address read operation will output data according to the location of the internal data word address counter. This is initiated with a Start condition, followed by a valid device address byte with the  $R/\overline{W}$  bit set to logic '1'. The device will ACK this sequence and the current address data word is serially clocked out on the SDA line. All types of read operations will be terminated if the bus host does not respond with an ACK (it NACKs) during the ninth clock cycle. After the NACK response, the host may send a Stop condition to complete the protocol or it can send a Start condition to begin the next sequence.

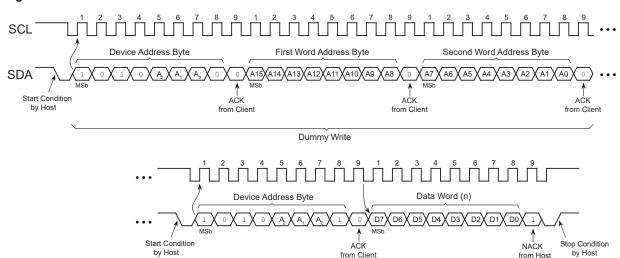
Figure 8-1. Current Address Read



#### 8.2 Random Read

A random read begins in the same way as a byte write operation does to load in a new data word address. This is known as a "dummy write" sequence; however, the data byte and the Stop condition of the byte write must be omitted to prevent the part from entering an internal write cycle. Once the device address and word address are clocked in and acknowledged by the EEPROM, the bus host must generate another Start condition. The bus host now initiates a current address read by sending a Start condition, followed by a valid device address byte with the R/W bit set to logic '1'. The EEPROM will ACK the device address and serially clock out the data word on the SDA line. All types of read operations will be terminated if the bus host does not respond with an ACK (it NACKs) during the ninth clock cycle. After the NACK response, the host may send a Stop condition to complete the protocol, or it can send a Start condition to begin the next sequence.

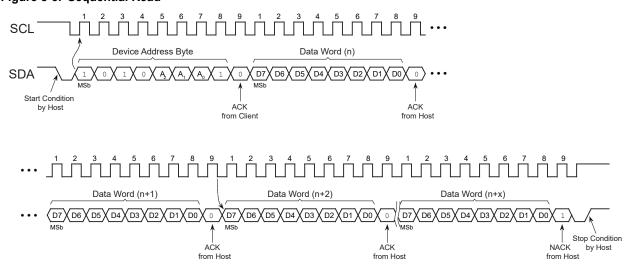
Figure 8-2. Random Read



## 8.3 Sequential Read

Sequential reads are initiated by either a current address read or a random read. After the bus host receives a data word, it responds with an Acknowledge. As long as the EEPROM receives an ACK, it will continue to increment the word address and serially clock out sequential data words. When the maximum memory address is reached, the data word address will rollover and the sequential read will continue from the beginning of the memory array. All types of read operations will be terminated if the bus host does not respond with an ACK (it NACKs) during the ninth clock cycle. After the NACK response, the host may send a Stop condition to complete the protocol or it can send a Start condition to begin the next sequence.

Figure 8-3. Sequential Read



<ol><li>Device Default Condition from Microc</li></ol>	cnip
--	------

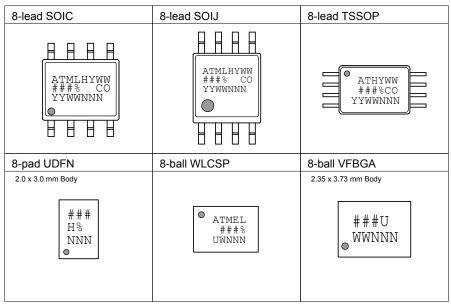
The AT24C512C is delivered with the EEPROM array set to logic '1', resulting in FFh data in all locations.

Datasheet

#### 10. **Packaging Information**

#### **Package Marking Information** 10.1





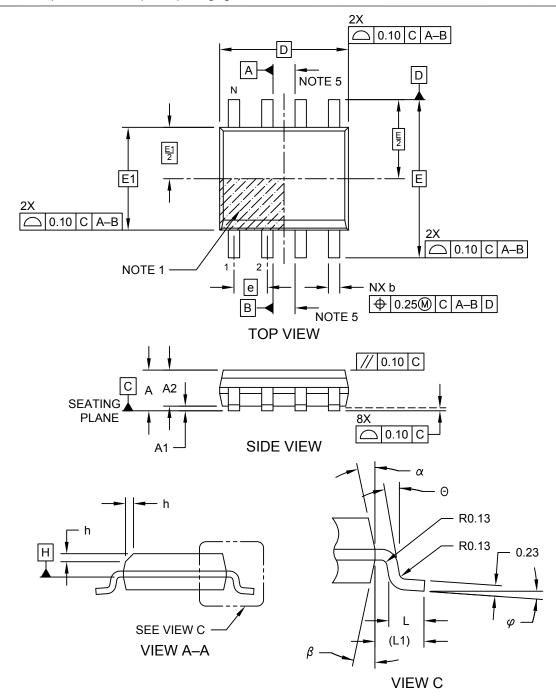
Note 1: O designates pin 1 Note 2: Package drawings are not to scale

Catalog Number Truncation								
AT24C512C			Trun	Truncation Code: ### = 2FC				
Date Code	<u> </u>				Voltages			
YY = Year		Y = Year		WW = Work Week of Assembly	% = Minimum Voltage			
16: 2016 17: 2017 18: 2018 19: 2019	20: 2020 21: 2021 22: 2022 23: 2023	6: 2016 7: 2017 8: 2018 9: 2019	0: 2020 1: 2021 2: 2022 3: 2023	02: Week 2 04: Week 4  52: Week 52	M: 1.7V min D: 2.5V min			
Country of	Origin		Device	Grade	Atmel Truncation			
CO = Coun	try of Origin		H or U:	Industrial Grade	AT: Atmel ATM: Atmel ATML: Atmel			
Lot Number or Trace Code								

NNN = Alphanumeric Trace Code (2 Characters for Small Packages)

## 8-Lead Plastic Small Outline (SN) - Narrow, 3.90 mm (.150 ln.) Body [SOIC]

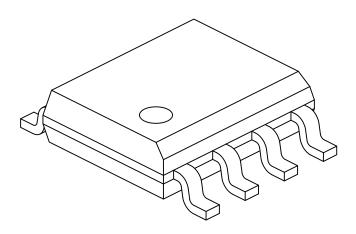
**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Microchip Technology Drawing No. C04-057-SN Rev F Sheet 1 of 2

## 8-Lead Plastic Small Outline (SN) - Narrow, 3.90 mm (.150 ln.) Body [SOIC]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	MILLIMETERS			
Dimension	Limits	MIN	NOM	MAX
Number of Pins	N		8	
Pitch	е		1.27 BSC	
Overall Height	Α	1	-	1.75
Molded Package Thickness	A2	1.25	ı	-
Standoff §	A1	0.10	ı	0.25
Overall Width	Е	6.00 BSC		
Molded Package Width E1 3.90 BSC				
Overall Length	D	4.90 BSC		
Chamfer (Optional)	h	0.25	ı	0.50
Foot Length	L	0.40	ı	1.27
Footprint	L1		1.04 REF	
Foot Angle	$\varphi$	0°	ı	8°
Lead Thickness	С	0.17	ı	0.25
Lead Width	b	0.31	-	0.51
Mold Draft Angle Top	α	5°	-	15°
Mold Draft Angle Bottom	β	5°	-	15°

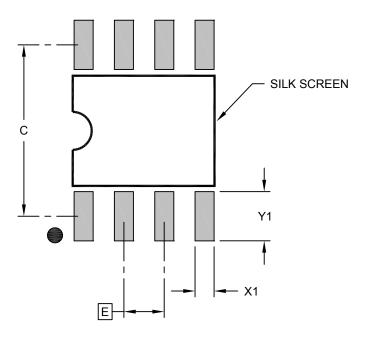
#### Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. § Significant Characteristic
- 3. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15mm per side.
- 4. Dimensioning and tolerancing per ASME Y14.5M
  - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
  - REF: Reference Dimension, usually without tolerance, for information purposes only.
- 5. Datums A & B to be determined at Datum H.

Microchip Technology Drawing No. C04-057-SN Rev F Sheet 2 of 2

## 8-Lead Plastic Small Outline (SN) - Narrow, 3.90 mm (.150 ln.) Body [SOIC]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



### RECOMMENDED LAND PATTERN

	N	IILLIMETER	S	
Dimension Limits		MIN	NOM	MAX
Contact Pitch E		1.27 BSC		
Contact Pad Spacing	С		5.40	
Contact Pad Width (X8)	X1			0.60
Contact Pad Length (X8)	Y1			1.55

#### Notes:

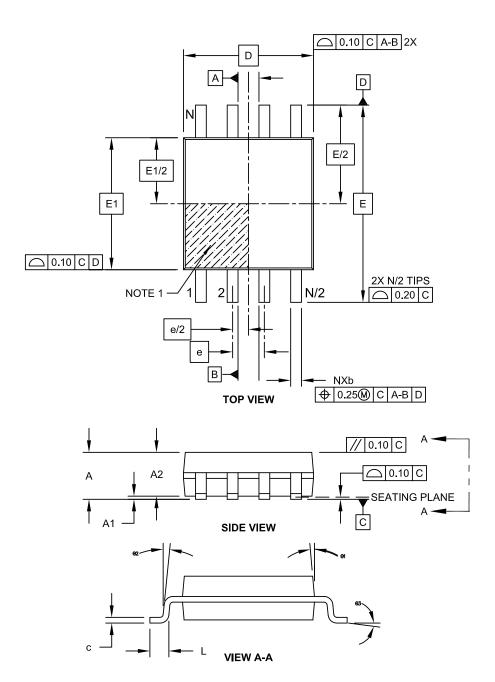
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-2057-SN Rev F

### 8-Lead Plastic Small Outline (SM) - Medium, 5.28 mm Body [SOIJ]

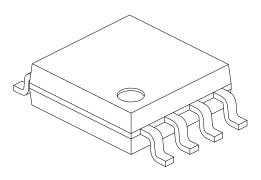
**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Microchip Technology Drawing C04-056C Sheet 1 of 2

## 8-Lead Plastic Small Outline (SM) - Medium, 5.28 mm Body [SOIJ]

For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	MILLIMETERS				
Dimension	Limits	MIN	NOM	MAX	
Number of Pins	N		8		
Pitch	е		1.27 BSC		
Overall Height	Α	1.77	ı	2.03	
Standoff §	A1	0.05		0.25	
Molded Package Thickness	A2	1.75	ı	1.98	
Overall Width	Е		7.94 BSC		
Molded Package Width	E1		5.25 BSC		
Overall Length	D		5.26 BSC		
Foot Length	L	0.51	-	0.76	
Lead Thickness	С	0.15	ı	0.25	
Lead Width	b	0.36	-	0.51	
Mold Draft Angle	Θ1	-	1	15°	
Lead Angle	Θ2	0°	ı	8°	
Foot Angle	Θ3	0°	-	8°	

**Datasheet** 

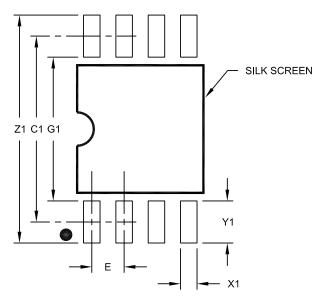
#### Notes:

- 1. SOIJ, JEITA/EIAJ Standard, Formerly called SOIC
- 2. § Significant Characteristic
- 3. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.25mm per side.

Microchip Technology Drawing No. C04-056C Sheet 2 of 2

### 8-Lead Plastic Small Outline (SM) - Medium, 5.28 mm Body [SOIJ]

For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

	N	<b>IILLIMETER</b>	S	
Dimension	MIN	NOM	MAX	
Contact Pitch E			1.27 BSC	
Overall Width	Z1			9.00
Contact Pad Spacing	C1		7.30	
Contact Pad Width (X8)	X1			0.65
Contact Pad Length (X8)	Y1			1.70
Distance Between Pads	G1	5.60		
Distance Between Pads	G	0.62		

#### Notes:

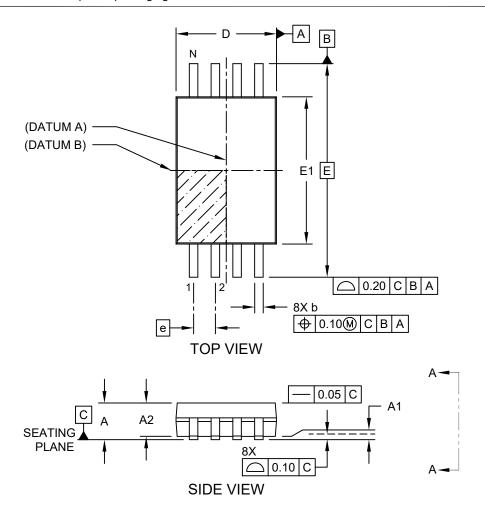
1. Dimensioning and tolerancing per ASME Y14.5M

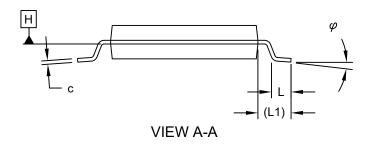
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2056C

## 8-Lead Plastic Thin Shrink Small Outline (ST) - 4.4 mm Body [TSSOP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging

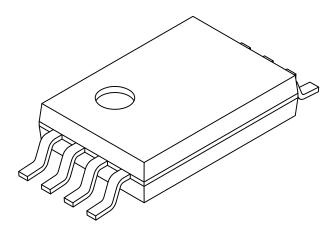




Microchip Technology Drawing C04-086 Rev C Sheet 1 of 2

## 8-Lead Plastic Thin Shrink Small Outline (ST) - 4.4 mm Body [TSSOP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	MILLIMETERS			
Dimension	Limits	MIN	NOM	MAX
Number of Pins	N		8	
Pitch	е		0.65 BSC	
Overall Height	Α	-	-	1.20
Molded Package Thickness	A2	0.80	1.00	1.05
Standoff	A1	0.05	-	-
Overall Width	Е		6.40 BSC	
Molded Package Width	E1	4.30	4.40	4.50
Overall Length	D	2.90	3.00	3.10
Foot Length	L	0.45	0.60	0.75
Footprint	L1		1.00 REF	
Lead Thickness	С	0.09	-	0.25
Foot Angle	$\varphi$	0°	4°	8°
Lead Width	b	0.19	_	0.30

#### Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.20mm per side.
- 3. Dimensioning and tolerancing per ASME Y14.5M

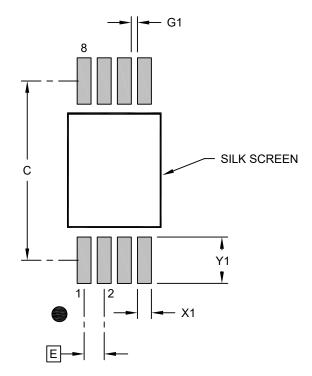
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-086 Rev C Sheet 2 of 2

## 8-Lead Plastic Thin Shrink Small Outline (ST) - 4.4 mm Body [TSSOP]

For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



#### RECOMMENDED LAND PATTERN

	N	<b>MILLIMETER</b>	S	
Dimension Limits		MIN	NOM	MAX
Contact Pitch	Е		0.65 BSC	
Contact Pad Spacing	С		5.80	
Contact Pad Width (X8)	X1			0.45
Contact Pad Length (X8)	Y1			1.50
Contact Pad to Center Pad (X6)	G1	0.20		

#### Notes:

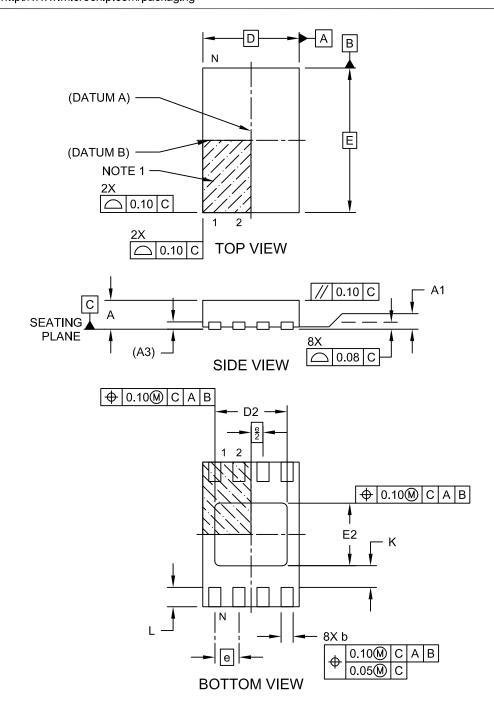
Note:

- 1. Dimensioning and tolerancing per ASME Y14.5M
  - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
- 2. For best soldering results, thermal vias, if used, should be filled or tented to avoid solder loss during reflow process

Microchip Technology Drawing C04-2086 Rev B

# 8-Lead Ultra Thin Plastic Dual Flat, No Lead Package (Q4B) - 2x3 mm Body [UDFN] Atmel Legacy Global Package Code YNZ

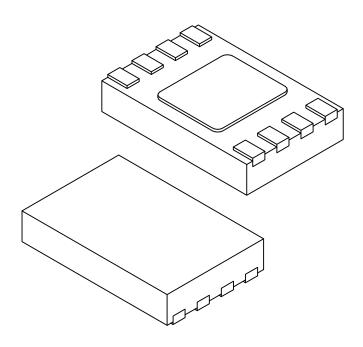
**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Microchip Technology Drawing C04-21355-Q4B Rev C Sheet 1 of 2

# 8-Lead Ultra Thin Plastic Dual Flat, No Lead Package (Q4B) - 2x3 mm Body [UDFN] Atmel Legacy Global Package Code YNZ

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	MILLIMETERS				
Dimension	Limits	MIN	NOM	MAX	
Number of Terminals	Ν		8		
Pitch	е		0.50 BSC		
Overall Height	Α	0.50	0.55	0.60	
Standoff	A1	0.00	0.02	0.05	
Terminal Thickness	А3		0.152 REF		
Overall Length	D	2.00 BSC			
Exposed Pad Length	D2	1.40	1.50	1.60	
Overall Width	Е		3.00 BSC		
Exposed Pad Width	E2	1.20	1.30	1.40	
Terminal Width	b	0.18	0.25	0.30	
Terminal Length	L	0.25	0.35	0.45	
Terminal-to-Exposed-Pad	K	0.20	-	-	

#### Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. Package is saw singulated
- 3. Dimensioning and tolerancing per ASME Y14.5M

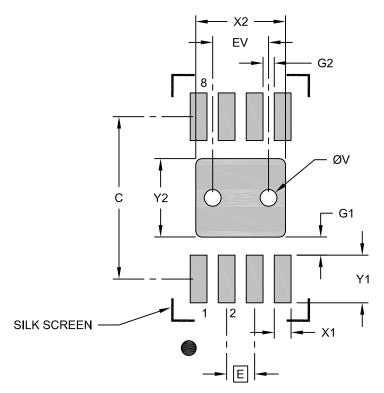
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-21355-Q4B Rev C Sheet 2 of 2

# 8-Lead Ultra Thin Plastic Dual Flat, No Lead Package (Q4B) - 2x3 mm Body [UDFN] Atmel Legacy Global Package Code YNZ

**bte:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



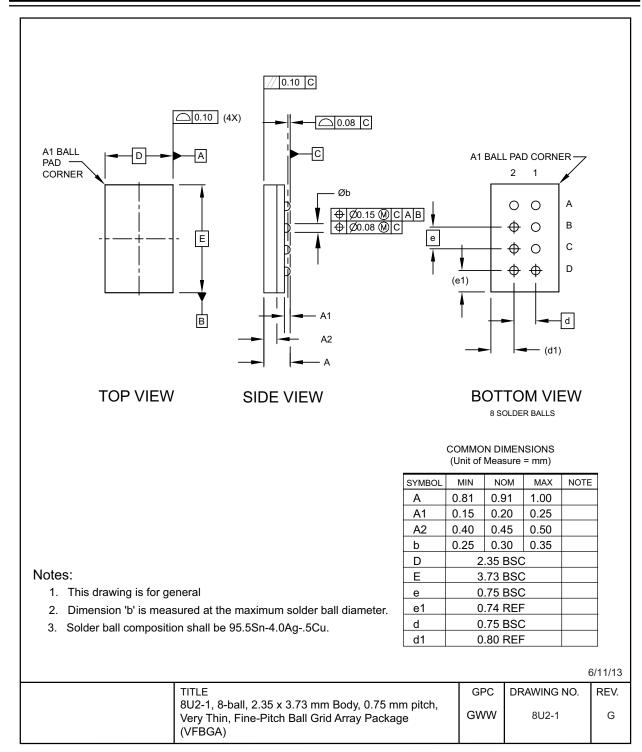
#### RECOMMENDED LAND PATTERN

	MILLIMETERS			
Dimension	MIN	NOM	MAX	
Contact Pitch	Е	0.50 BSC		
Optional Center Pad Width	X2			1.60
Optional Center Pad Length	Y2			1.40
Contact Pad Spacing	С		2.90	
Contact Pad Width (X8)	X1			0.30
Contact Pad Length (X8)	Y1			0.85
Contact Pad to Center Pad (X8)	G1	0.33		
Contact Pad to Contact Pad (X6)	G2	0.20		
Thermal Via Diameter	V		0.30	
Thermal Via Pitch	EV		1.00	

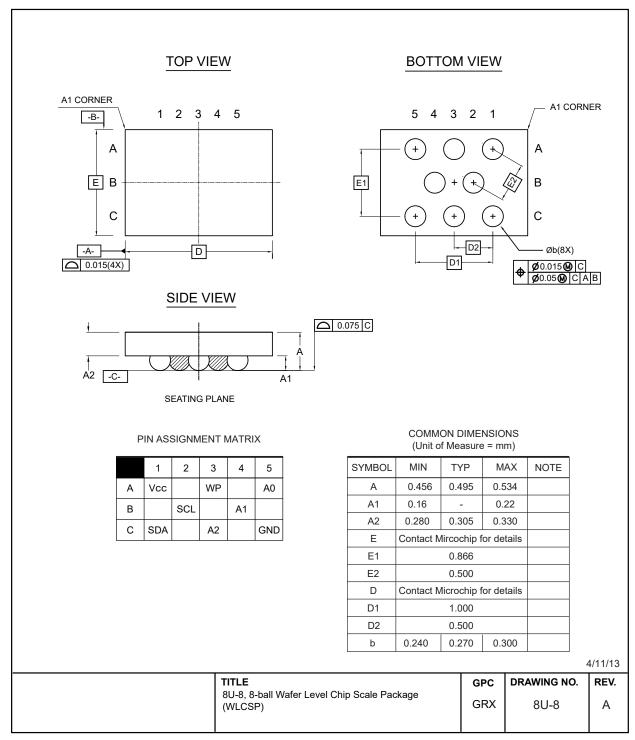
#### Notes:

- Dimensioning and tolerancing per ASME Y14.5M
   BSC: Basic Dimension. Theoretically exact value shown without tolerances.
- 2. For best soldering results, thermal vias, if used, should be filled or tented to avoid solder loss during reflow process

Microchip Technology Drawing C04-23355-Q4B Rev C



**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging.



**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging.

## 11. Revision History

#### Revision C (April 2021)

Replaced terminology "Master" and "Slave" with "Host" and "Client", respectively. Added note to Table 4-6 that explains the array architecture and how endurance is specified. Updated TSSOP and UDFN package drawings.

#### Revision B (March 2020)

Revised Noise Suppression Time (t<sub>I</sub>) from 100 ns to 50 ns. Updated SOIC 8-Lead package drawing.

#### Revision A (March 2019)

Updated to the Microchip template. Microchip DS20006161 replaces Atmel document 8720. Corrected  $t_{LOW}$  typo from 400 ns to 500 ns. Corrected  $t_{AA}$  typo from 550 ns to 450 ns. Deleted the AT24C512C-CUMHY-T package options. Updated Part Marking Information. Updated the "Software Reset" section. Added ESD rating. Removed lead finish designation. Updated trace code format in package markings. Updated section content throughout for clarification. Added a figure for "System Configuration Using Two-Wire Serial EEPROMs". Added POR recommendations section. Updated the SOIC, SOIJ, TSSOP and UDFN package drawings to Microchip format.

#### Atmel Document 8720 Revision G (September 2015)

Added AT24C512C-CUMHY-T package option.

#### Atmel Document 8720 Revision F (January 2015)

Added the UDFN expanded quantity option. Updated package outline drawings and the ordering information section.

#### Atmel Document 8720 Revision E (August 2013)

Corrected spelling error. Corrected subscript pin names on pinouts. Updated the  $I_{CC1}$  and  $I_{CC2}$  supply currents in the DC Characteristics table.

#### Atmel Document 8720 Revision D (March 2013)

Added 8U-8 WLCSP package offering. Updated related information throughout document. Updated footers and disclaimer page.

#### Atmel Document 8720 Revision C (July 2012)

Updated part markings. Updated package drawings. Updated template.

#### Atmel Document 8720 Revision B (December 2012)

Replaced part markings with single page standard marking. Removed five ordering code combinations.

#### Atmel Document 8720 Revision A (September 2010)

Initial document release.

# The Microchip Website

Microchip provides online support via our website at <a href="www.microchip.com/">www.microchip.com/</a>. This website is used to make files and information easily available to customers. Some of the content available includes:

- **Product Support** Data sheets and errata, application notes and sample programs, design resources, user's guides and hardware support documents, latest software releases and archived software
- General Technical Support Frequently Asked Questions (FAQs), technical support requests, online discussion groups, Microchip design partner program member listing
- Business of Microchip Product selector and ordering guides, latest Microchip press releases, listing of seminars and events, listings of Microchip sales offices, distributors and factory representatives

## **Product Change Notification Service**

Microchip's product change notification service helps keep customers current on Microchip products. Subscribers will receive email notification whenever there are changes, updates, revisions or errata related to a specified product family or development tool of interest.

To register, go to www.microchip.com/pcn and follow the registration instructions.

## **Customer Support**

Users of Microchip products can receive assistance through several channels:

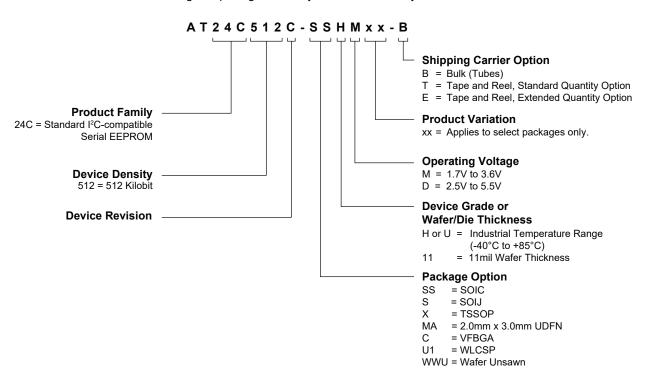
- · Distributor or Representative
- · Local Sales Office
- Embedded Solutions Engineer (ESE)
- · Technical Support

Customers should contact their distributor, representative or ESE for support. Local sales offices are also available to help customers. A listing of sales offices and locations is included in this document.

Technical support is available through the website at: www.microchip.com/support

# **Product Identification System**

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.



#### Examples

Device	Package	Package Drawing Code	Package Option	Voltage Range	Shipping Carrier Option	Device Grade
AT24C512C-SSHM-B	SOIC	SN	SS	1.7V to 3.6V	Bulk (Tubes)	
AT24C512C-SHD-T	SOIJ	SM	S	2.5V to 5.5V	Tape and Reel	
AT24C512C-XHM-T	TSSOP	ST	X	1.7V to 3.6V	Tape and Reel	
AT24C512C-XHD-T	TSSOP	ST	X	2.5V to 5.5V	Tape and Reel	Industrial Tamparatura
AT24C512C-MAHM-T	UDFN	Q4B	MA	1.7V to 3.6V	Tape and Reel	Industrial Temperature (-40°C to +85°C)
AT24C512C-MAHM-E	UDFN	Q4B	MA	1.7V to 3.6V	Extended Qty. Tape and Reel	
AT24C512C-U1UM-T	WLCSP	8U-8	U1	1.7V to 3.6V	Tape and Reel	
AT24C512C-CUM-T	VFBGA	8U2-1	С	1.7V to 3.6V	Tape and Reel	

# **Microchip Devices Code Protection Feature**

Note the following details of the code protection feature on Microchip devices:

- · Microchip products meet the specifications contained in their particular Microchip Data Sheet.
- Microchip believes that its family of products is secure when used in the intended manner and under normal conditions.

- There are dishonest and possibly illegal methods being used in attempts to breach the code protection features
  of the Microchip devices. We believe that these methods require using the Microchip products in a manner
  outside the operating specifications contained in Microchip's Data Sheets. Attempts to breach these code
  protection features, most likely, cannot be accomplished without violating Microchip's intellectual property rights.
- Microchip is willing to work with any customer who is concerned about the integrity of its code.
- Neither Microchip nor any other semiconductor manufacturer can guarantee the security of its code. Code
  protection does not mean that we are guaranteeing the product is "unbreakable." Code protection is constantly
  evolving. We at Microchip are committed to continuously improving the code protection features of our products.
  Attempts to break Microchip's code protection feature may be a violation of the Digital Millennium Copyright Act.
  If such acts allow unauthorized access to your software or other copyrighted work, you may have a right to sue
  for relief under that Act.

## **Legal Notice**

Information contained in this publication is provided for the sole purpose of designing with and using Microchip products. Information regarding device applications and the like is provided only for your convenience and may be superseded by updates. It is your responsibility to ensure that your application meets with your specifications.

THIS INFORMATION IS PROVIDED BY MICROCHIP "AS IS". MICROCHIP MAKES NO REPRESENTATIONS OR WARRANTIES OF ANY KIND WHETHER EXPRESS OR IMPLIED, WRITTEN OR ORAL, STATUTORY OR OTHERWISE, RELATED TO THE INFORMATION INCLUDING BUT NOT LIMITED TO ANY IMPLIED WARRANTIES OF NON-INFRINGEMENT, MERCHANTABILITY, AND FITNESS FOR A PARTICULAR PURPOSE OR WARRANTIES RELATED TO ITS CONDITION, QUALITY, OR PERFORMANCE.

IN NO EVENT WILL MICROCHIP BE LIABLE FOR ANY INDIRECT, SPECIAL, PUNITIVE, INCIDENTAL OR CONSEQUENTIAL LOSS, DAMAGE, COST OR EXPENSE OF ANY KIND WHATSOEVER RELATED TO THE INFORMATION OR ITS USE, HOWEVER CAUSED, EVEN IF MICROCHIP HAS BEEN ADVISED OF THE POSSIBILITY OR THE DAMAGES ARE FORESEEABLE. TO THE FULLEST EXTENT ALLOWED BY LAW, MICROCHIP'S TOTAL LIABILITY ON ALL CLAIMS IN ANY WAY RELATED TO THE INFORMATION OR ITS USE WILL NOT EXCEED THE AMOUNT OF FEES, IF ANY, THAT YOU HAVE PAID DIRECTLY TO MICROCHIP FOR THE INFORMATION. Use of Microchip devices in life support and/or safety applications is entirely at the buyer's risk, and the buyer agrees to defend, indemnify and hold harmless Microchip from any and all damages, claims, suits, or expenses resulting from such use. No licenses are conveyed, implicitly or otherwise, under any Microchip intellectual property rights unless otherwise stated.

## **Trademarks**

The Microchip name and logo, the Microchip logo, Adaptec, AnyRate, AVR, AVR logo, AVR Freaks, BesTime, BitCloud, chipKIT, chipKIT logo, CryptoMemory, CryptoRF, dsPIC, FlashFlex, flexPWR, HELDO, IGLOO, JukeBlox, KeeLoq, Kleer, LANCheck, LinkMD, maXStylus, maXTouch, MediaLB, megaAVR, Microsemi, Microsemi logo, MOST, MOST logo, MPLAB, OptoLyzer, PackeTime, PIC, picoPower, PICSTART, PIC32 logo, PolarFire, Prochip Designer, QTouch, SAM-BA, SenGenuity, SpyNIC, SST, SST Logo, SuperFlash, Symmetricom, SyncServer, Tachyon, TimeSource, tinyAVR, UNI/O, Vectron, and XMEGA are registered trademarks of Microchip Technology Incorporated in the U.S.A. and other countries.

AgileSwitch, APT, ClockWorks, The Embedded Control Solutions Company, EtherSynch, FlashTec, Hyper Speed Control, HyperLight Load, IntelliMOS, Libero, motorBench, mTouch, Powermite 3, Precision Edge, ProASIC, ProASIC Plus, ProASIC Plus logo, Quiet-Wire, SmartFusion, SyncWorld, Temux, TimeCesium, TimeHub, TimePictra, TimeProvider, WinPath, and ZL are registered trademarks of Microchip Technology Incorporated in the U.S.A.

Adjacent Key Suppression, AKS, Analog-for-the-Digital Age, Any Capacitor, Anyln, AnyOut, Augmented Switching, BlueSky, BodyCom, CodeGuard, CryptoAuthentication, CryptoAutomotive, CryptoCompanion, CryptoController, dsPICDEM, dsPICDEM.net, Dynamic Average Matching, DAM, ECAN, Espresso T1S, EtherGREEN, IdealBridge, In-Circuit Serial Programming, ICSP, INICnet, Intelligent Paralleling, Inter-Chip Connectivity, JitterBlocker, maxCrypto, maxView, memBrain, Mindi, MiWi, MPASM, MPF, MPLAB Certified logo, MPLIB, MPLINK, MultiTRAK, NetDetach, Omniscient Code Generation, PICDEM, PICDEM.net, PICkit, PICtail, PowerSmart, PureSilicon, QMatrix, REAL ICE, Ripple Blocker, RTAX, RTG4, SAM-ICE, Serial Quad I/O, simpleMAP, SimpliPHY, SmartBuffer, SMART-I.S., storClad, SQI, SuperSwitcher, SuperSwitcher II, Switchtec, SynchroPHY, Total Endurance, TSHARC, USBCheck, VariSense,

VectorBlox, VeriPHY, ViewSpan, WiperLock, XpressConnect, and ZENA are trademarks of Microchip Technology Incorporated in the U.S.A. and other countries.

SQTP is a service mark of Microchip Technology Incorporated in the U.S.A.

The Adaptec logo, Frequency on Demand, Silicon Storage Technology, and Symmcom are registered trademarks of Microchip Technology Inc. in other countries.

GestIC is a registered trademark of Microchip Technology Germany II GmbH & Co. KG, a subsidiary of Microchip Technology Inc., in other countries.

All other trademarks mentioned herein are property of their respective companies.

© 2019-2021, Microchip Technology Incorporated, Printed in the U.S.A., All Rights Reserved.

ISBN: 978-1-5224-8010-5

AMBA, Arm, Arm7, Arm7TDMI, Arm9, Arm11, Artisan, big.LITTLE, Cordio, CoreLink, CoreSight, Cortex, DesignStart, DynamIQ, Jazelle, Keil, Mali, Mbed, Mbed Enabled, NEON, POP, RealView, SecurCore, Socrates, Thumb, TrustZone, ULINK, ULINK2, ULINK-ME, ULINK-PLUS, ULINKpro, µVision, Versatile are trademarks or registered trademarks of Arm Limited (or its subsidiaries) in the US and/or elsewhere.

## **Quality Management System**

For information regarding Microchip's Quality Management Systems, please visit www.microchip.com/quality.



# **Worldwide Sales and Service**

AMERICAS	ASIA/PACIFIC	ASIA/PACIFIC	EUROPE
Corporate Office	Australia - Sydney	India - Bangalore	Austria - Wels
2355 West Chandler Blvd.	Tel: 61-2-9868-6733	Tel: 91-80-3090-4444	Tel: 43-7242-2244-39
Chandler, AZ 85224-6199	China - Beijing	India - New Delhi	Fax: 43-7242-2244-393
Tel: 480-792-7200	Tel: 86-10-8569-7000	Tel: 91-11-4160-8631	Denmark - Copenhagen
Fax: 480-792-7277	China - Chengdu	India - Pune	Tel: 45-4485-5910
Technical Support:	Tel: 86-28-8665-5511	Tel: 91-20-4121-0141	Fax: 45-4485-2829
www.microchip.com/support	China - Chongqing	Japan - Osaka	Finland - Espoo
Web Address:	Tel: 86-23-8980-9588	Tel: 81-6-6152-7160	Tel: 358-9-4520-820
www.microchip.com	China - Dongguan	Japan - Tokyo	France - Paris
Atlanta	Tel: 86-769-8702-9880	Tel: 81-3-6880- 3770	Tel: 33-1-69-53-63-20
Duluth, GA	China - Guangzhou	Korea - Daegu	Fax: 33-1-69-30-90-79
Tel: 678-957-9614	Tel: 86-20-8755-8029	Tel: 82-53-744-4301	Germany - Garching
Fax: 678-957-1455	China - Hangzhou	Korea - Seoul	Tel: 49-8931-9700
Austin, TX	Tel: 86-571-8792-8115	Tel: 82-2-554-7200	Germany - Haan
Tel: 512-257-3370	China - Hong Kong SAR	Malaysia - Kuala Lumpur	Tel: 49-2129-3766400
Boston	Tel: 852-2943-5100	Tel: 60-3-7651-7906	Germany - Heilbronn
Westborough, MA	China - Nanjing	Malaysia - Penang	Tel: 49-7131-72400
Tel: 774-760-0087	Tel: 86-25-8473-2460	Tel: 60-4-227-8870	Germany - Karlsruhe
Fax: 774-760-0088	China - Qingdao	Philippines - Manila	Tel: 49-721-625370
Chicago	Tel: 86-532-8502-7355	Tel: 63-2-634-9065	Germany - Munich
Itasca, IL	China - Shanghai	Singapore	Tel: 49-89-627-144-0
Tel: 630-285-0071	Tel: 86-21-3326-8000	Tel: 65-6334-8870	Fax: 49-89-627-144-44
Fax: 630-285-0075	China - Shenyang	Taiwan - Hsin Chu	Germany - Rosenheim
Dallas	Tel: 86-24-2334-2829	Tel: 886-3-577-8366	Tel: 49-8031-354-560
Addison, TX	China - Shenzhen	Taiwan - Kaohsiung	Israel - Ra'anana
Tel: 972-818-7423	Tel: 86-755-8864-2200	Tel: 886-7-213-7830	Tel: 972-9-744-7705
Fax: 972-818-2924	China - Suzhou	Taiwan - Taipei	Italy - Milan
Detroit	Tel: 86-186-6233-1526	Tel: 886-2-2508-8600	Tel: 39-0331-742611
Novi, MI	China - Wuhan	Thailand - Bangkok	Fax: 39-0331-466781
Tel: 248-848-4000	Tel: 86-27-5980-5300	Tel: 66-2-694-1351	Italy - Padova
Houston, TX	China - Xian	Vietnam - Ho Chi Minh	Tel: 39-049-7625286
Tel: 281-894-5983	Tel: 86-29-8833-7252	Tel: 84-28-5448-2100	Netherlands - Drunen
Indianapolis	China - Xiamen		Tel: 31-416-690399
Noblesville, IN	Tel: 86-592-2388138		Fax: 31-416-690340
Tel: 317-773-8323	China - Zhuhai		Norway - Trondheim
Fax: 317-773-5453	Tel: 86-756-3210040		Tel: 47-72884388
Tel: 317-536-2380			Poland - Warsaw
Los Angeles			Tel: 48-22-3325737
Mission Viejo, CA			Romania - Bucharest
Tel: 949-462-9523			Tel: 40-21-407-87-50
Fax: 949-462-9608			Spain - Madrid
Tel: 951-273-7800			Tel: 34-91-708-08-90
Raleigh, NC			Fax: 34-91-708-08-91
Tel: 919-844-7510			Sweden - Gothenberg
New York, NY			Tel: 46-31-704-60-40
Tel: 631-435-6000			Sweden - Stockholm
San Jose, CA			Tel: 46-8-5090-4654
Tel: 408-735-9110			UK - Wokingham
Tel: 408-436-4270			Tel: 44-118-921-5800
Canada - Toronto			Fax: 44-118-921-5820
Tel: 905-695-1980			
Fax: 905-695-2078			
000 000 2010			