### 2. Specifications

Characteristics	Item		Specifications	
Contact	Arrangement		1 Form C × 2, 1 Form C	
	Contact resistance (Initial)		N.O.: Typ 7mΩ, N.C.: Typ 10mΩ (By voltage drop 6V DC 1A)	
	Contact material		Ag alloy (Cadmium free)	
Rating	Nominal switching capacity (resistive load)		N.O.: 20 A 14V DC, N.C.: 10 A 14V DC	
	Max. carrying current (14V DC)*3		N.O.: 25 A for 1 hour, 35 A for 2 minutes at 20°C 68°F 20 A for 1 hour, 30 A for 2 minutes at 85°C 185°F	
	Nominal operating power		800 mW	
	Min. switching capacity (resistive load)*1		1 A 14V DC	
Electrical characteristics	Insulation resistance (Initial)		Min. 100 M $\Omega$ (at 500V DC, Measurement at same location as "Breakdown voltage" section.)	
	Breakdown voltage (Initial)	Between open contacts	500 Vrms for 1 min. (Detection current: 10mA)	
		Between contacts and coil	500 Vrms for 1 min. (Detection current: 10mA)	
	Operate time (at nominal voltage)		Max. 10ms (at 20°C 68°F, excluding contact bounce time) (Initial)	
	Release time (at nominal voltage)		Max. 10ms (at 20°C 68°F, excluding contact bounce time) (Initial)	
Mechanical characteristics	Shock resistance	Functional	Min. 100 m/s <sup>2</sup> {10G} (Half-wave pulse of sine wave: 11ms; detection time: $10\mu s$ )	
		Destructive	Min. 1,000 m/s <sup>2</sup> {100G} (Half-wave pulse of sine wave: 6ms)	
	Vibration resistance	Functional	10 Hz to 100 Hz, Min. 44.1 m/s² {4.5G} (Detection time: $10 \mu s)$	
		Destructive	10 Hz to 500 Hz, Min. 44.1 m/s² {4.5G}, Time of vibration for each direction; X, Y direction: 2 hours, Z direction: 4 hours	
	Mechanical		Min. 10 <sup>7</sup> (at 120 cpm)	
Expected life	Electrical		<resistive load=""> Min. 10<sup>5</sup> (at nominal switching capacity, operating frequency: 1s ON, 9s OFF) <motor load=""> N.O. side: Min. 2 × 10<sup>5</sup> (at Inrush 25A, Steady 5A 14 V DC), Min. 10<sup>5</sup> (at 25A 14 V DC motor lock condition) N.C. side: Min. 2 × 10<sup>6</sup> (at brake current 20A 14 V DC) (operating frequency: 0.5s ON, 9.5s OFF)</motor></resistive>	
Conditions	Conditions for operation, transport and storage*2		Ambient temperature: $-40^{\circ}$ C to $+85^{\circ}$ C $-40^{\circ}$ F to $+185^{\circ}$ F, Humidity: 5% R.H. to 85% R.H. (Not freezing and condensing at low temperature)	
	Max. operating speed		6 cpm (at nominal switching capacity)	
Mass			Twin type: approx. 8 g .28 oz, 1 Form C type: approx. 4 g .14 oz	

Notes:

\*1. This value can change due to the switching frequency, environmental conditions, and desired reliability level, therefore it is recommended to check this with the actual load.
 \*2. The upper operation ambient temperature limit is the maximum temperature that can satisfy the coil temperature rise value. Refer to "6. Usage, Storage and Transport Conditions" in AMBIENT ENVIRONMENT section in Relay Technical Information.

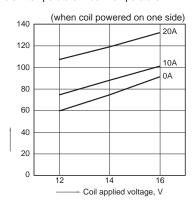
Please inquire if you will be using the relay in a high temperature atmosphere (110°C 230°F).

\*3. Depends on connection conditions. Also, this does not guarantee repeated switching. We recommend that you confirm operation under actual conditions.

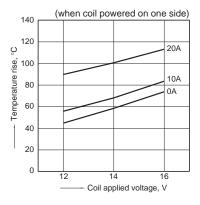
\* If the relay is used continuously for long periods of time with coils on both sides in an energized condition, breakdown might occur due to abnormal heating depending on the carrying condition. Therefore, please inquire when using with a circuit that causes an energized condition on both sides simultaneously.

### **REFERENCE DATA**

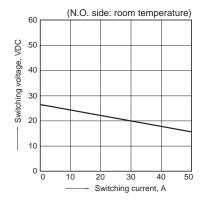
1-(1). Coil temperature rise (at room temperature) Sample: ACT212, 3pcs. Contact carrying current: 0A, 10A, 20A Ambient temperature: Room temperature

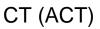


1-(2). Coil temperature rise (at 85°C 185°F) Sample: ACT212, 3pcs. Contact carrying current: 0A, 10A, 20A Ambient temperature: 85°C 185°F

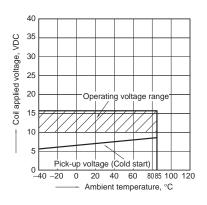


2. Max. switching capability (Resistive load, initial)

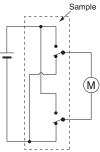




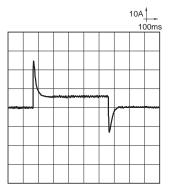
3. Ambient temperature and operating voltage range



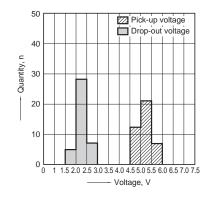
6-(1). Electrical life test (Motor free) Sample: ACT212, 3pcs. Load: Inrush 25A, steady 5A Brake current: 13A 14V DC, Power window motor actual load (free condition) Operating frequency: ON 0.5s, OFF 9.5s Ambient temperature: Room temperature Circuit:



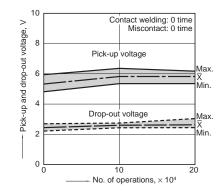
Load current waveform Inrush current: 25A, Steady current: 6A Brake current: 13A



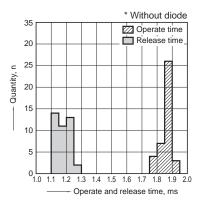
4. Distribution of pick-up and drop-out voltage Sample: ACT212, 40pcs.



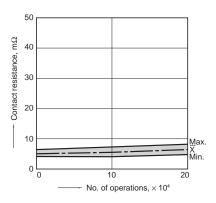
Change of pick-up and drop-out voltage



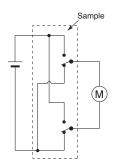
5. Distribution of operate and release time Sample: ACT212, 40pcs.



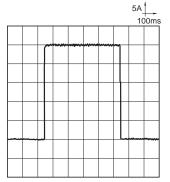
Change of contact resistance



6-(2). Electrical life test (Motor lock) Sample: ACT212, 3pcs. Load: 25A 14V DC Power window motor actual load (lock condition) Switching frequency: ON 0.5s, OFF 9.5s Ambient temperature: Room temperature Circuit:

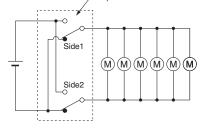


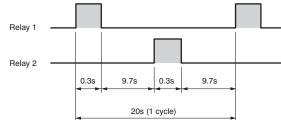
#### Load current waveform



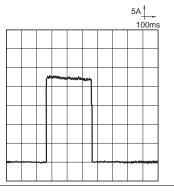
6-(3). Electrical life test (Motor lock) Sample: ACT212, 3pcs. Load: 20A 14V DC,

door lock motor actual load (Lock condition) Switching frequency: ON 0.3s, OFF 19.7s Ambient temperature: Room temperature Circuit: Sample

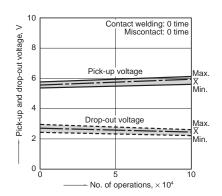




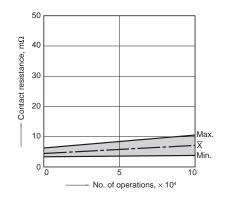
Load current waveform



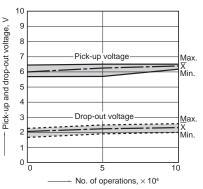
### Change of pick-up and drop-out voltage



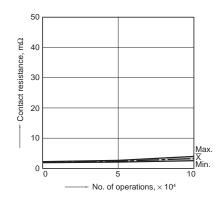
#### Change of contact resistance



Change of pick-up and drop-out voltage



#### Change of contact resistance



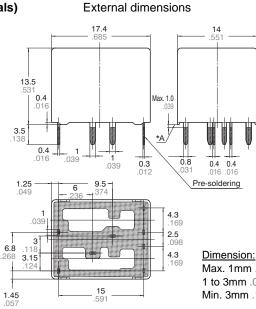
4

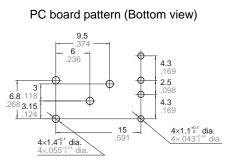
### DIMENSIONS (mm inch)

### 1. Twin type (8 terminals)

CAD Data



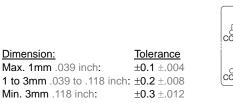




Download CAD Data from our Web site.

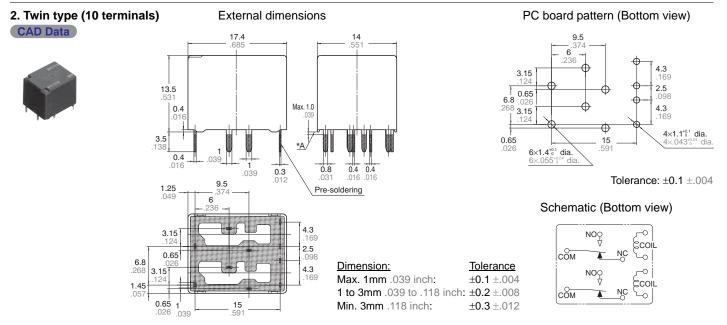
Tolerance:  $\pm 0.1 \pm .004$ 

### Schematic (Bottom view)



Сом	Å	NCO	COIL
Сом	NOO		

\* Dimensions (thickness and width) of terminal is measured before pre-soldering. Intervals between terminals is measured at A surface level.



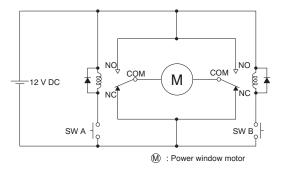
\* Dimensions (thickness and width) of terminal is measured before pre-soldering. Intervals between terminals is measured at A surface level.

#### 3. Slim 1c type External dimensions PC board pattern (Bottom view) CAD Data **17.4 3×1.4 dia.** 3×.055 dia 9.5 **4.3** .169 3.15 13.5 2×1.1<sup>+0.1</sup> dia. **0.4** .016 Max. 1.0 0.65 **15** .591 dia. **3.5** Tolerance: $\pm 0.1 \pm .004$ \*A **0.4** .016 0.8 Schematic (Bottom view) 0.30 0.3 .012 **0.4** .016 **0.4** .016 .039 9.5 **1.25** .049 Pre-soldering NO ♀ ζčόιι 6 374 сом NC Dimension: **Tolerance** 4.3 **3.15** .124 Max. 1mm .039 inch: $\pm 0.1 \pm .004$ 1 to 3mm .039 to .118 inch: ±0.2 ±.008 **1.45** .057 **0.65** 15 Min. 3mm .118 inch: $\pm 0.3 \pm .012$

\* Dimensions (thickness and width) of terminal is measured before pre-soldering. Intervals between terminals is measured at A surface level.

### **EXAMPLE OF CIRCUIT**

Forward/reverse control circuits of DC motor for power windows



For Cautions for Use, see Relay Technical Information.