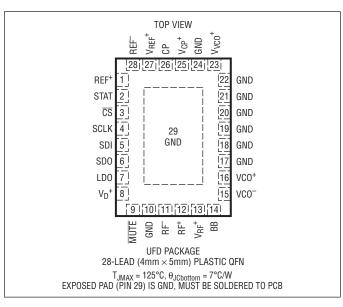
ABSOLUTE MAXIMUM RATINGS

(Note 1)

| Supply Voltages |
|---|
| V^+ (V_{REF}^+ , V_{RF}^+ , V_{VCO}^+ , V_D^+) to GND |
| V_{CP}^+ to GND5.5V |
| Voltage on CP Pin GND – 0.3V to V_{CP}^+ + 0.3V |
| Voltage on all other PinsGND – 0.3V to V^+ + 0.3V |
| Operating Junction Temperature Range, TJ |
| LTC6947I (Note 2)40°C to 105°C |
| Junction Temperature, T _{JMAX} 125°C |
| Storage Temperature Range–65°C to 150°C |

PIN CONFIGURATION



ORDER INFORMATION

| LEAD FREE FINISH | TAPE AND REEL | PART MARKING | PACKAGE DESCRIPTION | JUNCTION TEMPERATURE RANGE |
|------------------|-------------------|--------------|--|----------------------------|
| LTC6947IUFD#PBF | LTC6947IUFD#TRPBF | 6947 | 28-Lead (4mm \times 5mm) Plastic QFN | -40°C to 105°C |

Consult LTC Marketing for parts specified with wider operating temperature ranges.

Consult LTC Marketing for information on nonstandard lead based finish parts.

For more information on lead free part marking, go to: http://www.linear.com/leadfree/

For more information on tape and reel specifications, go to: http://www.linear.com/tapeandreel/

ELECTRICAL CHARACTERISTICS

The • denotes the specifications which apply over the full operating junction temperature range, otherwise specifications are at $T_A = 25^{\circ}$ C. $V_{REF}^+ = V_D^+ = V_{RF}^+ = V_{VCO}^+ = 3.3$ V, $V_{CP}^+ = 5$ V unless otherwise specified (Note 2). All voltages are with respect to GND.

| SYMBOL | PARAMETER | CONDITIONS | CONDITIONS | | ТҮР | MAX | UNITS |
|------------------|---------------------------------|--|------------|------|------|------|------------------|
| Reference I | nputs (REF+, REF ⁻) | | | | | | |
| f _{REF} | Input Frequency | | | 10 | | 425 | MHz |
| V _{REF} | Input Signal Level | Single-Ended, 1µF AC-Coupling Capacitors | | 0.5 | 2 | 2.7 | V _{P-P} |
| | Input Slew Rate | | | 20 | | | V/µs |
| | Input Duty Cycle | | | | 50 | | % |
| | Self-Bias Voltage | | | 1.65 | 1.85 | 2.25 | V |
| | Input Resistance | Differential | | 5.8 | 8.4 | 11.6 | kΩ |
| | Input Capacitance | Differential | | | 14 | | pF |



ELECTRICAL CHARACTERISTICS The • denotes the specifications which apply over the full operating junction temperature range, otherwise specifications are at $T_A = 25^{\circ}$ C. $V_{REF}^+ = V_D^+ = V_{RF}^+ = V_{VCO}^+ = 3.3$ V, $V_{CP}^+ = 5$ V unless otherwise specified (Note 2). All voltages are with respect to GND.

| SYMBOL | PARAMETER | CONDITIONS | | MIN | ТҮР | MAX | UNITS |
|----------------------|--|---|-------------|---------------------------|-----------------------------|---|--|
| VCO Input (\ | /CO+, VCO ⁻) | | | | | | |
| f _{VCO} | Input Frequency | | | 350 | | 6000 | MHz |
| P _{VCOI} | Input Power Level | $R_Z = 50\Omega$, Single-Ended | | -8 | 0 | 6 | dBm |
| | Input Resistance | Single-Ended, Each Input | | 94 | 132 | 161 | Ω |
| RF Output (F | RF ⁺ , RF [−]) | | | | | | |
| f _{RF} | Output Frequency | | | 350 | | 6000 | MHz |
| 0 | Output Divider Range | All Integers Included | | 1 | | 6 | |
| | Output Duty Cycle | | | | 50 | | % |
| | Output Resistance | Single-Ended, Each Output to V _{RF} ⁺ | | 100 | 136 | 175 | Ω |
| P _{RF-SE} | Output Power, Single-Ended, f _{RF} = 900MHz | $\begin{array}{l} {\sf RFO}[1:0]=0, {\sf R}_Z=50\Omega, {\sf LC} {\sf Match} \\ {\sf RFO}[1:0]=1, {\sf R}_Z=50\Omega, {\sf LC} {\sf Match} \\ {\sf RFO}[1:0]=2, {\sf R}_Z=50\Omega, {\sf LC} {\sf Match} \\ {\sf RFO}[1:0]=3, {\sf R}_Z=50\Omega, {\sf LC} {\sf Match} \end{array}$ | • • • | -9 -6.1 -2.9 0.1 | -7.3 -4.5 -1.4 1.5 | -5.5 -2.8 0.2 3.0 | dBm dBm dBm dBm |
| | Output Power, Muted, f _{RF} = 900MHz | $R_Z = 50\Omega$, Single-Ended, $0 = 2$ to 6 | | | | -80 | dBm |
| | Mute Enable Time | | | | | 110 | ns |
| | Mute Disable Time | | | | | 170 | ns |
| Phase/Frequ | iency Detector | | | | | | |
| f _{PFD} | Input Frequency | Integer mode Fractional mode LDOEN = 0 LDOV = 3, LDOEN = 1 LDOV = 2, LDOEN = 1 LDOV = 1, LDOEN = 1 LDOV = 0, LDOEN = 1 | • | | | 100 76.1 66.3 56.1 45.9 34.3 | MH: MH: MH: MH: MH: MH: |
| Charge Pum | p | 1 | | | - | | 1 |
| I _{CP} | Output Current Range | 8 Settings (See Table 6) | | 1 | | 11.2 | m/ |
| | Output Current Source/Sink Accuracy | All Settings, $V(CP) = V_{CP}^{+}/2$ | | | | ±6 | % |
| | Output Current Source/Sink Matching | $I_{CP} = 1.0$ mA to 2.8mA, V(CP) = $V_{CP}^{+}/2$ $I_{CP} = 4.0$ mA to 11.2mA, V(CP) = $V_{CP}^{+}/2$ | | | | ±3.5 ±2 | % |
| | Output Current vs Output Voltage Sensitivity | (Note 3) | | | 0.2 | 1.0 | %/\ |
| | Output Current vs Temperature | $V(CP) = V_{CP}^{+}/2$ | | | 170 | | ppm/°(|
| | Output Hi-Z Leakage Current | $I_{CP} = 11.2$ mA, CPCLO = CPCHI = 0 (Note 3) | | | 0.03 | | n/ |
| V _{CLMP-LO} | Low Clamp Voltage | CPCLO = 1 | | | 0.84 | | ١ |
| V _{CLMP-HI} | High Clamp Voltage | CPCHI = 1, Referred to V_{CP}^+ | | | -0.96 | | \ |
| V _{MID} | Mid-Supply Output Bias Ratio | Referred to $(V_{CP}^+ - GND)$ | | | 0.48 | | V/N |
| Reference (I | R) Divider | | | | | | |
| R | Divide Range | All Integers Included | | 1 | | 31 | Counts |
| VCO (N) Div | ider | | | | | | |
| N | Divide Range | All Integers Included, Integer Mode All Integers Included, Fractional Mode | • | 32 35 | | 1023 1019 | Count Count |
| Fractional Δ | Σ Modulator | | | | | | |
| | Numerator Range | All Integers Included | | 1 | | 262143 | Count |
| | | | | | | | |

ELECTRICAL CHARACTERISTICS junction temperature range, otherwise specifications are at $T_A = 25^{\circ}$ C. $V_{REF}^+ = V_D^+ = V_{RF}^+ = V_{VCO}^+ = 3.3$ V, $V_{CP}^+ = 5$ V unless otherwise specified (Note 2). All voltages are with respect to GND.

| SYMBOL | PARAMETER | CONDITIONS | | MIN | ТҮР | MAX | UNITS |
|-----------------------|--|--|------------------|-------|---|---|--|
| Modulator L | DO | · | | | | | <u>. </u> |
| | Output Voltage | LDO Enabled, Four Values LDO Disabled | | | 1.7 to 2.6 V _D ⁺ | | V V |
| | External Pin Capacitance | Required for LDO Stability | | 0.047 | 0.1 | 1 | μF |
| Digital Pin | Specifications | | | | | | |
| VIH | High Level Input Voltage | MUTE, CS, SDI, SCLK | | 1.55 | | | V |
| V _{IL} | Low Level Input Voltage | MUTE, CS, SDI, SCLK | | | | 0.8 | V |
| V _{IHYS} | Input Voltage Hysteresis | MUTE, CS, SDI, SCLK | | | 250 | | mV |
| | Input Current | MUTE, CS, SDI, SCLK | | | | ±1 | μA |
| I _{OH} | High Level Output Current | SDO and STAT, $V_{OH} = V_D^+ - 400 \text{mV}$ | | | -3.3 | -1.9 | mA |
| I _{OL} | Low Level Output Current | SDO and STAT, V _{OL} = 400mV | | 2.0 | 3.4 | | mA |
| | SDO Hi-Z Current | | | | | ±1 | μA |
| Digital Timi | ng Specifications (See Figure 7 and Figure 8) | - | | | | | <u> </u> |
| t _{CKH} | SCLK High Time | | | 25 | | | ns |
| t _{CKL} | SCLK Low Time | | | 25 | | | ns |
| t _{CSS} | CS Setup Time | | | 10 | | | ns |
| t _{CSH} | CS High Time | | | 10 | | | ns |
| t _{CS} | SDI to SCLK Setup Time | | | 6 | | | ns |
| t _{CH} | SDI to SCLK Hold Time | | | 6 | | | ns |
| t _{DO} | SCLK to SDO Time | To V _{IH} /V _{IL} /Hi-Z with 30pF Load | | | | 16 | ns |
| Power Supp | ly Voltages | | | | | | · |
| | V _{REF} ⁺ Supply Range | | | 3.15 | 3.3 | 3.45 | V |
| | V _D ⁺ Supply Range | | | 3.15 | 3.3 | 3.45 | V |
| | V _{RF} ⁺ Supply Range | | | 3.15 | 3.3 | 3.45 | V |
| | V _{VCO} ⁺ Supply Range | | | 3.15 | 3.3 | 3.45 | V |
| | V _{CP} ⁺ Supply Range | | | 3.15 | | 5.25 | V |
| Power Supp | ly Currents | - | | | | | |
| I _{DD} | V _D ⁺ Supply Current | Digital Inputs at Supply Levels, PDFN = 1 Digital Inputs at Supply Levels, Fractional Mode, f _{PFD} = 66.3MHz MHz, LDOV[1:0] = 3 | • | | 18.2 | 1500 22 | μA mA |
| I _{CC(5V)} | Sum V _{CP} ⁺ Supply Currents | I _{CP} = 11.2mA I _{CP} = 1.0mA PDALL = 1 | • | | 34 12 230 | 40 14 650 | mA mA μA |
| I _{CC(3.3V)} | Sum V _{REF} ⁺ , V _{RF} ⁺ , V _{VCO} ⁺ Supply Currents | $\begin{array}{l} {\sf RF} \mbox{ Muted, } {\sf OD}[2:0] = 1 \\ {\sf RF} \mbox{ Enabled, } {\sf RFO}[1:0] = 0, \mbox{ OD}[2:0] = 1 \\ {\sf RF} \mbox{ Enabled, } {\sf RFO}[1:0] = 3, \mbox{ OD}[2:0] = 1 \\ {\sf RF} \mbox{ Enabled, } {\sf RFO}[1:0] = 3, \mbox{ OD}[2:0] = 2 \\ {\sf RF} \mbox{ Enabled, } {\sf RFO}[1:0] = 3, \mbox{ OD}[2:0] = 3 \\ {\sf RF} \mbox{ Enabled, } {\sf RFO}[1:0] = 3, \mbox{ OD}[2:0] = 4 \mbox{ to } 6 \\ {\sf PDALL} = 1 \end{array}$ | • • • • | | 70.4 81.1 91.3 109.2 114.8 119.6 53 | 80 95 105 125 135 140 250 | mA mA mA mA mA mA μA |



ELECTRICAL CHARACTERISTICS

The • denotes the specifications which apply over the full operating junction temperature range, otherwise specifications are at $T_A = 25^{\circ}$ C. $V_{REF}^+ = V_D^+ = V_{RF}^+ = V_{VCO}^+ = 3.3$ V, $V_{CP}^+ = 5$ V unless otherwise specified (Note 2). All voltages are with respect to GND.

| SYMBOL | PARAMETER | CONDITIONS | MIN | ТҮР | MAX | UNITS |
|-------------------------|--|--|-----|-------|-----|----------|
| Phase Noise | and Spurious | | | | | <u> </u> |
| L _{MIN} | Output Phase Noise Floor (Note 5) | RF0[1:0] = 3, OD[2:0] = 1, f _{RF} = 6GHz | | -155 | | dBc/Hz |
| | | RF0[1:0] = 3, OD[2:0] = 2, f _{RF} = 3GHz | | -155 | | dBc/Hz |
| | | RF0[1:0] = 3, OD[2:0] = 3, f _{RF} = 2GHz | | -156 | | dBc/Hz |
| | | RF0[1:0] = 3, OD[2:0] = 4, f _{RF} = 1.5GHz | | -156 | | dBc/Hz |
| | | RF0[1:0] = 3, OD[2:0] = 5, f _{RF} = 1.2GHz | | -157 | | dBc/Hz |
| | | RF0[1:0] = 3, OD[2:0] = 6, f _{RF} = 1.0GHz | | -158 | | dBc/Hz |
| L _{NORM(INT)} | Integer Normalized In-Band Phase Noise Floor | INTN = 1, I _{CP} = 5.6mA (Notes 6, 7, 9) | | -226 | | dBc/Hz |
| L _{NORM(FRAC)} | Fractional Normalized In-Band Phase Noise Floor | INTN = 0, CPLE = 1, I _{CP} = 5.6mA (Notes 6, 7, 9) | | -225 | | dBc/Hz |
| L _{1/f} | Normalized In-Band 1/f Phase Noise | I _{CP} = 11.2mA (Notes 6, 10) | | -274 | | dBc/Hz |
| | In-Band Phase Noise Floor | Fractional Mode, CPLE = 1 (Notes 4, 6, 7, 10, 11) | | -109 | | dBc/Hz |
| | Integrated Phase Noise from 100Hz to 40MHz | Fractional Mode, CPLE = 1 (Notes 4, 7, 11) | | 0.076 | | °RMS |
| | Spurious | Fractional Mode, f _{OFFSET} = f _{PFD} , PLL Locked (Notes 4, 7, 11, 12) | | -97 | | dBc |

Note 1: Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

Note 2: The LTC6947I is guaranteed to meet specified performance limits over the full operating junction temperature range of -40°C to 105°C.

Note 3: For $0.9V < V(CP) < (V_{CP}^+ - 0.9V)$.

Note 4: VCO is Crystek CVC055C-2328-2536.

Note 5: f_{VCO} = 6GHz, f_{OFFSET} = 40MHz.

Note 6: Measured inside the loop bandwidth with the loop locked.

Note 7: Reference frequency supplied by Wenzel 501-04516, f_{REF} = 100MHz, $P_{REF} = 10dBm$.

Note 8: Reference frequency supplied by Wenzel 500-23571, f_{REF} = 61.44MHz, $P_{REF} = 10$ dBm.

Note 9: Output phase noise floor is calculated from normalized phase noise floor by $L_{OUT} = L_{NORM} + 10log_{10} (f_{PFD}) + 20log_{10} (f_{RF}/f_{PFD})$. Note 10: Output 1/f noise is calculated from normalized 1/f phase noise by $L_{OUT(1/f)} = L_{1/f} + 20log_{10} (f_{RF}) - 10log_{10} (f_{OFFSET}).$

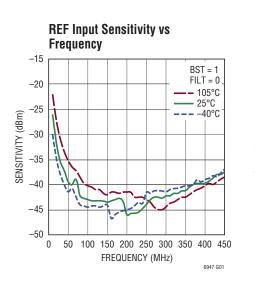
Note 11: I_{CP} = 5.6mA, f_{PFD} = 50MHz, FILT[1:0] = 0, Loop BW = 31kHz; $f_{RF} = 2415MHz$, $f_{VCO} = 2415MHz$.

Note 12: Measured using DC1846.

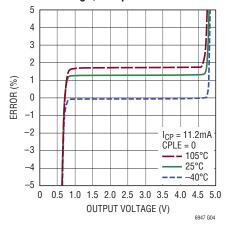
Note 13: VCO is RFMD UMX-918-D16-G.

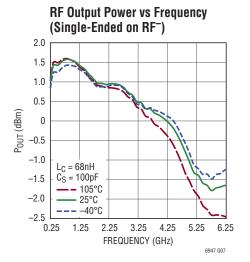


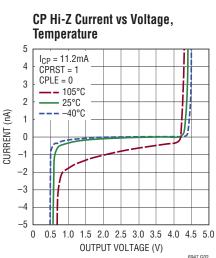
TYPICAL PERFORMANCE CHARACTERISTICS $T_A = 25^{\circ}C$. $V_{REF}^+ = V_{D}^+ = V_{RF}^+ = V_{VCO}^+ = 3.3V$, $V_{CP}^+ = 5V$, INTN = 0, DITHEN = 1, CPLE = 1, RF0[1:0] = 3, unless otherwise noted.



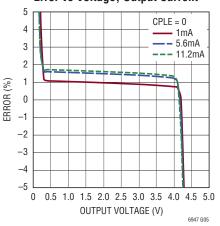
Charge Pump Sink Current Error vs Voltage, Temperature



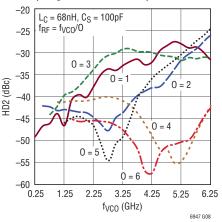




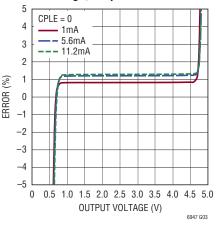
Charge Pump Source Current Error vs Voltage, Output Current



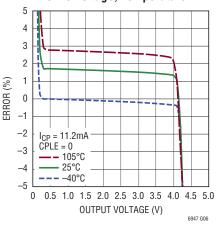
RF Output HD2 vs Output Divide (Single-Ended on RF⁻)



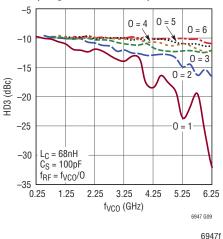
Charge Pump Sink Current Error vs Voltage, Output Current



Charge Pump Source Current Error vs Voltage, Temperature



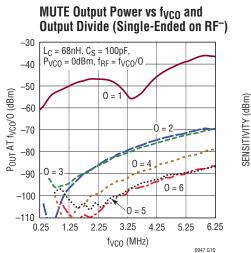
RF Output HD3 vs Output Divide (Single-Ended on RF⁻)

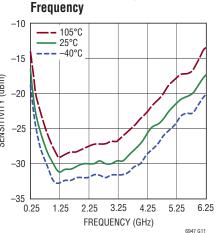




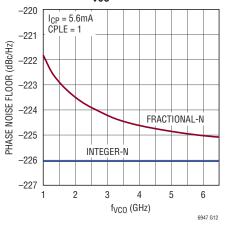
TYPICAL PERFORMANCE CHARACTERISTICS $T_A = 25^{\circ}C$. $V_{REF}^+ = V_{D}^+ = V_{RF}^+ = V_{VCO}^+ = 3.3V$, $V_{CP}^+ = 5V$, INTN = 0, DITHEN = 1, CPLE = 1, RF0[1:0] = 3, unless otherwise noted.

VCO Input Sensitivity vs

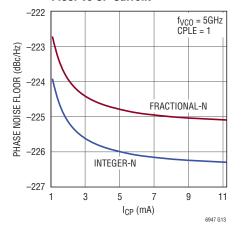




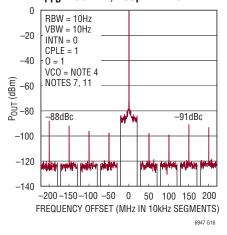
Normalized In-Band Phase Noise Floor vs fvco



Normalized In-Band Phase Noise Floor vs CP Current



Spurious Response $f_{BF} = 2415MHz, f_{BEF} = 100MHz,$ f_{PFD} = 50MHz, Loop BW = 31kHz

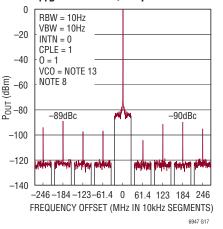


Downloaded from Arrow.com.

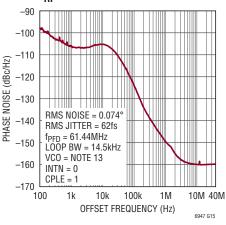
 $f_{BF} = 2415 MHz$ -90 -100 -110 PHASE NOISE (dBc/Hz) -120 -130 RMS NOISE = 0.076° RMS JITTER = 87fs -140 $f_{PFD} = 50MHz$ LOOP BW = 31kHz -150 VCO = NOTE 4 INTN = 0-160 CPLE = 1 NOTE 11 -170 100 1k 10k 100k 1M 10M 40M OFFSET FREQUENCY (Hz) 6947 G14

Closed-Loop Phase Noise

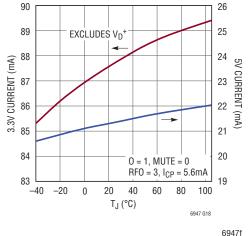
Spurious Response $f_{RF} = 3330MHz, f_{REF} = 61.44MHz,$ $f_{PFD} = 61.44$ MHz, Loop BW = 14.5kHz



Closed-Loop Phase Noise $f_{\rm RF} = 3330 MHz$

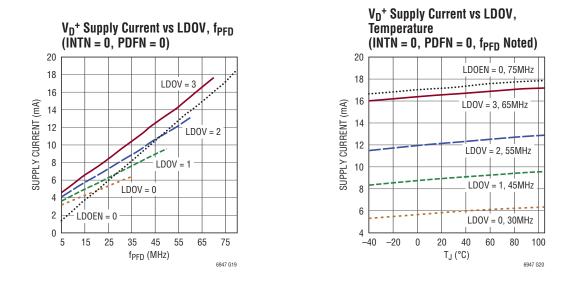


Supply Current vs Temperature



TYPICAL PERFORMANCE CHARACTERISTICS $T_A = 25^{\circ}C. V_{BEF}^+ = V_D^+ = V_{BF}^+ = V_{VCO}^+ = 3.3V,$

 V_{CP}^+ = 5V, INTN = 0, DITHEN = 1, CPLE = 1, RF0[1:0] = 3, unless otherwise noted.



PIN FUNCTIONS

REF⁺, **REF⁻** (**Pins 1, 28**): Reference Input Signals. This differential input is buffered with a low noise amplifier. which feeds the reference divider. They are self-biased and must be AC-coupled with 1µF capacitors. If used singleended with $V_{REF}^+ \leq 2.7 V_{P-P}$, bypass REF⁻ to GND with a 1µF capacitor. If used single-ended with $V_{REF}^+ > 2.7V_{P-P}$, bypass REF⁻ to GND with a 47pF capacitor.

STAT (Pin 2): Status Output. This signal is a configurable logical OR combination of the UNLOK, LOK, THI, and TLO status bits, programmable via the STATUS register. See the Operation section for more details.

CS (Pin 3): Serial Port Chip Select. This CMOS input initiates a serial port communication burst when driven low, ending the burst when driven back high. See the Operation section for more details.

SCLK (Pin 4): Serial Port Clock. This CMOS input clocks serial port input data on its rising edge. See the Operation section for more details.

SDI (Pin 5): Serial Port Data Input. The serial port uses this CMOS input for data. See the Operation section for more details.

SDO (Pin 6): Serial Port Data Output. This CMOS threestate output presents data from the serial port during a read communication burst. Optionally attach a resistor of >200k to GND to prevent a floating output. See the Applications Information section for more details.

LDO (Pin 7): $\Delta\Sigma$ Modulator LDO Bypass Pin. This pin should be bypassed directly to the ground plane using a low ESR (<0.8 Ω) 0.1 μ F ceramic capacitor as close to the pin as possible.

V_D⁺ (Pin 8): 3.15V to 3.45V Positive Supply Pin for Serial Port and $\Delta\Sigma$ Modulator Circuitry. This pin should be bypassed directly to the ground plane using a 0.1µF ceramic capacitor as close to the pin as possible.

MUTE (Pin 9): RF Mute. The CMOS active-low input mutes the RF[±] differential outputs while maintaining internal bias levels for quick response to de-assertion.

69471

PIN FUNCTIONS

GND (Pins 10, 17, 18, 19, 20, 21, 22, Exposed Pad Pin 29): Negative Power Supply (Ground). These pins should be tied directly to the ground plane with multiple vias for each pin. The package exposed pad must be soldered directly to the PCB land. The PCB land pattern should have multiple thermal vias to the ground plane for both low ground inductance and also low thermal resistance.

RF⁻, RF⁺ (Pins 11, 12): RF Output Signals. The VCO output divider is buffered and presented differentially on these pins. The outputs are open-collector, with 136Ω (typical) pull-up resistors tied to V_{RF}⁺ to aid impedance matching. If used single-ended, the unused output should be terminated to 50Ω . See the Applications Information section for more details on impedance matching.

 V_{RF}^+ (Pin 13): 3.15V to 3.45V Positive Supply Pin for RF Circuitry. This pin should be bypassed directly to the ground plane using a 0.01µF ceramic capacitor as close to the pin as possible.

BB (Pin 14): RF Reference Bypass. This output has a 2.5k resistance and must be bypassed with a 1μ F ceramic capacitor to GND. Do not couple this pin to any other signal.

VCO⁻, **VCO⁺** (**Pins 15, 16**): VCO Input Signals. The differential signal placed on these pins is buffered with a low noise amplifier and fed to the internal output and feedback dividers. These self-biased inputs must be AC-coupled

and present a single-ended 121Ω (typical) resistance to aid impedance matching. They may be used singleended by bypassing VCO⁻ to GND with a capacitor. See the Applications Information section for more details on impedance matching.

 V_{VCO}^+ (Pin 23): 3.15V to 3.45V Positive Supply Pin for VCO Circuitry. This pin should be bypassed directly to the ground plane using a 0.01µF ceramic capacitor as close to the pin as possible.

GND (24): Negative Power Supply (Ground). This pin is attached directly to the die attach paddle (DAP) and should be tied directly to the ground plane.

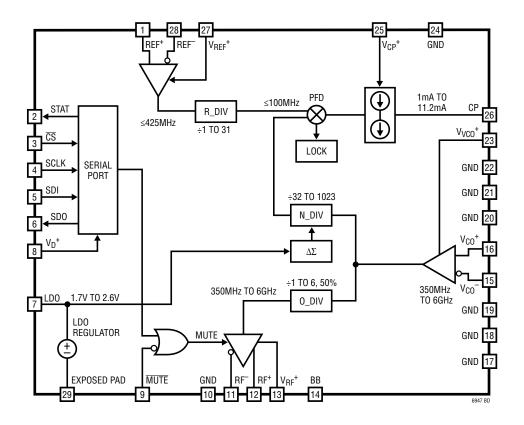
 V_{CP} + (Pin 25): 3.15V to 5.25V Positive Supply Pin for Charge Pump Circuitry. This pin should be bypassed directly to the ground plane using a 0.1µF ceramic capacitor as close to the pin as possible.

CP (Pin 26): Charge Pump Output. This bidirectional current output is normally connected to the external loop filter. See the Applications Information section for more details.

 V_{REF} ⁺ (Pin 27): 3.15V to 3.45V Positive Supply Pin for Reference Input Circuitry. This pin should be bypassed directly to the ground plane using a 0.1µF ceramic capacitor as close to the pin as possible.



BLOCK DIAGRAM





6947f

The LTC6947 is a high performance fractional-N PLL, and, combined with an external high performance VCO, can produce low noise LO signals up to 6GHz. The output frequency range may be further extended by utilizing the output divider. The device is able to achieve superior integrated phase noise by the combination of its extremely low in-band phase noise performance and the wide bandwidth allowed by its low spurious products.

The fractional-N feedback divider uses an advanced $\Delta\Sigma$ modulator, resulting in virtually no discrete modulator spurious tones. The modulator may be disabled if integer-N feedback is required.

REFERENCE INPUT BUFFER

The PLL's reference frequency is applied differentially on pins REF⁺ and REF⁻. These high impedance inputs are self-biased and must be AC-coupled with 1 μ F capacitors (see Figure 1 for a simplified schematic). Alternatively, the inputs may be used single-ended by applying the reference frequency at REF⁺ and bypassing REF⁻ to GND with a 1 μ F capacitor. If the single-ended signal is greater than 2.7V_{P-P}, then use a 47pF capacitor for the GND bypass.

A high quality signal must be applied to the REF[±] inputs

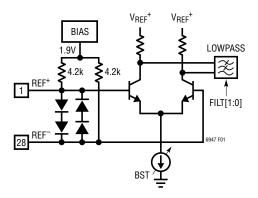


Figure 1. Simplified REF Interface Schematic

as they provide the frequency reference to the entire PLL. To achieve the part's in-band phase noise performance, apply a CW signal of at least 6dBm into 50Ω , or a square wave of at least $0.5V_{P-P}$ with slew rate of at least $40V/\mu$ s.

Additional options are available through serial port register hOB to further refine the application. Bits FILT[1:0] control the reference input buffer's lowpass filter, and should be set based upon f_{REF} to limit the reference's wideband noise. The FILT[1:0] bits must be set correctly to reach the L_{NORM} normalized in-band phase noise floor. See Table 1 for recommended settings.

| Table 1. | FILT[1:0] | Programming |
|----------|-----------|-------------|
|----------|-----------|-------------|

| FILT[1:0] | f _{REF} | | | |
|-----------|------------------|--|--|--|
| 3 | <20MHz | | | |
| 2 | NA | | | |
| 1 | 20MHz to 50MHz | | | |
| 0 | >50MHz | | | |

The BST bit should be set based upon the input signal level to prevent the reference input buffer from saturating. See Table 2 for recommended settings and the Applications Information section for programming examples.

Table 2. BST Programming

| BST | V _{REF} |
|-----|--------------------|
| 1 | <2V _{P-P} |
| 0 | ≥2V _{P-P} |

REFERENCE (R) DIVIDER

A 5-bit divider, R_DIV, is used to reduce the frequency seen at the PFD. Its divide ratio R may be set to any integer from 1 to 31, inclusive. Use the RD[4:0] bits found in registers h06 to directly program the R divide ratio. See the Applications Information section for the relationship between R and the f_{REF} , f_{PFD} , f_{VCO} , and f_{RF} frequencies.

PHASE/FREQUENCY DETECTOR (PFD)

The phase/frequency detector (PFD), in conjunction with the charge pump, produces source and sink current pulses proportional to the phase difference between the outputs of the R and N dividers. This action provides the necessary feedback to phase-lock the loop, forcing a phase alignment at the PFD's inputs. The PFD may be disabled with the CPRST bit which prevents UP and DOWN pulses from being produced. See Figure 2 for a simplified schematic of the PFD.



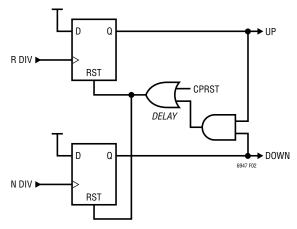


Figure 2. Simplified PFD Schematic

LOCK INDICATOR

The lock indicator uses internal signals from the PFD to measure phase coincidence between the R and N divider output signals. It is enabled by programming LKCT[1:0] in the serial port register hOC (see Table 5), and produces both LOCK and UNLOCK status flags, available through both the STAT output and serial port register hOO.

The user sets the phase difference lock window time t_{LWW} for a valid LOCK condition with the LKWIN[2:0] bits. When using the device as a fractional-N synthesizer (fractional mode), the $\Delta\Sigma$ modulator changes the instantaneous phase seen at the PFD on every R_DIV and N_DIV cycle. The maximum allowable time difference in this case depends upon both the VCO frequency f_{VCO} and also the charge pump linearization enable bit CPLE (see the Charge Pump Linearizer section for an explanation of this function). Table 3 contains recommended settings for LKWIN[2:0] when using the device in fractional mode. See the Applications Information section for examples.

| lable 3. LKWIN[| 2:0] Fraction | nal Mode | Program | ming |
|-----------------|---------------|----------|---------|------|
| 1 K/WIN[2.0] | t | fuer (CI | DIE_1) | fund |

| LKWIN[2:0] | t _{LWW} | f_{VCO} (CPLE = 1) | f _{VCO} (CPLE = 0) |
|------------|------------------|----------------------|-----------------------------|
| 0 | 5.0ns | ≥2.97GHz | ≥1.35GHz |
| 1 | 7.35ns | ≥2.00GHz | ≥919MHz |
| 2 | 10.7ns | ≥1.39GHz | ≥632MHz |
| 3 | 15.8ns | ≥941MHz | ≥428MHz |
| 4 | 23.0ns | ≥646MHz | ≥294MHz |
| 5 | 34.5ns | ≥431MHz | ≥196MHz |
| 6 | 50.5ns | ≥294MHz | ≥134MHz |
| 7 | 76.0ns | ≥196MHz | ≥89MHz |

When using the device as an integer-N synthesizer (integer mode), the phase difference seen at the PFD is minimized by the feedback of the PLL and no longer depends upon f_{VCO} . Table 4 contains recommended settings for different f_{PFD} frequencies when used in integer mode.

| LKWIN[2:0] | t _{LWW} | f _{PFD} | | | | |
|------------|------------------|------------------|--|--|--|--|
| 0 | 5.0ns | >6.8MHz | | | | |
| 1 | 7.35ns | ≤6.8MHz | | | | |
| 2 | 10.7ns | ≤4.7MHz | | | | |
| 3 | 15.8ns | ≤3.2MHz | | | | |
| 4 | 23.0ns | ≤2.2MHz | | | | |
| 5 | 34.5ns | ≤1.5MHz | | | | |
| 6 | 50.5ns | ≤1.0MHz | | | | |
| 7 | 76.0ns | ≤660kHz | | | | |
| | | | | | | |

Table 4. LKWIN[2:0] Integer Mode Programming

The PFD phase difference must be less than t_{LWW} for the COUNTS number of successive counts before the lock indicator asserts the LOCK flag. The LKCT[1:0] bits found in register hOC are used to set COUNTS depending upon the application. Set LKCT[1:0] = 0 to disable the lock indicator. See Table 5 for LKCT[1:0] programming and the Applications Information section for examples.

| Table S | 5. LK | CT[1:0] | Programming |
|---------|-------|---------|-------------|
|---------|-------|---------|-------------|

| COUNTS |
|-------------------------|
| Lock Indicator Disabled |
| 32 |
| 256 |
| 2048 |
| |

When the PFD phase difference is greater than t_{LWW} , the lock indicator immediately asserts the UNLOCK status flag and clears the LOCK flag, indicating an out-of-lock condition. The UNLOCK flag is immediately de-asserted when the phase difference is less than t_{LWW} . See Figure 3 below for more details.

Note that f_{REF} must be present for the LOCK and UNLOCK flags to properly assert and clear.

CHARGE PUMP

The charge pump, controlled by the PFD, forces sink (DOWN) or source (UP) current pulses onto the CP pin,

6947f





OPERATION +tLWW PHASE DIFFERENCE 0 -tLWW UNLOCK FLAG LOCK FLAG -t = COUNTS/fpFD -ture -tur

Figure 3. UNLOCK and LOCK Timing

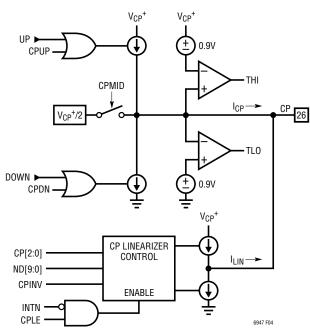


Figure 4. Simplified Charge Pump Schematic

which should be connected to an appropriate loop filter. See Figure 4 for a simplified schematic of the charge pump.

The output current magnitude I_{CP} may be set from 1mA to 11.2mA using the CP[2:0] bits found in serial port register hOC. A larger I_{CP} can result in lower in-band noise due to the lower impedance of the loop filter components, although currents larger than 5.6mA typically cause worse spurious performance. See Table 6 for programming specifics and the Applications Information section for loop filter examples.

| Table | 6. | CP[2:0] | Programming |
|-------|----|---------|-------------|
|-------|----|---------|-------------|

| CP[2:0] | I _{CP} | | |
|---------|-----------------|--|--|
| 0 | 1.0mA | | |
| 1 | 1.4mA | | |
| 2 | 2.0mA | | |
| 3 | 2.8mA | | |
| 4 | 4.0mA | | |
| 5 | 5.6mA | | |
| 6 | 8.0mA | | |
| 7 | 11.2mA | | |
| | | | |

The CPINV bit found in register hOD should be set for applications requiring signal inversion from the PFD, such as for external loops using an op amp. A passive loop filter as shown in Figure 14 requires CPINV = 0. An active loop filter as shown in Figure 15 requires CPINV = 1 for a positive K_{VCO} .

Charge Pump Functions

The charge pump contains additional features to aid in system startup. See Table 7 for a summary.

 Table 7. Charge Pump Function Bit Descriptions

| BIT | DESCRIPTION | | |
|--------|----------------------------------|--|--|
| CPCHI | Enable High Voltage Output Clamp | | |
| CPCLO | Enable Low Voltage Output Clamp | | |
| CPDN | Force Sink Current | | |
| CPINV | Invert PFD Phase | | |
| CPLE | Linearizer Enable | | |
| CPMID | Enable Mid-Voltage Bias | | |
| CPRST | Reset PFD | | |
| CPUP | Force Source Current | | |
| CPWIDE | Extend Current Pulse Width | | |
| THI | High Voltage Clamp Flag | | |
| TLO | Low Voltage Clamp Flag | | |
| | | | |

The CPCHI and CPCLO bits found in register hOD enable the high and low voltage clamps, respectively. When CPCHI is enabled and the CP pin voltage exceeds approximately $V_{CP}^+ - 0.9V$, the THI status flag is set, and the charge pump sourcing current is disabled. Alternately, when CPCLO is enabled and the CP pin voltage is less than approximately 0.9V, the TLO status flag is set, and the charge pump sinking current is disabled. See Figure 4 for a simplified schematic.

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The CPMID bit also found in register h0D enables a resistive $V_{CP}^{+/2}$ output bias which may be used to pre-bias troublesome loop filters into a valid voltage range. When using CPMID, it is recommended to also assert the CPRST bit, forcing a PFD reset. Both CPMID and CPRST must be set to 0 for normal operation.

The CPUP and CPDN bits force a constant I_{CP} source or sink current, respectively, on the CP pin. The CPRST bit may also be used in conjunction with the CPUP and CPDN bits, allowing a pre-charge of the loop to a known state, if required. CPUP, CPDN, and CPRST must be set to 0 to allow the loop to lock.

The CPWIDE bit extends the charge pump output current pulse width by increasing the PFD reset path's delay value (see Figure 2). CPWIDE is normally set to 0.

Charge Pump Linearizer

When the LTC6947 is operated in fractional mode, the charge pump's current output versus its phase stimulus (its gain linearity) must be extremely accurate. The CP gain linearizer automatically adds a correction current I_{LIN} to minimize the charge pump's impact on in-band phase noise and spurious products during fractional operation.

The CP gain linearizer is enabled by setting CPLE = 1. It is automatically disabled when in integer mode. CPLE should be set to 0 if CPRST or CPMID are asserted to prevent the linearizer from producing unintended currents.

VCO INPUT BUFFER

The VCO frequency is applied differentially on pins VCO⁺ and VCO⁻. The inputs are self-biased and must be AC-coupled. Alternatively, the inputs may be used single-ended by applying the VCO frequency at VCO⁺ and bypassing VCO⁻ to GND with a capacitor. Each input provides a single-ended 121 Ω resistance to aid in impedance matching at high frequencies. See the Applications Information section for matching guidelines.

The BB pin is used to bias internal VCO buffer circuitry. The BB pin has a 2k output resistance and should be bypassed with a 1μ F ceramic capacitor to GND, giving a time constant of 2ms. Stable bias voltages are achieved after approximately 3 time constants following power-up.

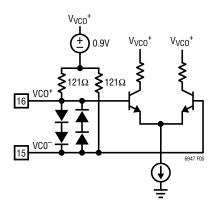


Figure 5. Simplified VCO Interface Schematic

VCO (N) DIVIDER

The 10-bit N divider provides the feedback from the VCO to the PFD. Its divide ratio N is restricted to any integer from 35 to 1019, inclusive, when in fractional mode. The divide ratio may be programmed from 32 to 1023, inclusive, when in integer mode. Use the ND[9:0] bits found in registers h06 and h07 to directly program the N divide ratio. See the Applications Information section for the relationship between N and the f_{REF} , f_{PFD} , f_{VCO} , and f_{RF} frequencies.

$\Delta\Sigma \text{ MODULATOR}$

The $\Delta\Sigma$ modulator changes the N divider's ratio each PFD cycle to achieve an average fractional divide ratio. The fractional numerator NUM[17:0] is programmable from 1 to 262143, or $2^{18} - 1$. The fractional denominator is fixed at 262144 (or 2^{18}), with the resulting fractional ratio F given by Equation 3. See the Applications Information section for the relationship between NUM, F, and the f_{REF} , f_{PFD} , f_{VCO} , and f_{RF} frequencies.

The $\Delta\Sigma$ modulator uses digital signal processing (DSP) techniques to achieve an average fractional divide ratio. The modulator is clocked at the f_{PFD} rate. This process produces output modulation noise known as quantization noise with a highpass frequency response. The external lowpass loop filter is used to filter this quantization noise to a level beneath the phase noise of the VCO. This prevents the noise from contributing to the overall phase noise of the system. The loop filter must be designed to adequately filter the quantization noise.

The oversampling ratio OSR is defined as the ratio of the $\Delta\Sigma$ modulator clock frequency f_{PFD} to the loop bandwidth $_{^{6947f}}$



BW of the PLL (see Equation 10). See the Applications Information section for guidelines concerning the OSR and the loop filter.

When the desired output frequency is such that the needed NUM value is 0, the LTC6947 should be operated in integer mode (INTN = 1). In integer mode, the modulator is placed in standby, with all blocks still powered up, thus allowing it to resume fractional operation immediately.

Enable numerator dither mode (DITHEN = 1) to further reduce spurious produced by the modulator. Dither has no measurable impact on in-band phase noise, and is enabled by default. See Table 8 for a complete list of modulator bit descriptions.

Modulator Reset

To achieve consistent spurious performance, the modulator DSP circuitry should be re-initialized by setting RSTFN = 1 whenever NUM[17:0] is changed. Setting AUTORST = 1 causes the RSTFN bit to be set automatically whenever any of serial port registers h05 through h0A are written. When AUTORST is enabled, there is no need for a separate register write to set the RSTFN bit. See Table 8 for a summary of the modulator bits.

Table 8. Fractional Modulator Bit Descriptions

| BIT | DESCRIPTION |
|---------|---|
| AUTORST | Automatically Reset Modulator when Registers h05 to h0A Are Written |
| DITHEN | Enable Fractional Numerator Dither |
| INTN | Integer Mode; Fractional Modulator Placed in Standby |
| RSTFN | Reset Modulator (Auto Clears) |
| SEED | Seed Value for Pseudorandom Dither Algorithm |

LDO REGULATOR

The adjustable low dropout (LDO) regulator supplies power to the $\Delta\Sigma$ modulator. The regulator requires a low ESR ceramic capacitor (ESR < 0.8 Ω) connected to the LDO pin (pin 7) for stability. The capacitor value may range from 0.047 μ F to 1 μ F.

The LDO voltage is set using the LDOV[1:0] bits, and should be chosen based upon the f_{PFD} frequency to minimize power and spurious. The regulator is disabled by setting

the LDOEN bit to 0. When disabled by using either the LDOEN or PDFN bits, the LDO pin is connected directly to V_D^+ using a low impedance switch, and the regulator is powered down. See Table 9 for programming details.

Table 9. LDOV[1:0] and LDOEN Programming

| LDOV[1:0] | LDOEN | V(LDO) | f _{PFD} |
|-----------|-------|------------------|------------------|
| 0 | 1 | 1.7V | ≤34.3MHz |
| 1 | 1 | 2.0V | ≤45.9MHz |
| 2 | 1 | 2.3V | ≤56.1MHz |
| 3 | 1 | 2.6V | ≤66.3MHz |
| Х | 0 | V _D + | ≤76.1MHz |

OUTPUT (0) DIVIDER

The 3-bit O divider can reduce the frequency from the VCO to extend the output frequency range. Its divide ratio O may be set to any integer from 1 to 6, inclusive, outputting a 50% duty cycle even with odd divide values. Use the OD[2:0] bits found in register hOB to directly program the O divide ratio. See the Applications Information section for the relationship between O and the f_{REF} , f_{PFD} , f_{VCO} , and f_{RF} frequencies.

RF OUTPUT BUFFER

The low noise, differential output buffer produces a differential output power of -4.3dBm to +4.5dBm, settable with bits RFO[1:0] according to Table 10. The outputs may be combined externally, or used individually. Terminate any unused output with a 50 Ω resistor to V_{RF}⁺.

Table 10. RF0[1:0] Programming

| RF0[1:0} | P _{RF} (DIFFERENTIAL) | P _{RF} (SINGLE-ENDED) |
|----------|--------------------------------|--------------------------------|
| 0 | -4.3dBm | -7.3dBm |
| 1 | -1.5dBm | -4.5dBm |
| 2 | 1.6dBm | -1.4dBm |
| 3 | 4.5dBm | 1.5dBm |

Each output is open-collector with 136 Ω pull-up resistors to V_{RF}⁺, easing impedance matching at high frequencies. See Figure 6 for circuit details and the Applications Information section for matching guidelines. The buffer may be muted with either the OMUTE bit, found in register h02, or by forcing the MUTE input low.



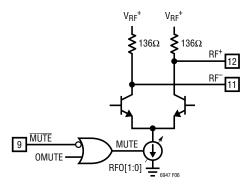


Figure 6. Simplified RF Interface Schematic

SERIAL PORT

The SPI-compatible serial port provides control and monitoring functionality. A configurable status output STAT gives additional instant monitoring.

Communication Sequence

The serial bus is comprised of \overline{CS} , SCLK, SDI, and SDO. Data transfers to the part are accomplished by the serial bus master device first taking \overline{CS} low to enable the LTC6947's port. Input data applied on SDI is clocked on the rising edge of SCLK, with all transfers *MSB first*. The communication burst is terminated by the serial bus master returning $\overline{\text{CS}}$ high. See Figure 7 for details.

Data is read from the part during a communication burst using SDO. Readback may be multidrop (more than one LTC6947 connected in parallel on the serial bus), as SDO is three-stated (Hi-Z) when $\overline{CS} = 1$, or when data is not being read from the part. *If the LTC6947 is not used in a multidrop configuration, or if the serial port master is not capable of setting the SDO line level between read sequences, it is recommended to attach a high value resistor of greater than 200k between SDO and GND to ensure the line returns to a known level during Hi-Z states.* See Figure 8 for details.

Single Byte Transfers

The serial port is arranged as a simple memory map, with status and control available in 15 byte-wide registers. All data bursts are comprised of at least two bytes. The seven most significant bits of the first byte are the register address, with an LSB of 1 indicating a read from the part, and LSB of 0 indicating a write to the part. The subsequent byte, or bytes, is data from/to the specified register address. See Figure 9 for an example of a detailed write sequence, and Figure 10 for a read sequence.

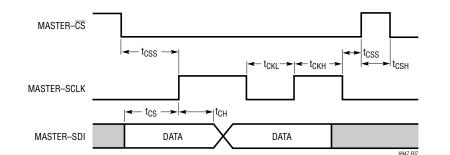


Figure 7. Serial Port Write Timing Diagram

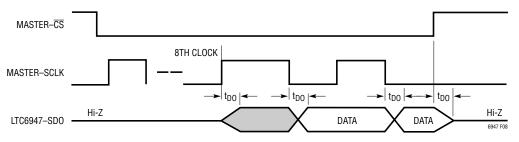


Figure 8. Serial Port Read Timing Diagram



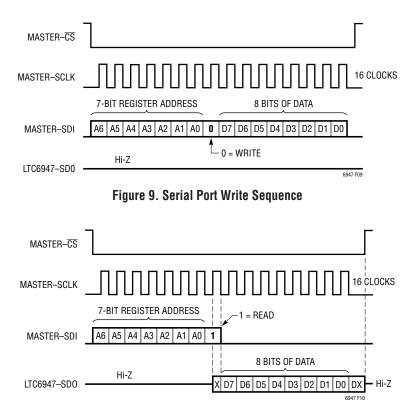


Figure 10. Serial Port Read Sequence

Figure 11 shows an example of two write communication bursts. The first byte of the first burst sent from the serial bus master on SDI contains the destination register address (Addr0) and an LSB of 0 indicating a write. The next byte is the data intended for the register at address Addr0. \overline{CS} is then taken high to terminate the transfer. The first byte of the second burst contains the destination register address (Addr1) and an LSB indicating a write. The next byte on SDI is the data intended for the register at address Addr1. \overline{CS} is then taken high to terminate the transfer.

Multiple Byte Transfers

More efficient data transfer of multiple bytes is accomplished by using the LTC6947's register address autoincrement feature as shown in Figure 12. The serial port master sends the destination register address in the first byte and its data in the second byte as before, but continues sending bytes destined for subsequent registers. Byte 1's address is Addr0+1, Byte 2's address is Addr0+2, and so on. If the register address pointer attempts to increment past 14 (h0E), it is automatically reset to 0. An example of an auto-increment read from the part is shown in Figure 13. The first byte of the burst sent from the serial bus master on SDI contains the destination register address (Addr0) and an LSB of 1 indicating a read. Once the LTC6947 detects a read burst, it takes SDO out of the Hi-Z condition and sends data bytes sequentially, beginning with data from register Addr0. The part ignores all other data on SDI until the end of the burst.

Multidrop Configuration

Several LTC6947s may share the serial bus. In this multidrop configuration, SCLK, SDI, and SDO are common between all parts. The serial bus master must use a separate \overline{CS} for each LTC6947 and ensure that only one device has \overline{CS} asserted at any time. It is recommended to attach a high value resistor to SDO to ensure the line returns to a known level during Hi-Z states.

Serial Port Registers

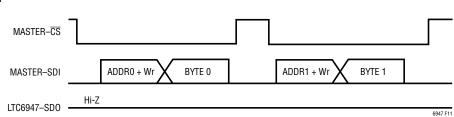
The memory map of the LTC6947 may be found in Table 11, with detailed bit descriptions found in Table 12. The



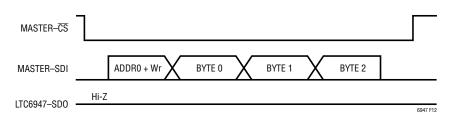
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LTC6947

OPERATION









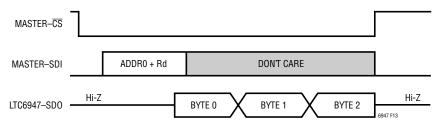


Figure 13. Serial Port Auto-increment Read

| ADDR | MSB | [6] | [5] | [4] | [3] | [2] | [1] | LSB | R/W | DEFAULT |
|------|----------|----------|----------|---------|---------|---------|---------|---------|-----|---------|
| h00 | * | * | UNLOCK | * | * | LOCK | THI | TL0 | R | |
| h01 | * | * | x[5] | * | * | x[2] | x[1] | x[0] | R/W | h04 |
| h02 | PDALL | PDPLL | * | PDOUT | PDFN | * | OMUTE | POR | R/W | h06 |
| h03 | * | * | * | * | * | AUTORST | DITHEN | INTN | R/W | h06 |
| h04 | * | * | * | * | CPLE | LDOEN | LDOV[1] | LDOV[0] | R/W | h07 |
| h05 | SEED[7] | SEED[6] | SEED[5] | SEED[4] | SEED[3] | SEED[2] | SEED[1] | SEED[0] | R/W | h11 |
| h06 | RD[4] | RD[3] | RD[2] | RD[1] | RD[0] | * | ND[9] | ND[8] | R/W | h08 |
| h07 | ND[7] | ND[6] | ND[5] | ND[4] | ND[3] | ND[2] | ND[1] | ND[0] | R/W | hFA |
| h08 | * | * | NUM[17] | NUM[16] | NUM[15] | NUM[14] | NUM[13] | NUM[12] | R/W | h3F |
| h09 | NUM[11] | NUM[10] | NUM[9] | NUM[8] | NUM[7] | NUM[6] | NUM[5] | NUM[4] | R/W | hFF |
| h0A | NUM[3] | NUM[2] | NUM[1] | NUM[0] | * | * | RSTFN | * | R/W | hF0 |
| h0B | BST | FILT[1] | FILT[0] | RF0[1] | RF0[0] | OD[2] | OD[1] | OD[0] | R/W | hF9 |
| h0C | LKWIN[2] | LKWIN[1] | LKWIN[0] | LKCT[1] | LKCT[0] | CP[2] | CP[1] | CP[0] | R/W | h4F |
| h0D | CPCHI | CPCLO | CPMID | CPINV | CPWIDE | CPRST | CPUP | CPDN | R/W | hE4 |
| h0E | REV[3] | REV[2] | REV[1] | REV[0] | PART[3] | PART[2] | PART[1] | PART[0] | R | hxx† |

Table 11. Serial Port Register Contents

*unused [†]varies depending on version





Table 12. Serial Port Register Bit Field Summary

| BITS | DESCRIPTION | DEFAULT |
|------------|---|---------|
| AUTORST | Reset Modulator Whenever Registers H05 to h0A Are Written | 1 |
| BST | REF Buffer Boost Current | 1 |
| CP[2:0] | CP Output Current | h7 |
| CPCHI | Enable Hi-Voltage CP Output Clamp | 1 |
| CPCLO | Enable Low-Voltage CP Output Clamp | 1 |
| CPDN | Force CP Pump Down | 0 |
| CPINV | Invert CP Phase | 0 |
| CPLE | CP Linearizer Enable | 0 |
| CPMID | CP Bias to Mid-Rail | 1 |
| CPRST | CP Tri-State | 1 |
| CPUP | Force CP Pump Up | 0 |
| CPWIDE | Extend CP Pulse Width | 0 |
| DITHEN | Enable Fractional Numerator Dither | 1 |
| FILT[1:0] | REF Input Buffer Filter | h3 |
| INTN | Integer Mode; Fractional Modulator Placed in Standby | 0 |
| LDOEN | LDO Enable | 1 |
| LDOV[1:0] | LDO Voltage | h3 |
| LKCT[1:0] | PLL Lock Cycle Count | h1 |
| LKWIN[2:0] | PLL Lock Indicator Window | h2 |
| LOCK | PLL Lock Indicator Flag | |
| ND[9:0] | N Divider Value (ND[9:0] \ge 32) | h0FA |
| NUM[17:0] | Fractional Numerator Value | h3FFF |
| OD[2:0] | Output Divider Value (0 < OD[2:0] < 7) | h1 |
| OMUTE | Mutes RF Output | 1 |
| PART[3:0] | Part Code | h0 |
| PDALL | Full Chip Powerdown | 0 |
| PDFN | Powers Down LDO and Modulator Clock | 0 |
| PDOUT | Powers Down N_DIV, RF Output Buffer | 0 |
| PDPLL | Powers Down REF, R_DIV, PFD, CPUMP | 0 |
| POR | Force Power-On-Reset | 0 |
| RD[4:0] | R Divider Value (RD[4:0] > 0) | h001 |
| REV[3:0] | Rev Code | h1 |
| RF0[1:0] | RF Output Power | h3 |
| RSTFN | Force Modulator Reset (Auto Clears) | 0 |
| SEED[7:0] | Modulator Dither Seed Value | h11 |
| THI | CP Clamp High Flag | |
| TL0 | CP Clamp Low Flag | |
| UNLOK | PLL Unlock Flag | |
| x[5,2:0] | STAT Output OR Mask | h04 |

register address shown in hexadecimal format under the ADDR column is used to specify each register. Each register is denoted as either read-only (R) or read-write (R/W). The register's default value on device power-up or after a reset is shown at the right.

The read-only register at address h00 is used to determine different status flags. These flags may be instantly output on the STAT pin by configuring register h01. See the STAT Output section for more information.

The read-only register at address h0E is a ROM byte for device identification.

STAT Output

The STAT output pin is configured with the x[5,2:0] bits of register h01. These bits are used to bit-wise mask, or enable, the corresponding status flags of status register h00, according to Equation 1. The result of this bit-wise Boolean operation is then output on the STAT pin.

STAT = OR (Reg00[5,2:0] AND Reg01[5,2:0]) (1)

or, expanded,

STAT = (UNLOCK AND x[5]) OR (LOCK AND x[2]) OR (THI AND x[1]) OR (TLO AND x[0])

For example, if the application requires STAT to go high whenever the LOCK or THI flags are set, then x[2] and x[1] should be set to 1, giving a register value of h06.

Block Power-Down Control

The LTC6947's power-down control bits are located in register h02, described in Table 12. Different portions of the device may be powered down independently. *Care must be taken with the LSB of the register, the POR (power-on-reset) bit. When written to a 1, this bit forces a full reset of the part's digital circuitry to its power-up default state.*



INTRODUCTION

A PLL is a complex feedback system that may conceptually be considered a frequency multiplier. The system multiplies the frequency input at REF[±] and outputs a higher frequency at RF[±]. The PFD, charge pump, N divider, external VCO, and loop filter form a feedback loop to accurately control the output frequency (see Figure 14).

The external loop filter is used to set the PLL's loop bandwidth BW. Lower bandwidths generally have better spurious performance and lower $\Delta\Sigma$ modulator quantization noise. Higher bandwidths can have better total integrated phase noise.

The R and O divider and input frequency f_{REF} are used to set the output frequency resolution. When in fractional mode, the $\Delta\Sigma$ modulator changes the N divider's ratio each PFD cycle to produce an average fractional divide ratio. This achieves a much smaller frequency resolution for a given f_{PFD} as compared to integer mode.

OUTPUT FREQUENCY

When the loop is locked, the frequency f_{VCO} (in Hz) produced at the output of the VCO is determined by the reference frequency f_{REF} , the R and N divider values, and the fractional value F, given by Equation 2:

$$f_{VC0} = \frac{f_{REF} \bullet (N+F)}{R}$$
(2)

where the fractional value F is given by Equation 3:

$$F = \frac{NUM}{2^{18}}$$
(3)

NUM is programmable from 1 to 262143, or 2^{18} – 1. When using the LTC6947 in integer mode, F = 0.

The PFD frequency f_{PFD} is given by the following equation:

$$f_{PFD} = \frac{f_{REF}}{R}$$
(4)

and f_{VCO} may be alternatively expressed as:

$$f_{VCO} = f_{PFD} \bullet (N + F)$$
(5)

The output frequency f_{RF} produced at the output of the O divider is given by Equation 6:

$$f_{\rm RF} = \frac{f_{\rm VCO}}{0} \tag{6}$$

Using the above equations, the minimum output frequency resolution $f_{\text{STEP}(\text{MIN})}$ produced by a unit change in the fractional numerator NUM while in fractional mode is given by Equation 7:

$$f_{\text{STEP(MIN)}} = \frac{f_{\text{REF}}}{R \cdot 0 \cdot 2^{18}}$$
(7)

Alternatively, to calculate the numerator step size NUM_{STEP} needed to produce a given frequency step $f_{\text{STEP}(\text{FRAC})}$, use Equation 8:

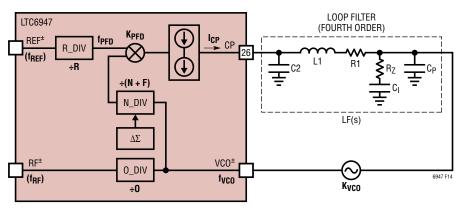


Figure 14. PLL Loop Diagram



$$NUM_{STEP} = \frac{f_{STEP(FRAC)} \bullet R \bullet O \bullet 2^{18}}{f_{REF}}$$
(8)

The output frequency resolution $f_{\text{STEP}(\text{INT})}$ produced by a unit change in N while in integer mode is given by Equation 9:

$$f_{\text{STEP(INT)}} = \frac{f_{\text{REF}}}{R \cdot 0}$$
(9)

LOOP FILTER DESIGN

A stable PLL system requires care in designing the external loop filter. The Linear Technology FracNWizard application, available from www.linear.com, aids in design and simulation of the complete system.

The loop design should use the following algorithm:

- Determine the output frequency f_{RF} and frequency step size f_{STEP} based on application requirements. Using Equations 2, 4, 6, and 7, change f_{REF}, N, R, and 0 until the application frequency constraints are met. Use the minimum R value that still satisfies the constraints.
- Select the open loop bandwidth BW constrained by f_{PFD} and oversampling ratio OSR. The OSR is the ratio of f_{PFD} to BW (see Equation 10):

$$OSR = \frac{f_{PFD}}{BW}$$
(10)

or

$$\mathsf{BW} = \frac{\mathsf{f}_{\mathsf{PFD}}}{\mathsf{OSR}}$$

where BW and f_{PFD} are in Hz.

A stable loop, both in integer and fractional mode, requires that the OSR is greater than or equal to 10. Further, in fractional mode, OSR must be high enough to allow the loop filter to reduce modulator quantization noise to an acceptable level.

Choosing a higher-order loop filter when using the $\Delta\Sigma$ modulator allows for a smaller OSR, and thus a larger

loop bandwidth. Linear Technology's FracNWizard helps choose the appropriate OSR and BW values.

3) Select loop filter component R_Z and charge pump current I_{CP} based on BW and the VCO gain factor, K_{VCO}.
 BW (in Hz) is approximated by the following equation:

$$\mathsf{BW} \cong \frac{\mathsf{I}_{\mathsf{CP}} \bullet \mathsf{R}_{\mathsf{Z}} \bullet \mathsf{K}_{\mathsf{VCO}}}{2 \bullet \pi \bullet \mathsf{N}} \tag{11}$$

or

$$R_{Z} = \frac{2 \bullet \pi \bullet BW \bullet N}{I_{CP} \bullet K_{VCO}}$$

where K_{VCO} is in Hz/V, I_{CP} is in Amps, and R_Z is in Ohms. K_{VCO} is the VCO's frequency tuning sensitivity, and may be determined from the VCO specifications. Use $I_{CP} = 5.6$ mA to lower in-band noise unless component values force a lower setting.

 Select loop filter components C_I and C_P based on BW and R_Z. A reliable second-order loop filter design can be achieved by using the following equations for the loop capacitors (in Farads).

$$C_{I} = \frac{3.5}{2 \bullet \pi \bullet BW \bullet R_{Z}}$$
(12)

$$C_{P} = \frac{1}{7 \bullet \pi \bullet BW \bullet R_{Z}}$$
(13)

Use FracNWizard to aid in the design of higher order loop filters.

LOOP FILTERS USING AN OP AMP

Some VCO tune voltage ranges are greater than the LTC6947's charge pump voltage range. An active loop filter using an op amp can increase the tuning voltage range. To maintain the LTC6947's high performance, care must be given to picking an appropriate op amp.

The op amp input common mode voltage should be biased within the LTC6947 charge pump's voltage range, while its output voltage should achieve the VCO tuning range. See Figure 15 for an example op amp loop filter.



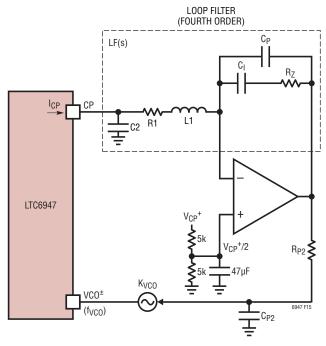


Figure 15. Op Amp Loop Filter

The op amp's input bias current is supplied by the charge pump; minimizing this current keeps spurs related to f_{PFD} low. The input bias current should be less than the charge pump leakage (found in the Electrical Characteristics section) to avoid increasing spurious products.

Op amp noise sources are highpass filtered by the PLL loop filter and should be kept at a minimum, as their effect raises the total system phase noise beginning near the loop bandwidth. Choose a low noise op amp whose input-referred voltage noise is less than the thermal noise of R_Z . Additionally, the gain-bandwidth of the op amp should be at least 20 times the loop bandwidth to limit phase margin degradation. The LT®1678 is an op amp that works very well in most applications.

An additional R-C lowpass filter (formed by R_{P2} and C_{P2} in Figure 15) connected at the input of the VCO will limit the op amp output noise sources. The bandwidth of this filter should be approximately 15 to 20 times the PLL loop bandwidth to limit loop phase margin degradation. R_{P2} should be small (preferably less than R_2) to minimize its noise impact on the loop. However, picking too small of a value can make the op amp unstable as it has to drive the capacitor in this filter.

DESIGN AND PROGRAMMING EXAMPLE

This programming example uses the DC1846 with the LTC6947. Assume the following parameters of interest:

 $f_{REF} = 100MHz$ at 7dBm into 50 Ω $f_{STEP} = 50kHz$ $f_{RF} = 2415.15MHz$ $f_{VCO} = 2328MHz$ to 2536MHz $K_{VCO} = 78MHz/V$ $L_{M(VCO)} = -127dBc/Hz$ at 100kHz offset

Determining Divider Values

Following the Loop Filter Design algorithm, first determine all the divider values. The maximum f_{PFD} while in fractional mode is less than 100MHz, so R must be greater than 1. Further, the minimum N value in fractional mode is 35, setting the lower limit on R:

R = 2

Then, using Equations 4 and 6, calculate the following values:

 $f_{PFD} = 50MHz$

Then using Equation 5:

$$N + F = \frac{2415.15MHz}{50MHz} = 48.303$$

Therefore:

Then, from Equation 3,

NUM = 0.303 • 2¹⁸ = 79430

Selecting Filter Type and Loop Bandwidth

The next step in the algorithm is choosing the open loop bandwidth. Select the minimum bandwidth resulting from the below constraints.

1) The OSR must be at least 10 (sets absolute maximum BW).

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For more information www.linear.com/LTC6947



- 2) The integrated phase noise due to thermal noise should be minimized, neglecting any modulator noise.
- 3) However, the loop bandwidth must also be narrow enough to adequately filter the modulator's quantization noise.

FracNWizard reports loop bandwidths resulting from each of the above constraints. The quantization noise constrained results vary according to the shape of the external loop filter. FracNWizard reports an optimal bandwidth for several filter types.

FracNWizard reports the thermal noise optimized loop bandwidth is 31.6kHz. Filter 2 (third order response) has a quantization noise constrained BW of 56.2kHz, making it a good choice. Select Filter 2 and use the smaller of the two bandwidths (31.6kHz) for optimal integrated phase noise. Use Equation 10 to calculate OSR:

$$OSR = \frac{50MHz}{31.6kHz} = 1582$$

Loop Filter Component Selection

Now set loop filter resistor R_Z and charge pump current $I_{CP}.$ Using an I_{CP} of 5.6mA and the specified K_{VCO} of 78MHz/V, FracNWizard uses Equation 11 to determine R_Z :

$$R_{Z} = \frac{2 \bullet \pi \bullet 31.6 k \bullet 48}{5.6 m \bullet 78 M}$$
$$R_{Z} = 21.8 \Omega$$

For the 3rd order Filter 2, FracNWizard uses modified Equations 7 and 8 to calculate C_I , C_P :

$$C_{I} = \frac{4}{2 \bullet \pi \bullet 31.6k \bullet 21.8} = 924nF$$
$$C_{P} = \frac{1}{10.5 \bullet \pi \bullet 31.6k \bullet 21.8} = 44nF$$

FracNWizard calculates R1 and C2 to be:

R1 = 21.8Ω

$$C2 = 29.3 nF$$

These values are used with the schematic of Figure 15 (with L1 unused).

Status Output Programming

This example will use the STAT pin to indicate the LTC6947 is locked. Program x[2] = 1 to force the STAT pin high whenever the LOCK flag asserts:

Reg01 = h04

Power Register Programming

For correct PLL operation all internal blocks should be enabled. OMUTE may remain asserted (or the MUTE pin held low) until programming is complete. For OMUTE = 1:

Reg02 = h02

AUTORST Programming

Set the modulator auto reset option (AUTORST = 1) and the $\Delta\Sigma$ modulator modes (DITHEN = 1, INTN = 0) at the same time:

Reg03 = h06

The $\Delta\Sigma$ modulator will be reset at the end of the SPI write communication burst (assuming an auto-increment write is used to write all registers).

LDO Programming

Use Table 9 and f_{PFD} = 50MHz to determine V(LDO) and LDOV[1:0]:

```
V(LDO) = 2.3V and LDOV[1:0] = 1
```

Use LDOV[1:0] and LDOEN = 1 (to enable the LDO) to set Reg04. CPLE should be set to 1 to reduce in-band noise and spurious due to the $\Delta\Sigma$ modulator:

Reg04 = h0E

SEED Programming

The SEED[7:0] value is used to initialize the $\Delta\Sigma$ modulator dither circuitry. Use the default value:

Reg05 = h11

R and N Divider and Numerator Programming

Program registers Reg06 to Reg0A with the previously determined R and N divider and numerator values. Because



the AUTORST bit was previously set to 1, RSTFN does not need to be set:

Reg06 = h10

Reg07 = h30

Reg08 = h13

Reg09 = h64

Reg0A = h60

Reference Input Settings and Output Divider Programming

From Table 1, FILT = 0 for a 100MHz reference frequency. Next, convert 7dBm into V_{P-P} . For a CW tone, use the following equation with R = 50:

$$V_{P-P} \cong \sqrt{R} \bullet 10^{(dBm-21)/20} \tag{14}$$

This gives $V_{P\text{-}P}$ = 1.41V, and, according to Table 2, set BST = 1.

Now program Reg0B, assuming maximum RF^{\pm} output power (RF0[1:0] = 3 according to Table 10) and OD[2:0] = 1:

RegOB = h99

Lock Detect and Charge Pump Current Programming

Next, determine the lock indicator window from f_{PFD} . From Table 3 we see that LKWIN[1:0] = 1 with a t_{LWW} of 7.35ns for CPLE = 1 and f_{VCO} = 2415MHz. The LTC6947 will consider the loop locked as long as the phase coincidence at the PFD is within 132°, as calculated below.

phase = $360^{\circ} \bullet t_{LWW} \bullet f_{PFD} = 360 \bullet 7.35n \bullet 50M$ $\approx 132^{\circ}$

Choosing the correct COUNTS value depends upon the OSR. Smaller ratios dictate larger COUNTS values, although application requirements will vary. A COUNTS value of 32 will work for the OSR ratio of 1582. From Table 5, LKCT[1:0] = 1 for 32 counts.

Using Table 6 with the previously selected I_{CP} of 5.6mA gives CP[3:0] = 5. This gives enough information to program RegOC:

RegOC = h2D

Charge Pump Function Programming

The DC1846 includes an LT1678I op amp in the loop filter. This allows the circuit to reach the voltage range specified for the VCO's tuning input. However, it also adds an inversion in the loop transfer function. Compensate for this inversion by setting CPINV = 1.

This example does not use the additional voltage clamp features to allow fault condition monitoring. The loop feedback provided by the op amp will force the charge pump output to be equal to the op amp positive input pin's voltage. Disable the charge pump voltage clamps by setting CPCHI = 0 and CPCLO = 0. Disable all the other charge pump functions (CPMID, CPRST, CPUP, and CPDN) to allow the loop to lock:

RegOD = h10

The loop should now lock. Now un-mute the output by setting OMUTE = 0 (assumes the $\overline{\text{MUTE}}$ pin is high).

Reg02 = h00

REFERENCE SOURCE CONSIDERATIONS

A high quality signal must be applied to the REF[±] inputs as they provide the frequency reference to the entire PLL. As mentioned previously, to achieve the part's in-band phase noise performance, apply a CW signal of at least 6dBm into 50 Ω , or a square wave of at least 0.5V_{P-P} with slew rate of at least 40V/µs.

The LTC6947 may be driven single-ended to CMOS levels (greater than $2.7V_{P-P}$). Apply the reference signal at REF⁺, and bypass REF⁻ to GND with a 47pF capacitor. The BST bit must also be set to 0, according to guidelines given in Table 2.

The LTC6947 achieves an integer mode in-band normalized phase noise floor $L_{NORM(INT)} = -226 dBc/Hz$ typical, and a fractional mode phase noise floor $L_{NORM(FRAC)} = -225 dBc/Hz$ typical. To calculate its equivalent input phase noise floor L_{IN} , use the following Equation 15.

$$L_{IN} = L_{NORM} + 10 \bullet \log_{10} (f_{REF})$$
(15)

For example, using a 10MHz reference frequency in integer mode gives an input phase noise floor of -156dBc/Hz. The reference frequency source's phase noise must be at

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least 3dB better than this to prevent limiting the overall system performance.

IN-BAND OUTPUT PHASE NOISE

The in-band phase noise floor L_{OUT} produced at f_{RF} may be calculated by using Equation 16.

 $L_{OUT} = L_{NORM} + 10 \cdot \log_{10} (f_{PFD})$ (16) + 20 \cdot log_{10} (f_{RF}/f_{PFD}) or

 $L_{OUT} \approx L_{NORM} + 10 \bullet \log_{10} (f_{PFD})$

+ 20 • log₁₀ (N/O)

where L_{NORM} is -226dBc/Hz for integer mode and -225dBc/Hz for fractional mode.

As can be seen, for a given PFD frequency f_{PFD} , the output in-band phase noise increases at a 20dB-per-decade rate with the N divider count. So, for a given output frequency f_{RF} , f_{PFD} should be as large as possible (or N should be as small as possible) while still satisfying the application's frequency step size requirements.

OUTPUT PHASE NOISE DUE TO 1/f NOISE

In-band phase noise at very low offset frequencies may be influenced by the LTC6947's 1/f noise, depending upon f_{PFD}. Use the normalized in-band 1/f noise L_{1/f} of -274dBc/Hz with Equation 17 to approximate the output 1/f phase noise at a given frequency offset f_{OFFSET}.

 $L_{OUT(1/f)} (f_{OFFSET}) = L_{1/f} + 20 \bullet \log_{10} (f_{RF})$ (17) - 10 • log_{10} (f_{OFFSET})

Unlike the in-band noise floor L_{OUT} , the 1/f noise $L_{OUT(1/f)}$ does not change with f_{PFD} , and is not constant over offset frequency. See Figure 16 for an example of integer mode in-band phase noise for f_{PFD} equal to 3MHz and 100MHz. The total phase noise will be the summation of L_{OUT} and $L_{OUT(1/f)}$.

VCO INPUT MATCHING

The VCO^{\pm} inputs may be used differentially or single-ended. Each input provides a single-ended 121 Ω resistance to aid

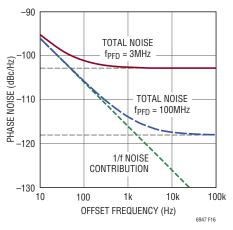


Figure 16. Theoretical Integer Mode In-Band Phase Noise, f_{RF} = 2500MHz

in impedance matching at high frequencies. The inputs are self-biased and must be AC-coupled using 100pF capacitors (or 270pF for VCO frequencies less than 500MHz).

The inputs may be used single-ended by applying the ACcoupled VCO frequency at VCO⁺ and bypassing VCO⁻ to GND with a 100pF capacitor (270pF for frequencies less than 500MHz). Measured VCO⁺ s-parameters (with VCO⁻ bypassed with 100pF to GND) are shown in Table 13 to aid in the design of external impedance matching networks.

Table 13. Single-Ended VCO+ Input Impedance

| FREQUENCY (MHz) | IMPEDANCE (Ω) | S11 (dB) |
|-----------------|------------------------|----------|
| 250 | 118 – j78 | -5.06 |
| 500 | 83.6 – j68.3 | -5.90 |
| 1000 | 52.8 – j56.1 | -6.38 |
| 1500 | 35.2 – j41.7 | -6.63 |
| 2000 | 25.7 – j30.2 | -6.35 |
| 2500 | 19.7 – j20.6 | -5.94 |
| 3000 | 17.6 – j11.2 | -6.00 |
| 3500 | 17.8 – j3.92 | -6.41 |
| 4000 | 19.8 + j4.74 | -7.20 |
| 4500 | 21.5 + j15.0 | -7.12 |
| 5000 | 21.1 + j19.4 | -6.52 |
| 5500 | 27.1 + j22.9 | -7.91 |
| 6000 | 38.3 + j33.7 | -8.47 |
| 6500 | 36.7 + j42.2 | -6.76 |
| 7000 | 46.2 + j40.9 | -8.11 |
| 7500 | 76.5 + j36.8 | -9.25 |
| 8000 | 84.1+ j52.2 | -7.27 |



INTEGER BOUNDARY SPURS

Integer boundary spurs are caused by intermodulation between harmonics of the PFD frequency f_{PFD} and the VCO frequency f_{VCO} . The coupling between the frequency source harmonics can occur either on- or off-chip. The spurs are located at offset frequencies defined by the beat frequency between the reference harmonics and the VCO frequency, and are attenuated by the loop filter. The spurs only occur while in fractional mode.

Integer boundary spurs are most commonly seen when the fractional value F approaches either zero or one such that the VCO frequency offset from an integer frequency is within the loop bandwidth:

 $f_{PFD} \bullet F \le BW$

or

 $f_{PFD} \bullet (1 - F) \le BW$

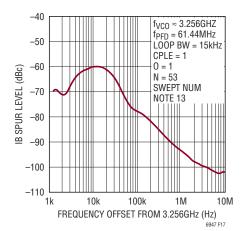


Figure 17. Integer Boundary Spur Power vs Frequency Offset from Boundary

The spur will have a relatively constant power in-band, and is attenuated by the loop out-of-band. An example integer boundary spur measurement is shown in Figure 17.

RF OUTPUT MATCHING

The RF[±] outputs may be used in either single-ended or differential configurations. Using both RF outputs differentially will result in approximately 3dB more output power than single-ended. Impedance matching to an external load in both cases requires external chokes tied to $V_{RF}^{+}.$ Measured RF[±] S-parameters are shown below in Table 14 to aid in the design of impedance matching networks.

Table 14. Single-Ended RF Output Impedance

| FREQUENCY (MHz) | IMPEDANCE (Ω) | S11 (dB) |
|-----------------|------------------------|----------|
| 100 | 133.0 – j16.8 | -6.7 |
| 500 | 110.8 – j46.1 | -6.8 |
| 1000 | 74.9 – j57.0 | -6.9 |
| 1500 | 49.0 – j51.3 | -6.7 |
| 2000 | 34.4 – j41.4 | -6.5 |
| 2500 | 27.0 – j32.1 | -6.5 |
| 3000 | 23.2 – j24.1 | -6.6 |
| 3500 | 21.6 – j15.9 | -7.1 |
| 4000 | 20.9 – j7.7 | -7.5 |
| 4500 | 20.1 – j0.2 | -7.4 |
| 5000 | 18.1 + j7.4 | -6.4 |
| 5500 | 16.7 + j12.5 | -5.6 |
| 6000 | 17.1 + j16.1 | -5.5 |
| 6500 | 20.2 + j20.1 | -6.2 |
| 7000 | 26.9 + j24.6 | -7.6 |
| 7500 | 38.8 + j32.3 | -8.8 |
| 8000 | 52.9 + j43.1 | -8.2 |

Single-ended impedance matching is accomplished using the circuit of Figure 18, with component values found in Table 15. Using smaller inductances than recommended can cause phase noise degradation, especially at lower center frequencies.

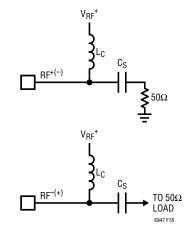


Figure 18. Single-Ended Output Matching Schematic



| f _{RF} (MHz) | L _C (nH) | C _S (pF) |
|-----------------------|---------------------|---------------------|
| 350 to 1500 | 180 | 270 |
| 1000 to 6000 | 68 | 100 |

Return loss measured on the DC1846 using the above component values is shown in Figure 19. A broadband match is achieved using an $\{L_C, C_S\}$ of either $\{68nH, 100pF\}$ or $\{180nH, 270pF\}$. However, for maximum output power and best phase noise performance, use the recommended component values of Table 15. L_C should be a wirewound inductor selected for maximum Q factor and SRF, such as the Coilcraft HP series of chip inductors.

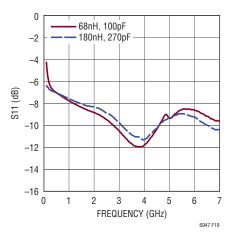


Figure 19. RF Single-Ended Return Loss

The LTC6947's differential RF[±] outputs may be combined using an external balun to drive a single-ended load. The advantages are approximately 3dB more output power than each output individually and better 2nd order harmonic performance.

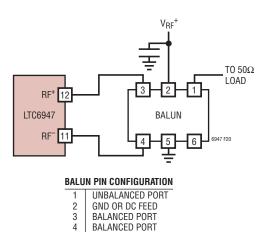
For lower frequencies, transmission line (TL) baluns such as the M/A-COM MABACT0065 and the TOKO #617DB-1673 provide good results. At higher frequencies, surface mount (SMT) baluns such as those produced by TDK, Anaren, and Johanson Technology, can be attractive alternatives. See Table 16 for recommended balun part numbers versus frequency range.

The listed SMT baluns contain internal chokes to bias RF^{\pm} and also provide input-to-output DC isolation. The pin denoted as GND or DC FEED should be connected to the

 $V_{\text{RF}}{}^{+}$ voltage. Figure 20 shows a surface mount balun's connections with a DC FEED pin.

| Table 16. Suggested Ba | luns |
|------------------------|------|
|------------------------|------|

| f _{RF} (MHz) | PART NUMBER | MANUFACTURER | TYPE | |
|-----------------------|---------------|--------------|------|--|
| 350 to 900 | #617DB-1673 | ТОКО | TL | |
| 400 to 600 | HHM1589B1 | TDK | SMT | |
| 600 to 1400 | BD0810J50200 | Anaren | SMT | |
| 600 to 3000 | MABACT0065 | M/A-COM | TL | |
| 1000 to 2000 | HHM1518A3 | TDK | SMT | |
| 1400 to 2000 | HHM1541E1 | TDK | SMT | |
| 1900 to 2300 | 2450BL15B100E | Johanson | SMT | |
| 2000 to 2700 | HHM1526 | TDK | SMT | |
| 3700 to 5100 | HHM1583B1 | TDK | SMT | |
| 4000 to 6000 | HHM1570B1 | TDK | SMT | |

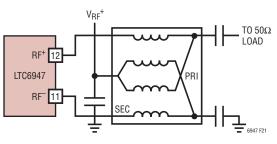




5 GND

6 NC

The listed TL baluns do not provide input-to-output DC isolation and must be AC-coupled at the output. Figure 21 displays RF^{\pm} connections using these baluns.





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SUPPLY BYPASSING AND PCB LAYOUT GUIDELINES

Care must be taken when creating a PCB layout to minimize power supply decoupling and ground inductances. All power supply V⁺ pins should be bypassed directly to the ground plane using a 0.1μ F ceramic capacitor as close to the pin as possible. Multiple vias to the ground plane should be used for all ground connections, including to the power supply decoupling capacitors.

The package's exposed pad is a ground connection, and must be soldered directly to the PCB land pattern. The PCB land pattern should have multiple thermal vias to the ground plane for both low ground inductance and also low thermal resistance (see Figure 22 for an example). See QFN Package Users Guide, page 8, on Linear Technology website's Packaging Information page for specific recommendations concerning land patterns and land via solder masks. A link is provided below.

http://www.linear.com/designtools/packaging

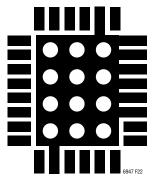


Figure 22. Example Exposed Pad Land Pattern

REFERENCE SIGNAL ROUTING, SPURIOUS, AND PHASE NOISE

The charge pump operates at the PFD's comparison frequency f_{PFD} . The resultant output spurious energy is small and is further reduced by the loop filter before it modulates the VCO frequency.

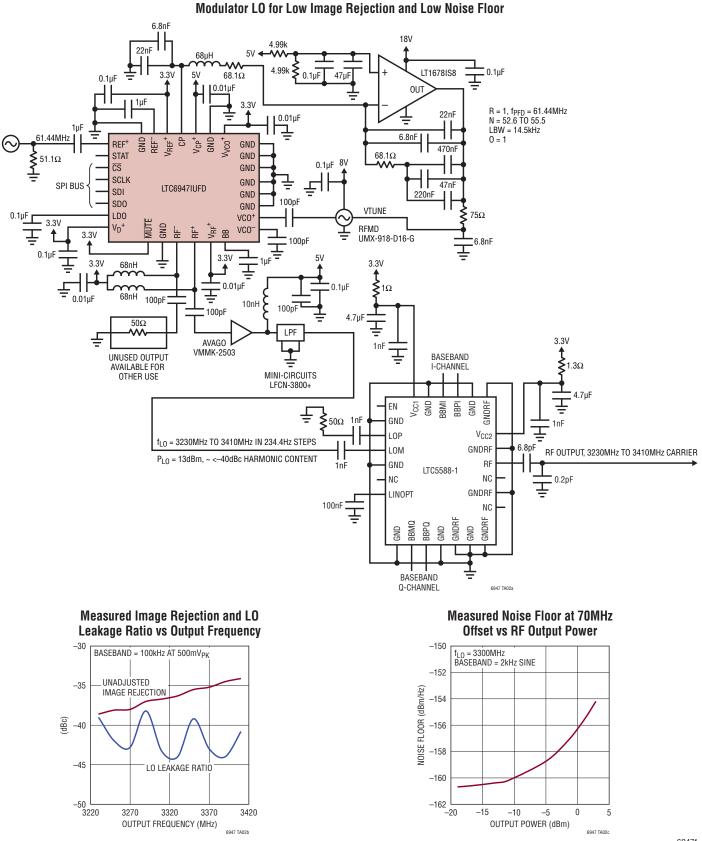
However, improper PCB layout can degrade the LTC6947's inherent spurious performance. Care must be taken to prevent the reference signal f_{REF} from coupling onto the VCO's tune line, or into other loop filter signals. Example suggestions are the following.

- 1) Do not share power supply decoupling capacitors between same-voltage power supply pins.
- 2) Use separate ground vias for each power supply decoupling capacitor, especially those connected to V_{REF}^+ , V_D^+ , LDO, V_{CP}^+ , and V_{VCO}^+ .
- 3) Physically separate the reference frequency signal from the loop filter and VCO.





TYPICAL APPLICATIONS

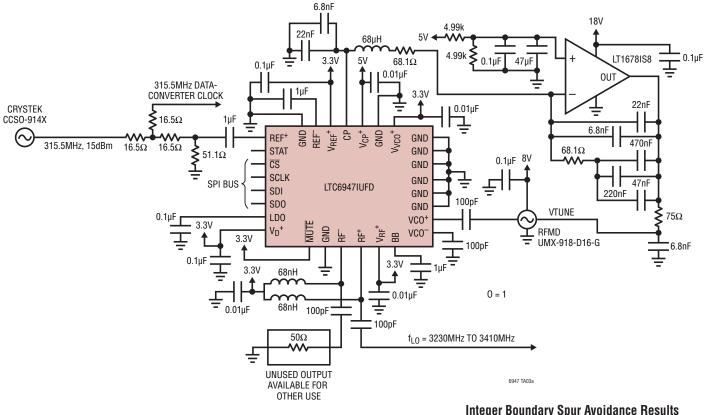




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TYPICAL APPLICATIONS

Integer Boundary Spur Avoidance



THIS APPLICATION EXAMPLE ILLUSTRATES A STRAIGHTFORWARD PROGRAMMING METHOD TO MINIMIZE INTEGER BOUNDARY SPURS. SWITCH THE REFERENCE DIVIDER VALUE, R, BETWEEN TWO PREDETERMINED VALUES TO AVOID FRACTIONAL VALUES, F, CLOSE TO 0 OR 1.

 $f_{REF} = 315.5MHz$

FOR R1 = 6: f_{PFD}(R1) = 52.58MHz, f_{STEP}(R1) = 200.59Hz

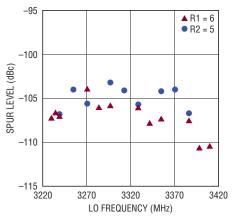
FOR R2 = 5: $f_{PFD}(R2) = 63.10MHz$, $f_{STEP}(R2) = 240.7Hz$

FIRST, CALCULATE f_{SPUR}(R), FREQUENCY OFFSET OF THE INTEGER-BOUNDARY SPUR NEAREST INTEGER BOUNDARY AS A DISTANCE FROM THE CARRIER, FOR EACH R VALUE.

$$\begin{split} f_{SPUR}(R) &= F \bullet \frac{f_{REF}}{R}, \text{ FOR } F < 0.5 \\ f_{SPUR}(R) &= (1 - F) \bullet \frac{f_{REF}}{R}, \text{ FOR } F \ge 0.5 \\ \text{WHERE } F &= \frac{NUM}{2^{18}} \end{split}$$

NEXT, LET R = R1 for $f_{SPUR}(R1) > f_{SPUR}(R2)$, ELSE LET R = R2

Integer Boundary Spur Avoidance Results (Measured at Nearest Integer Boundary)

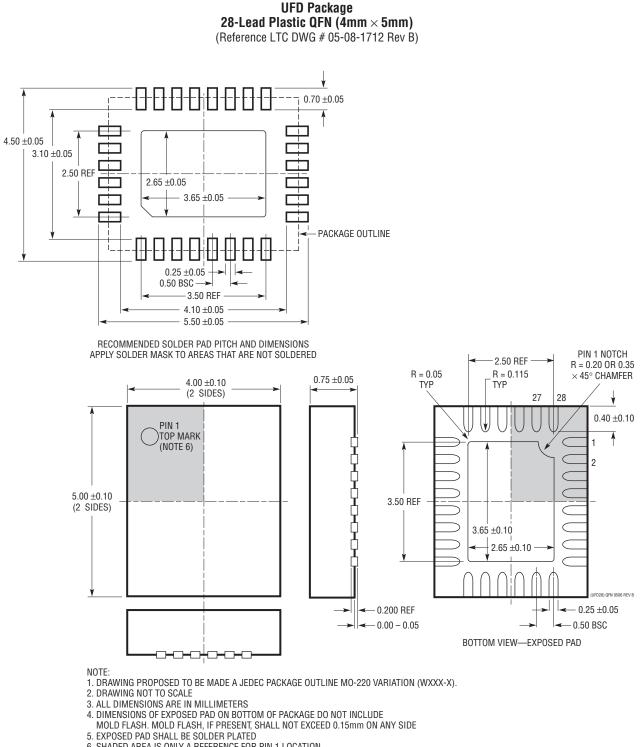


NOTE: SPURS UP TO -70dBC CAN BE FOUND NEAR F VALUES OF 0.5 IN VERY NARROW BANDS (10s OF kHz) AND UP TO -75dBC NEAR F VALUES OF 0.333 OR 0.667. APPROPRIATELY SWITCHING BETWEEN R1 AND R2 CAN AVOID THESE SPURS. 1000 THESE SPURS.



PACKAGE DESCRIPTION

Please refer to http://www.linear.com/designtools/packaging/ for the most recent package drawings.

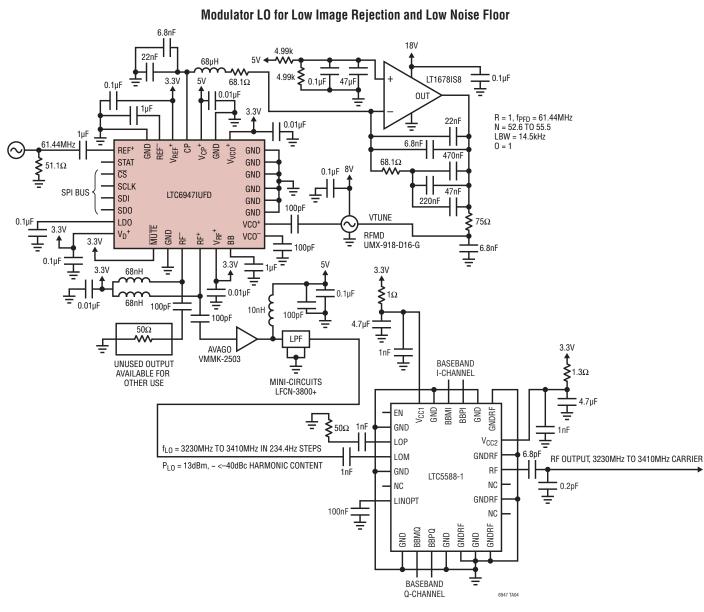


- 6. SHADED AREA IS ONLY A REFERENCE FOR PIN 1 LOCATION
 - ON THE TOP AND BOTTOM OF PACKAGE



Information furnished by Linear Technology Corporation is believed to be accurate and reliable. However, no responsibility is assumed for its use. Linear Technology Corporation makes no representation that the interconnection of its circuits as described herein will not infringe on existing patent rights. 6947f

TYPICAL APPLICATIONS



RELATED PARTS

| PART NUMBER | DESCRIPTION | COMMENTS |
|-------------|---|--|
| LTC6946-x | Ultralow Noise and Spurious Integer-N Synthesizer with Integrated VCO | 370MHz to 6.4GHz, –226dBc/Hz Normalized In-Band Phase Noise Floor, –157dBc/Hz Wideband Output Phase Noise Floor |
| LTC6945 | Ultralow Noise and Spurious Integer-N Synthesizer | 350MHz to 6GHz, –226dBc/Hz Normalized In-Band Phase Noise Floor, –157dBc/Hz Wideband Output Phase Noise Floor |
| LTC6948-x | Ultralow Noise Fractional-N Synthesizer with Integrated VCO | 370MHz to 6.4GHz, –226dBc/Hz Normalized In-Band Phase Noise Floor, –157dBc/Hz Wideband Output Phase Noise Floor |
| LTC6957 | Low Phase Noise, Dual Output Buffer/Driver/Logic Converter | Optimized Conversion of Sine Waves to Logic Levels, LVPECL/LVDS/CMOS Outputs, DC-300MHz, 45fsRMS additive jitter (LVPECL) |
| LTC5588-1 | Ultrahigh OIP3 I/Q Modulator | 200MHz to 6GHz, 31dBm OIP3, –160.6dBm/Hz Noise Floor |

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