TABLE OF CONTENTS

Features
Applications1
Functional Block Diagram1
General Description
Revision History
Specifications
Electrical Specifications
Timing Specifications4
Absolute Maximum Ratings5
ESD Caution
Pin Configuration and Function Descriptions
Interface Schematics7
Typical Performance Characteristics

REVISION HISTORY

4/2018—Rev. B to Rev C	
Changes to Figure 23	12
Change to PCB Description, Table 7	13
Updated Outline Dimensions	15

9/2017—Rev. A to Rev. B

Changed CP-24-16 to HCP-24-3	. Throughout
Updated Outline Dimensions	15
Changes to Ordering Guide	15

Insertion Loss, Return Loss, State Error, Step Error, and	
Relative Phase	8
Input Power Compression and Third-Order Intercept	10
Theory of Operation	11
Serial Control Interface	11
RF Input Output	11
Parallel Control Interface	12
Power-Up Sequence	12
Applications Information	13
Evaluation Printed Circuit Board	13
Packaging and Ordering Information	15
Outline Dimensions	15
Ordering Guide	15

8/2017—Rev. 0 to Rev. A

Added Timing Specifications Section	4
Moved Table 2	4
Changes to Figure 5 and Figure 6	7
Changes to Serial Control Interface Section	11
Moved Figure 22 and Table 6	11
Changes to Figure 23	12
Moved Parallel Control Interface Section, Direct Parallel Mod	e
Section, Latched Parallel Mode Section, Power-Up Sequence	
Section, and Power-Up States Section	12
Updated Outline Dimensions	15

9/2016—Revision 0: Initial Version

SPECIFICATIONS ELECTRICAL SPECIFICATIONS

 V_{DD} = 3.3 V to 5.0 V, T_{A} = 25°C, 50 Ω system, unless otherwise noted.

Table 1.

Parameter	Test Conditions/Comments	Min	Тур	Max	Unit
FREQUENCY RANGE		0.1		6.0	GHz
INSERTION LOSS	0.1 GHz to 1.0 GHz		1.1	1.8	dB
	0.1 GHz to 2.0 GHz		1.3	2.0	dB
	0.1 GHz to 4.0 GHz		1.6	2.3	dB
	0.1 GHz to 6.0 GHz		2.0	2.8	dB
ATTENUATION	0.2 GHz to 6.0 GHz				
Range	Delta between minimum and maximum attenuation states		31.75		dB
Accuracy	Referenced to insertion loss; all attenuation states	-(0.05 + 4% of attenuation setting)		+(0.05 + 4% of attenuation setting)	dB
Step Error	All attenuation states		±0.1		dB
Overshoot	Between all attenuation states		≤0.1		dB
RETURN LOSS	All attenuation states				
ATTNIN, ATTNOUT	1.0 GHz		23		dBm
	2.0 GHz		22		dBm
	4.0 GHz		19		dBm
	6.0 GHz		17		dBm
RELATIVE PHASE	1.0 GHz		6		Degrees
	2.0 GHz		18		Degrees
	4.0 GHz		38		Degrees
	6.0 GHz		58		Degrees
SWITCHING CHARACTERISTICS					
t _{RISE} , t _{FALL}	10%/90% RF output		60		ns
ton, toff	50% CTL to 10%/90% RF output		150		ns
Settling Time	50% CTL to 0.05 dB final RF output		250		ns
	50% CTL to 0.10 dB final RF output		200		ns
INPUT LINEARITY	All attenuation states, 0.2 GHz to 6 GHz				
0.1 dB Compression (P0.1dB)			30		dBm
1 dB Compression (P1dB)			31		dBm
Input Third-Order Intercept (IP3)	Two-tone input power = 16 dBm/tone, $\Delta f = 1 MHz$		54		dBm
SUPPLY CURRENT (IDD)	$V_{DD} = 3.3 V$		0.3		mA
	$V_{DD} = 5.0 V$		0.6		mA
CONTROL VOLTAGE THRESHOLD	<1 µA typical				
Low	$V_{DD} = 3.3 V$	0		0.5	v
	$V_{DD} = 5.0 V$	0		0.8	V
High	$V_{DD} = 3.3 V$	2.0		3.3	v
	$V_{DD} = 5.0 V$	3.5		5.0	v
RECOMMENDED OPERATING CONDITIONS					ĺ
Supply Voltage Range (V_{DD})		3.0		5.4	v
Digital Control Voltage Range	For P/S, CLK, SERNIN, LE, D0 to D6 pins	0		V _{DD}	V
RF Input Power	All attenuation states, $T_{CASE} = 85^{\circ}C$			24	dBm
Case Temperature (T _{CASE})		-40		+85	°C

TIMING SPECIFICATIONS

See Figure 23 and Figure 24 for the timing diagrams.

Table 2.

Parameter	Description	Min	Тур	Max	Unit
tscк	Minimum serial period, see Figure 23	70	ns		
t _{cs}	Control setup time, see Figure 23	15			ns
t _{CH}	Control hold time, see Figure 23	20			ns
t _{LN}	LE setup time, see Figure 23	15			ns
t _{LEW}	Minimum LE pulse width, see Figure 24	10			ns
t _{LES}	Minimum LE pulse spacing, see Figure 23		630		ns
t ски	Serial clock hold time from LE, see Figure 23	0			ns
t _{PH}	Hold time, see Figure 24		10		ns
t _{PS}	Setup time, see Figure 24	2 ns			ns

ABSOLUTE MAXIMUM RATINGS

Table 3.

14010 01	
Parameter	Rating
RF Input Power (T _{CASE} = 85°C)	25 dBm
Digital Control Inputs (P/S, CLK, SERNIN, LE, D0 to D6)	-0.3 V to V_{DD} + 0.5 V
Supply Voltage (V _{DD})	–0.3 V to +5.5 V
Continuous Power Dissipation (P _{DISS})	0.31 W
Thermal Resistance (at Maximum Power Dissipation)	156°C/W
Temperature	
Channel Temperature	135°C
Storage	–65°C to +150°C
Maximum Reflow Temperature	260°C (MSL3 Rating)
ESD Sensitivity (HBM)	2 kV (Class 2)

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

ESD CAUTION



ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

HMC1119

PIN CONFIGURATION AND FUNCTION DESCRIPTIONS

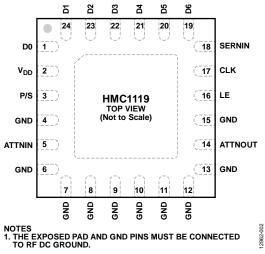


Figure 2. Pin Configuration

Table 4. Pin Function Descriptions

Pin No.	Mnemonic	Description
1, 19 to 24	D0, D6 to D1	Parallel Control Voltage Inputs. These pins attain the required attenuation (see Table 6). There is no internal pull-up or pull-down on these pins; therefore, these pins must always be kept at a valid logic level (V_{H} or V_{L}) and must not be left floating.
2	V _{DD}	Supply Voltage Pin.
3	P/S	Parallel/Serial Control Input. There is no internal pull-up or pull-down on this pin; therefore, this pin must always be kept at a valid logic level ($V_{\mathbb{H}}$ or $V_{\mathbb{L}}$) and must not be left floating. For parallel mode, set Pin 3 to low; for serial mode, set Pin 3 to high.
4, 6 to 13, 15	GND	Ground. The package bottom has an exposed metal pad that must connect to the printed circuit board (PCB) RF/dc ground. See Figure 4 for the GND interface schematic.
5	ATTNIN	Attenuator Input. This pin is dc-coupled and matched to 50 Ω . A blocking capacitor is required. Select the value of the capacitor based on the lowest frequency of operation. See Figure 5.
14	ATTNOUT	Attenuator Output. This pin is dc-coupled and matched to 50 Ω . A blocking capacitor is required. Select the value of the capacitor based on the lowest frequency of operation. See Figure 5.
16	LE	Serial/Parallel Interface Latch Enable Input. There is no internal pull-up or pull-down on this pin; therefore, this pin must always be kept at a valid logic level ($V_{\mathbb{H}}$ or $V_{\mathbb{L}}$) and must not be left floating. See the Theory of Operation section for more information.
17	CLK	Serial Interface Clock Input. There is no internal pull-up or pull-down on this pin; therefore, this pin must always be kept at a valid logic level ($V_{\mathbb{H}}$ or $V_{\mathbb{L}}$) and must not be left floating. See the Theory of Operation section for more information.
18	SERNIN	Serial interface Data Input. There is no internal pull-up or pull-down on this pin; therefore, this pin must always be kept at a valid logic level ($V_{\mathbb{H}}$ or $V_{\mathbb{L}}$) and must not be left floating. See the Theory of Operation section for more information.
	EPAD	Exposed Pad. The exposed pad must be connected to RF/dc ground.

INTERFACE SCHEMATICS

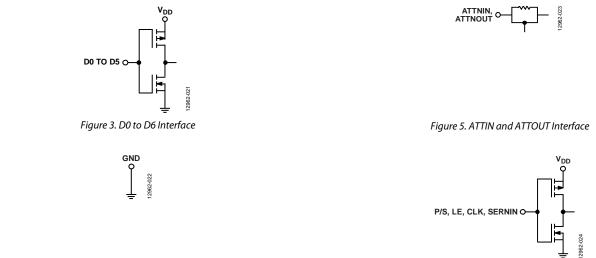
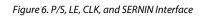


Figure 4. GND Interface



TYPICAL PERFORMANCE CHARACTERISTICS

INSERTION LOSS, RETURN LOSS, STATE ERROR, STEP ERROR, AND RELATIVE PHASE

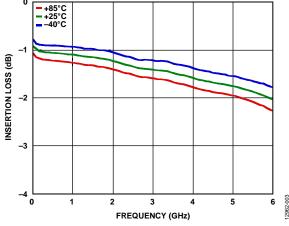
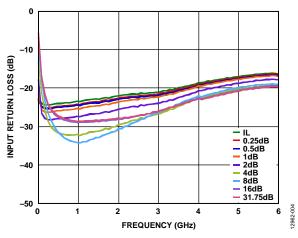
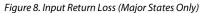


Figure 7. Insertion Loss vs. Frequency at Various Temperatures





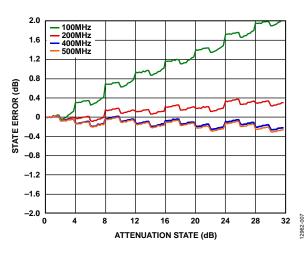
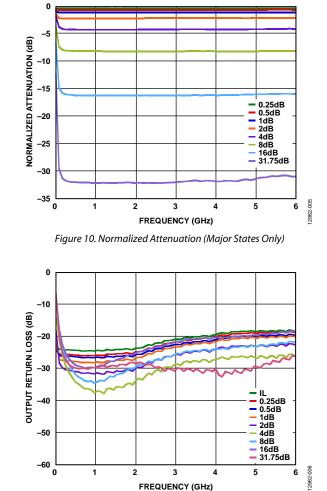


Figure 9. State Error vs. Attentuation State, 0.1 GHz to 0.5 GHz





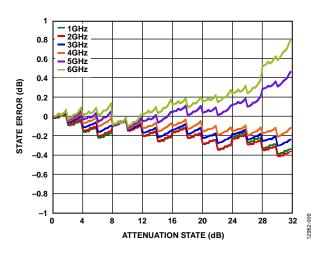


Figure 12. State Error vs. Attentuation State, 1 GHz to 6 GHz

Data Sheet

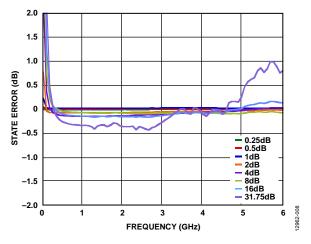


Figure 13. State Error vs. Frequency, Major States Only

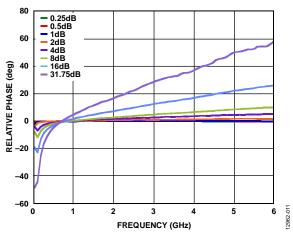


Figure 14. Relative Phase vs. Frequency, Major States Only

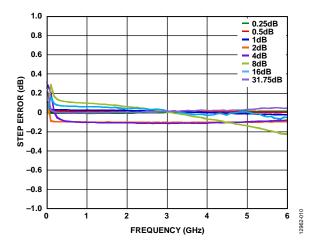
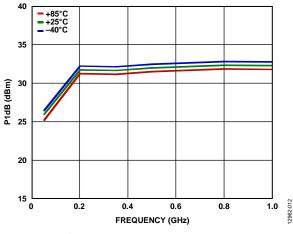


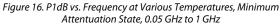
Figure 15. Step Error vs. Frequency, Major States Only

HMC1119

HMC1119

INPUT POWER COMPRESSION AND THIRD-ORDER INTERCEPT





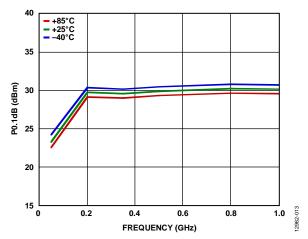


Figure 17. P0.1dB vs. Frequency at Various Temperatures, Minimum Attentuation State, 0.05 GHz to 1 GHz

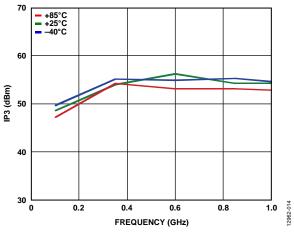


Figure 18. IP3 vs. Frequency at Various Temperatures, Minimum Attentuation State, 0.1 GHz to 1 GHz

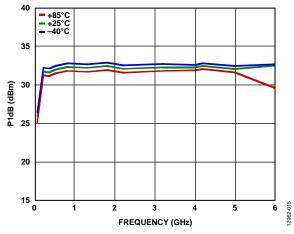


Figure 19. P1dB vs. Frequency at Various Temperatures, Minimum Attentuation State, 0.05 GHz to 6 GHz

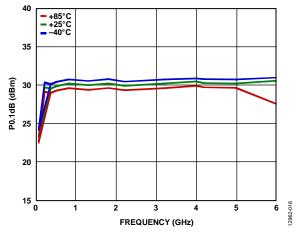


Figure 20. P0.1dB vs. Frequency at Various Temperatures, Minimum Attentuation State, 0.05 GHz to 6 GHz

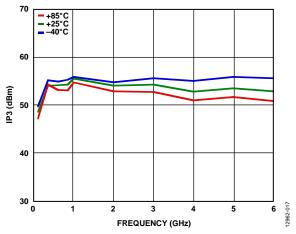


Figure 21. IP3 vs. Frequency at Various Temperatures, Minimum Attentuation State, 0.1 GHz to 6 GHz

THEORY OF OPERATION

The HMC1119 incorporates a 7-bit fixed attenuator array that offers an attenuation range of 0.25 dB to 31.75 dB, with 0.25 dB steps. An integrated driver provides both serial and parallel mode control of the attenuator array (see Figure 22).

The HMC1119 can be in either serial or parallel mode control by setting the P/S pin to high or low, respectively (see Table 5). The 7-bit data, loaded in either serial or parallel mode, then latches with the control signal, LE, to determine the attenuator value.

Table 5. Mode Selection Table¹

P/S Pin State	Control Mode
Low	Parallel
High	Serial

 1 The P/S pin must always be kept at a valid logic level (V_{I\!H} or V_{I\!L}) and must not be left floating.

SERIAL CONTROL INTERFACE

The HMC1119 utilizes a 3-wire serial to parallel (SPI) configuration, as shown in the serial mode timing diagram (see Figure 23): serial data input (SERNIN), clock (CLK), and latch enable (LE). The serial control interface activates when the P/S pin is set to high.

In serial mode, the 7-bit SERNIN data is clocked MSB first on rising CLK edges into the shift register; then, LE must be toggled high to latch the new attenuation state into the device. The LE must be set low to clock a set of 7-bit data into the shift register because CLK is masked to prevent the attenuator value from changing if LE is kept high.

In serial mode operation, both the serial control inputs (LE, CLK, SERNIN) and the parallel control inputs (D0 to D6) must always be kept at a valid logic level ($V_{\rm IH}$ or $V_{\rm IL}$) and must not be left floating. It is recommended to connect the parallel control inputs to ground and to use pull-down resistors on all serial control input lines if the device driving these input lines goes high impedance during hibernation.

RF INPUT OUTPUT

The attenuator in the HMC1119 is bidirectional; the ATTNIN and ATTNOUT pins are interchangeable as the RF input and output ports. The attenuator is internally matched to 50 Ω at both input and output; therefore, no external matching components are required. The RF pins are dc-coupled; therefore, dc blocking capacitors are required on RF lines.

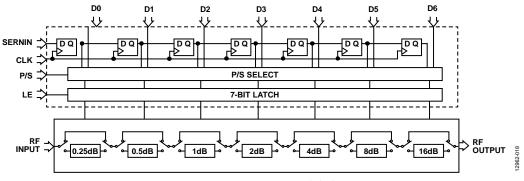


Figure 22. Attenuator Array Functional Block Diagram

Table 6. Truth Table

Digital Control Input ¹								
D6	D5	D4	D3	D2	D1	D0	Attenuation State (dB)	
Low	Low	Low	Low	Low	Low	Low	0 (reference)	
Low	Low	Low	Low	Low	Low	High	0.25	
Low	Low	Low	Low	Low	High	Low	0.5	
Low	Low	Low	Low	High	Low	Low	1.0	
Low	Low	Low	High	Low	Low	Low	2.0	
Low	Low	High	Low	Low	Low	Low	4.0	
Low	High	Low	Low	Low	Low	Low	8.0	
High	Low	Low	Low	Low	Low	Low	16.0	
High	High	High	High	High	High	High	31.75	

¹ Any combination of the control voltage input states shown in Table 6 provides an attenuation equal to the sum of the bits selected.

HMC1119

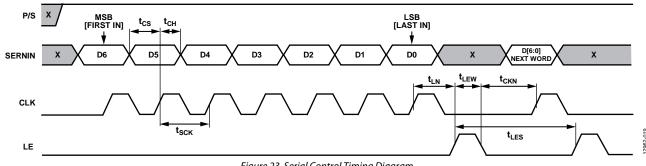


Figure 23. Serial Control Timing Diagram

PARALLEL CONTROL INTERFACE

The parallel control interface has seven digital control input lines (D6 to D0) to set the attenuation value. D6 is the most significant bit (MSB) that selects the 16 dB attenuator stage, and D0 is the least significant bit (LSB) that selects the 0.25 dB attenuator stage (see Figure 22).

In parallel mode operation, both the serial control inputs (LE, CLK, SERNIN) and the parallel control inputs (D0 to D6) must always be kept at a valid logic level (VIH or VIL) and must not be left floating. It is recommended to connect the serial control inputs to ground and to use pull-down resistors on all parallel control input lines if the device driving these input lines goes high impedance during hibernation.

Setting P/S to low enables parallel mode. There are two modes of parallel operation: direct parallel mode and latched parallel mode.

Direct Parallel Mode

For direct parallel mode, the latch enable (LE) pin must be kept high. Change the attenuation state using the control voltage inputs (D0 to D6) directly. This mode is ideal for manual control of the attenuator and using hardware, switches, or a jumper.

Latched Parallel Mode

The latch enable (LE) pin must be low when changing the control voltage inputs (D0 to D6) to set the attenuation state. When the desired state is set, LE must be toggled high to transfer the 7-bit data to the bypass switches of the attenuator array, then toggled low to latch the change into the device (see Figure 24).

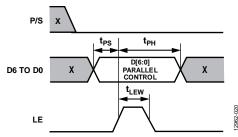


Figure 24. Latched Parallel Mode Timing Diagram

POWER-UP SEQUENCE

The ideal power-up sequence is as follows:

- Power up GND. 1.
- 2. Power up V_{DD}.
- 3. Power up the digital control inputs (the relative order of the digital control inputs is not important).
- Power up the RF input. 4.

For latched parallel mode operation, LE must be toggled. The relative order of the digital inputs is not important as long as the inputs are powered up after GND and V_{DD} .

Power-Up States

The logic state of the device is at maximum attenuation when, at power up, LE is set to low. The attenuator latches in the desired power-up state approximately 200 ms after power up.

APPLICATIONS INFORMATION evaluation printed circuit board

The schematic of the evaluation board, EV2HMC1119LP4M, is shown in Figure 25. The PCB is four-layer material with a copper thickness of 0.7 mils on each layer. Each copper layer is separated with a dielectric material. The top dielectric material is 10-mil RO4350 with a typical dielectric constant of 3.48. The middle and bottom dielectric materials are FR-4 material, used for mechanical strength and to meet the overall board thickness of approximately 62 mils, which allows SMA connectors to be slipped in at board edges. All RF and dc traces are routed on the top copper layer. The RF transmission lines are designed using coplanar waveguide model (CPWG) with a width of 18 mils, spacing of 17 mils, and dielectric thickness of 10 mils to maintain 50 Ω characteristic impedance. The inner and bottom layers are solid ground planes. For optimal electrical and thermal performance, an ample number of vias are populated around the transmission lines and under the package exposed pad. The evaluation board layout serves as a recommendation for the optimal performance on both electrical and thermal aspects.

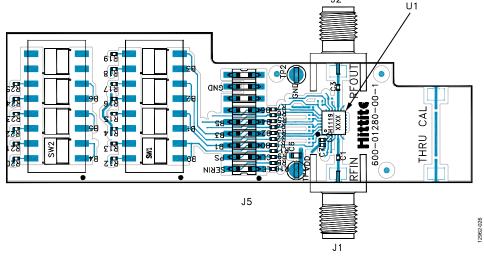


Figure 25. EV2HMC1119LP4M Evaluation PCB

Table 7. Bill of Materials							
ltem	Value ¹	Description	Manufacturer ²				
J1, J2		PCB mount SMA connector					
J3		18-pin dc connector					
TP1, TP2		Through hole mount test point					
C1, C3	100 pF	Capacitor, 0402 package					
C6	10 µF	Capacitor, 0603 package					
C7	1000 pF	Capacitor, 0402 package					
R1 to R11	0 Ω	Resistor, 0402 package					
R12 to R25	100 kΩ	Resistor, 0402 package					
SW1, SW2		SPDT four-position DIP switch					
U1		HMC1119 digital attenuator	Analog Devices, Inc.				
PCB ³		600-01280-00-1 evaluation PCB	EV2HMC1119LP4M ⁴ from Analog Devices				

¹ Blank cells in the Value column indicate that there is no specific value recommendation for the listed component.

² Blank cells in the Manufacturer column indicate that there is no specific manufacturer recommendation for the listed component.

³ Circuit board material is Arlon 25FR.

⁴ Reference this number when ordering the full evaluation PCB. See the Ordering Guide section.

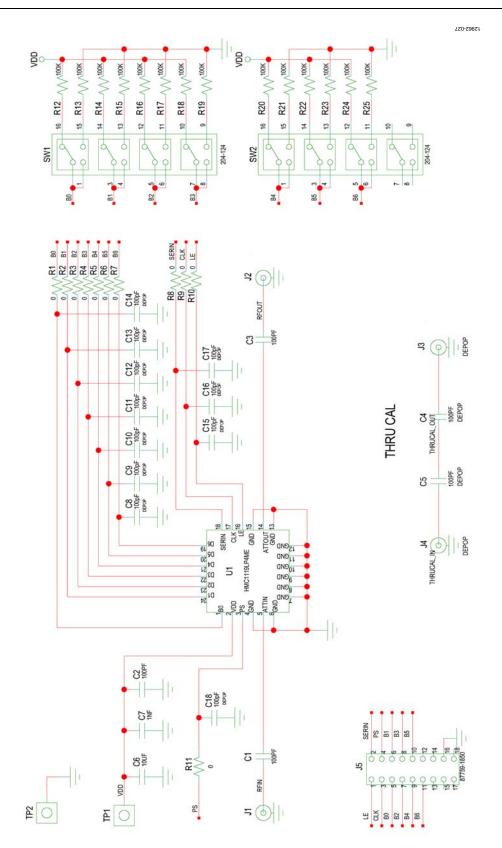
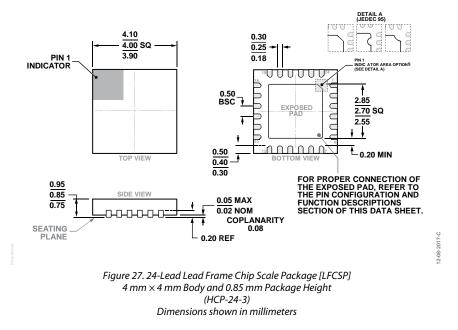


Figure 26. Applications Circuit

PACKAGING AND ORDERING INFORMATION OUTLINE DIMENSIONS



ORDERING GUIDE

Model ¹	Temperature Range	MSL Rating ²	Package Description	Package Option
HMC1119LP4ME	-40°C to +85°C	MSL3	24-Lead Lead Frame Chip Scale Package [LFCSP]	HCP-24-3
HMC1119LP4METR	-40°C to +85°C	MSL3	24-Lead Lead Frame Chip Scale Package [LFCSP]	HCP-24-3
EV2HMC1119LP4M			Evaluation Board	

¹ All models are RoHS compliant.

² See the Absolute Maximum Ratings section.

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Rev. C | Page 15 of 15